

DUACS-DT2018 : 25 YEARS OF REPROCESSED ALTIMETRIC PRODUCTS

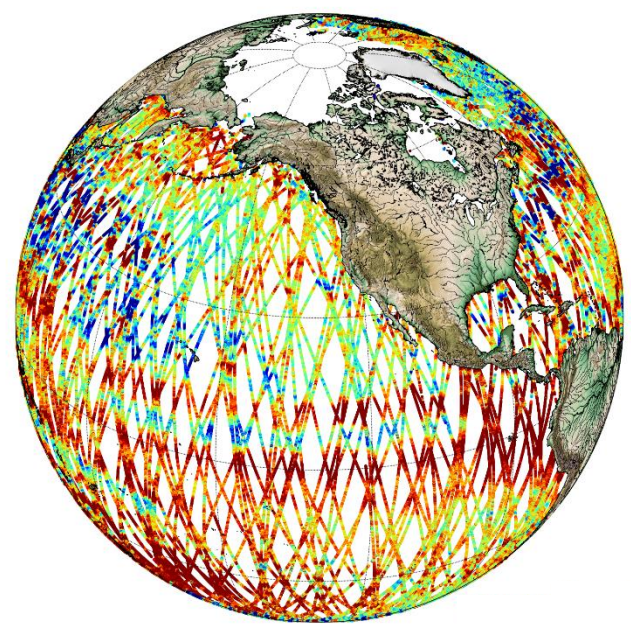
M. BALLAROTTA, G. TABURET and the DUACS Team (CLS)
G. DIBARBOURE (CNES)



ABSTRACT The DUACS system generates, as part as the Copernicus Marine Environment and Monitoring Service (CMEMS), high quality multi-mission altimetry Sea Level products. These products consist in Level 3 (along-track cross-calibrated Sea Level Anomaly SLA) and Level 4 (multiple sensors merged as maps or time series) products and are available in global and regional versions (Mediterranean Sea, Black Sea).

A full reprocessing is carried out and will be made available through the CMEMS. It will cover the entire 1993 – 2017 period and would benefit from major improvements associated with new altimeter correction standards and optimized mapping parameters.

Here, we report the first results of this upcoming multi-mission reprocessing and evaluate associated changes. Several comparisons with independent dataset (along-track, drifters, tide gauges) have been performed.



Level2P and Level3 improvement

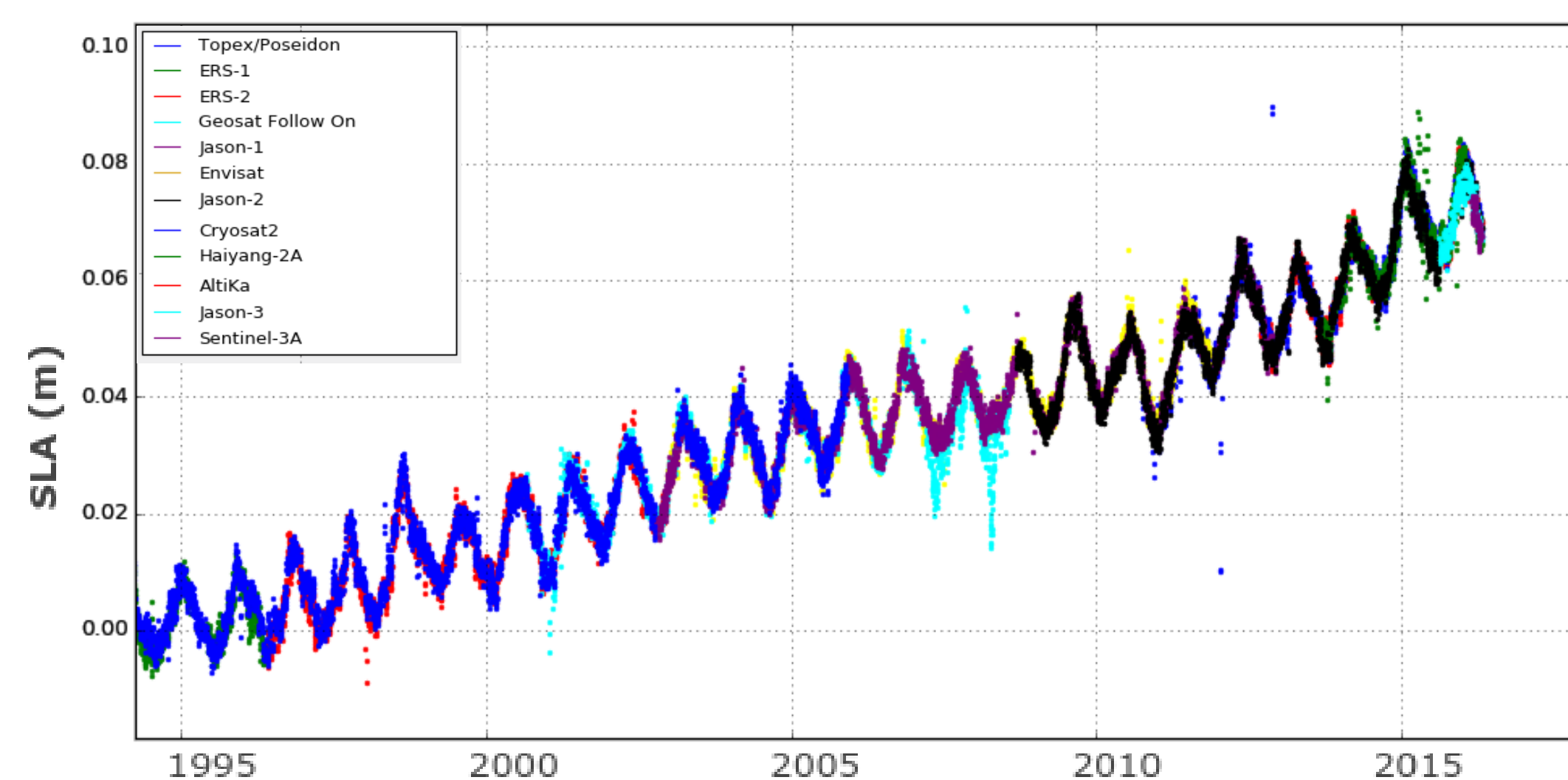
- Use of up-to-date standards.
Most important improvement : new MSS (CNES-CLS-2015), new Tide correction (FES2014) and better orbit computation.

