Ocean Surface Topography Science Team Meeting *Precise Orbit Determination Splinter*

North-South miscentering of the Jason-3 orbit observed by its yaw-flip capability

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Introduction



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 - Previous approaches
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 - Flips approach (GPS int ambiguity)
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 - Flips approach (other measurements)
 - Conclusion
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Context

- Satellite: Jason-3
- Nominal orientation: nadir Earth-pointed
- Attitude law:
 - Yaw steering when $\beta' > 15^{\circ}$ and $\beta' < -15^{\circ}$
 - Fixed yaw when -15°<β'<15°
 - A yaw flip is performed at β'=0°

Yaw flip benefits:

- Disentangle time tagging from along-track center of phase POD instrument offsets
- Observe separately the combined effects of crosstrack miscalibrated SRP models/thermal effects or POD instrument locations, and the Z-component of geocenter motion whose amplitude is thoroughly debated





Context

<u>Goal</u>:

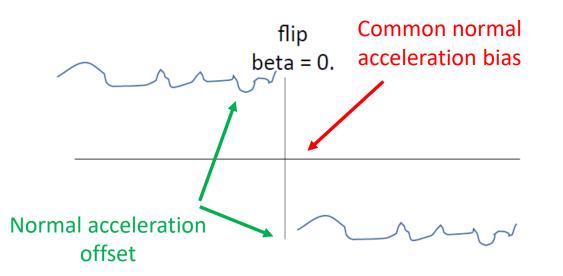
- Monitoring of the residual normal perturbations
- Observation of the geocenter motion estimates in the Z (North-South) direction
 - Comparison with previous methods

Approach:

- Focus on orbit arcs where flip events occur
- Definition of the 8-day orbit arcs: 4 days before and after the flip events
- Estimated empirical parameters:
 - o constant cross-track accelerations with 4-day intervals
 - o periodic once-per-revolution accelerations in the along/cross-track directions with 1-day intervals
 - constant along-track accelerations with 2 orbital period intervals

Context





Normal acceleration offset before and after the flip caused by:

- Cross-track error in the POD center of phase location
- Residual SRP modeling error of the satellite normal surfaces
- Unmodeled satellite thermal effects

Common normal acceleration bias on both sides of the flip caused by:

- Geocenter motion in the Z direction (mainly)
- Residual solar-reflected/Earth-emitted radiation modeling errors?

The miscentering of the orbit around the Earth's CM in the Z direction can be recovered using the equation:

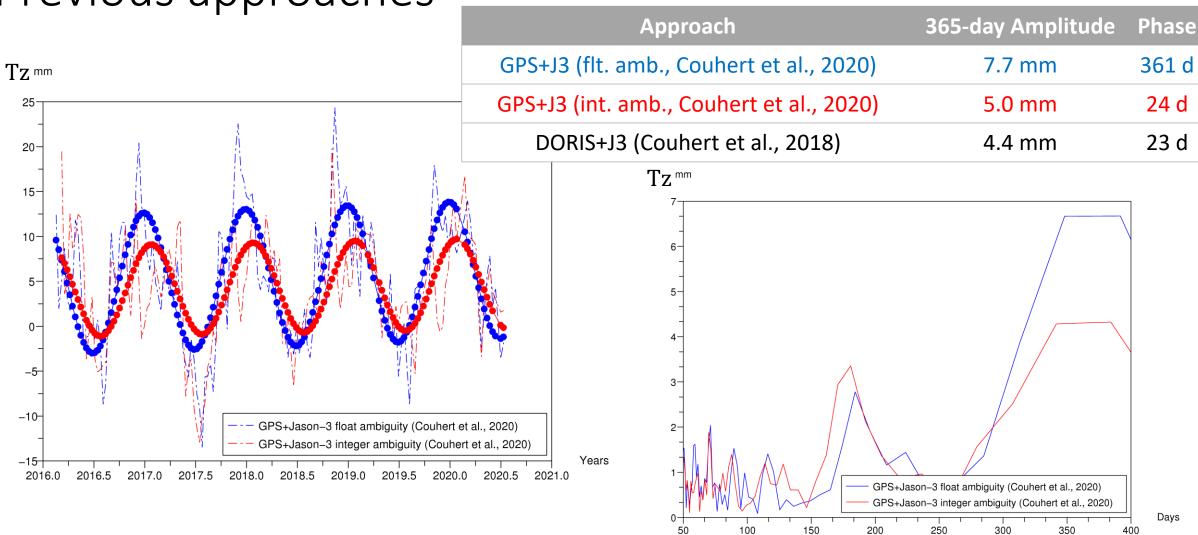
$$Tz = \frac{-C_{N0} r^3}{GMcos(i)}$$

where C_{N0} is the common cross-track acceleration bias

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Previous approaches



OSTST 2020

-2

-3

24200

24600

24800

25000

Period (davs)

24400



Normal offset (GPS int. ambiguity)

GPS measurements: integer ambiguity

Offsets of the estimated normal accelerations before/after the flip (the common bias has been removed), which can be attributed to a wrong cross-track center of phase/mass location. The correction to be applied is given by:

► 2*C_{N0}*

25800

25400

25200

25600

$$\frac{C_{N0}}{\omega_0^2} = 1.15 \ mm$$