- SLA was arbitrarily calibrated so that mean SLA is null over 1993. All missions are homogenized to ensure the continuity and consistency between all altimeter missions (e.g. global and regional mean sea level).

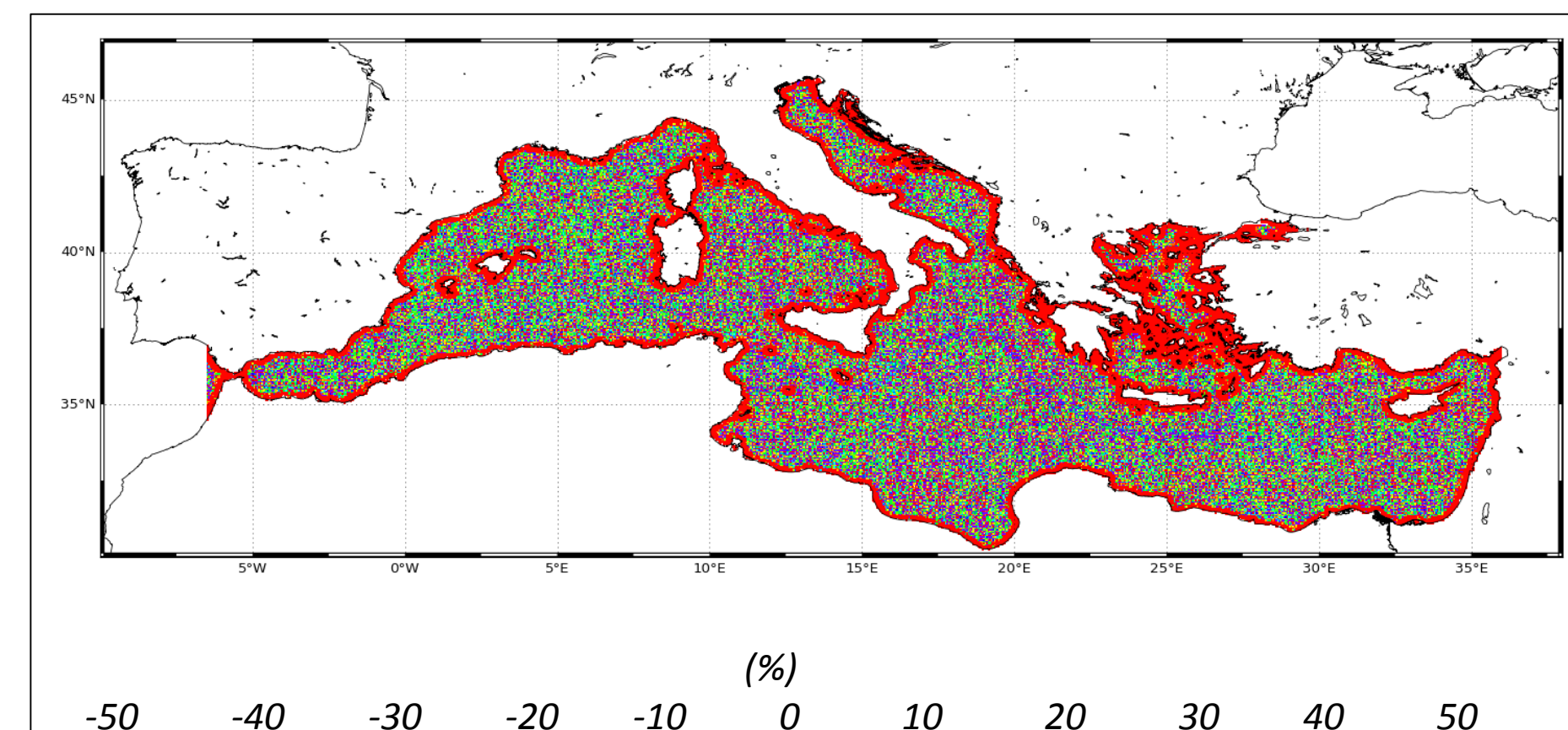
- For repetitive orbits, cross-tracks gradients are improved using reference Mean profile updated in order to take into account the new standards and to improve the quality near the coast. For geodetic missions, many points has been gained along the coast by using a more accurate MSS.

NTC L2P	ERS-1	ERS-2	T/P	EN	J1	J2	GFO	C2	AL	H2	J3	S3A
Orbit	Reper (Ruben et al., 2012)	GNSS STDs Level 3, 365, 1012 altimetry	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS
Sea State Bias	BM1 (Gang, 1994)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	Non parametric (Jin et al., 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)
Ionosphere	Ruger (Ruger, 2005) using 70 to 80 km and with 100 to 150 km and equivalent of GDR (Jin et al., 2005)	GNSS derived Path Delay (Fernandes et al., 2015)	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS
Wet troposphere	GNSS derived Path Delay (Fernandes et al., 2015)	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS	GNSS
Dry troposphere	Model based on ERA-INTERIM	Model based on ERA-INTERIM	Model based on ERA-INTERIM	Model based on ERA-INTERIM	Model based on ERA-INTERIM	Model based on ERA-INTERIM	Model based on ERA-INTERIM	Model based on ERA-INTERIM	Model based on ERA-INTERIM	Model based on ERA-INTERIM	Model based on ERA-INTERIM	Model based on ERA-INTERIM
Combined atmospheric correction	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies	MOG2D High frequencies forced with analyzed ERA-INTERIM pressure and wind field + inverse barometer Low frequencies
Ocean tide												
Solid Earth tide												
Pole tide												
MSS												

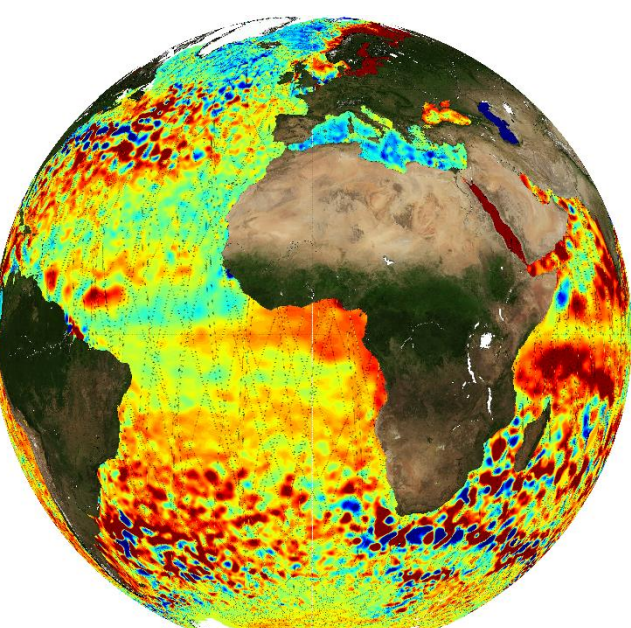
Standards of the different corrections applied on altimetric measurements for the DT-2018 processing. The green cells indicate a change with the previous version DT-2014.



Mean daily SLA (m) for the full reprocessing and for all missions between 1992 and 2017. Computed from L3 daily raw datasets.



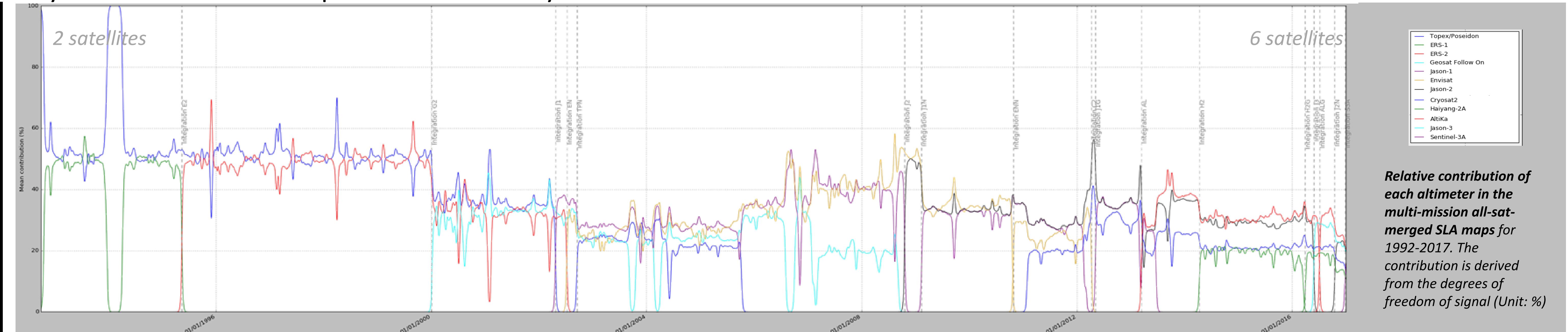
Percentage of Along-Track SLA data in the DT-2018 product which were not taken into account in the old version DT-2014. Only geodetic missions are taken into account



Level 4 improvements : from global to mesoscale

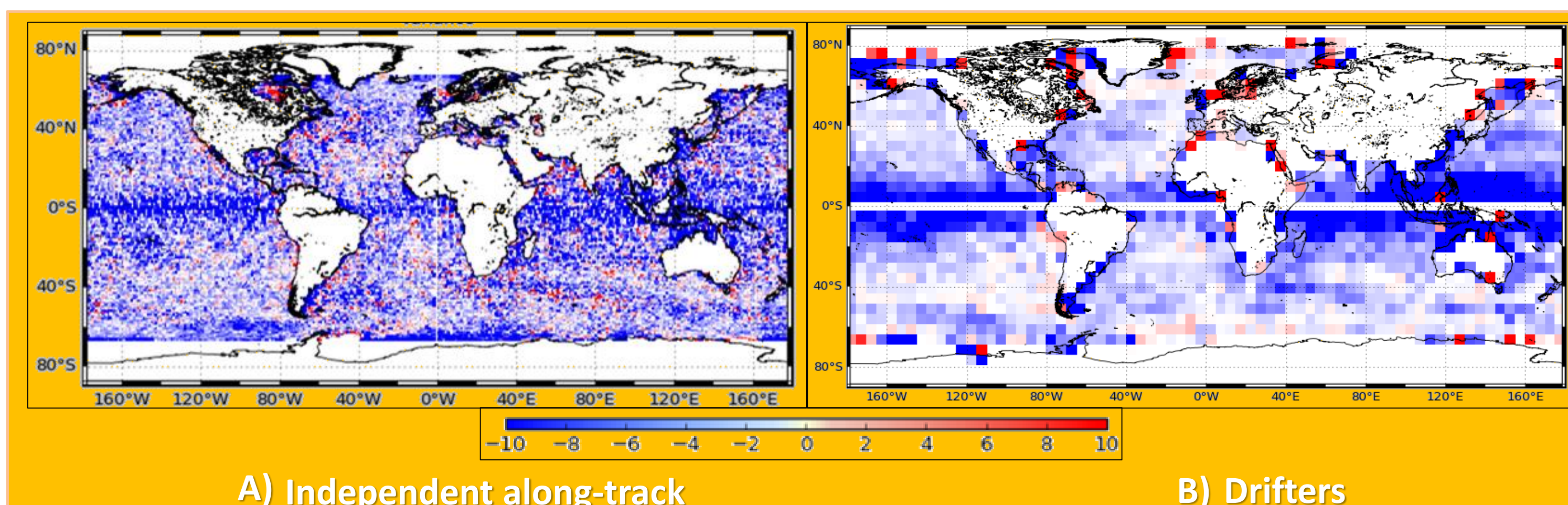
Improvements come from :
New mapping parameters: Optimized spatio-temporal selection of the observations, better a-priori knowledge of the signal variance based on 20 years of altimetry data, tuned correlation scale ...

25 years of altimetric data have been processed i.e. 76 cumulated years with 12 missions



Relative contribution of each altimeter in the multi-mission all-sat merged SLA maps for 1992-2017. The contribution is derived from the degrees of freedom of signal (Unit: %)

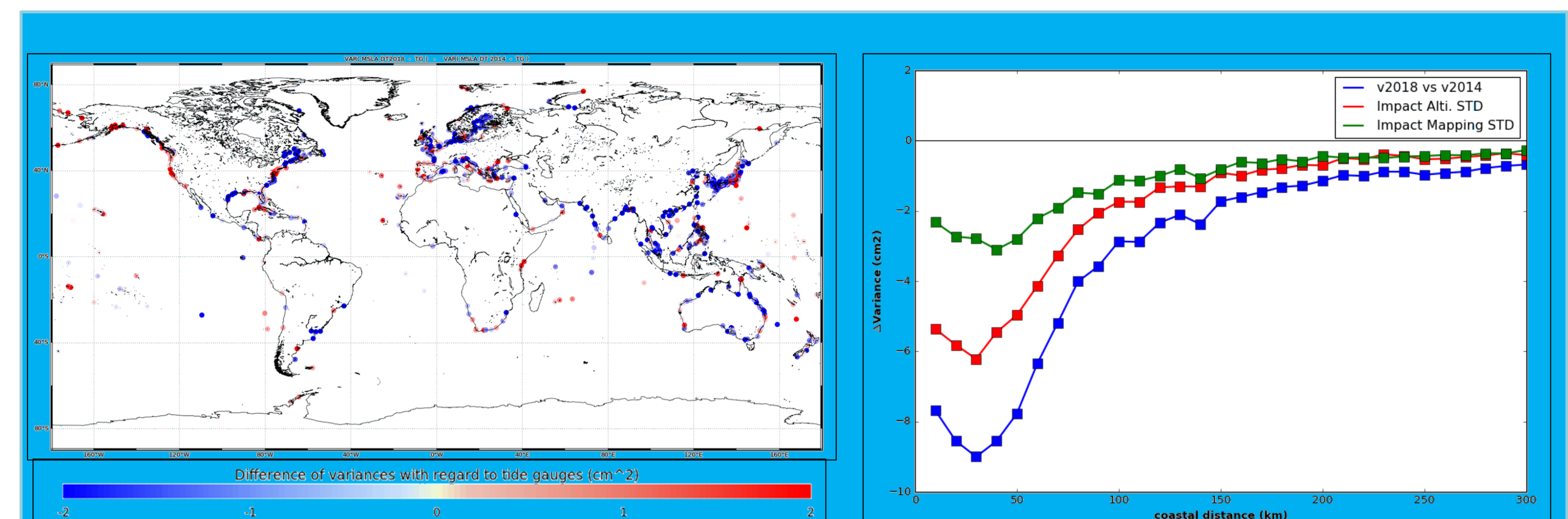
Improvements have been measured using independants datasets:



A) Independent along-track

B) Drifters

Fig.: Illustration of the improvement (in blue) / deterioration (in red) DT2018 vs DT2014. A) Reduction of variance between SLA maps and independent TPN along-tracks (units: in %) B) Reduction of variance between geostrophic velocities derived from DT2018 maps and independent drifters data (only the zonal component is displayed, units: in %)



C) Tide gauges

D) Independent along-track

Fig.: Illustration coastal improvement (in blue) / deterioration (in red) DT2018 vs DT2014. C) Reduction of variance between SLA maps and independent tide gauges (units: in cm²). D) Reduction of variance between maps and independent C2 along-tracks as a function of the coastal distance (units: in cm²)

Conclusions & perspectives

First results are very promising :

- DT2018 products benefit of large scale and meso-scale improvement compared with DT2014
- Largest improvements are found in coastal regions and are mainly associated with new altimetry standards. Offshore improvements are mainly linked to the new mapping parameters.

An additional accurate and homogeneous altimeter gridded sea level product based on a stable two-satellite merged constellation will be also distributed in the frame of the Copernicus Climate Service (C3S).

Perspectives:

- The time series will be extended until mid 2017
- More S3A data will be available : New data (version 02.00) will be included in 2016 and 2017 !

Available in March 2018 in the Copernicus Marine Service (CMEMS) catalogue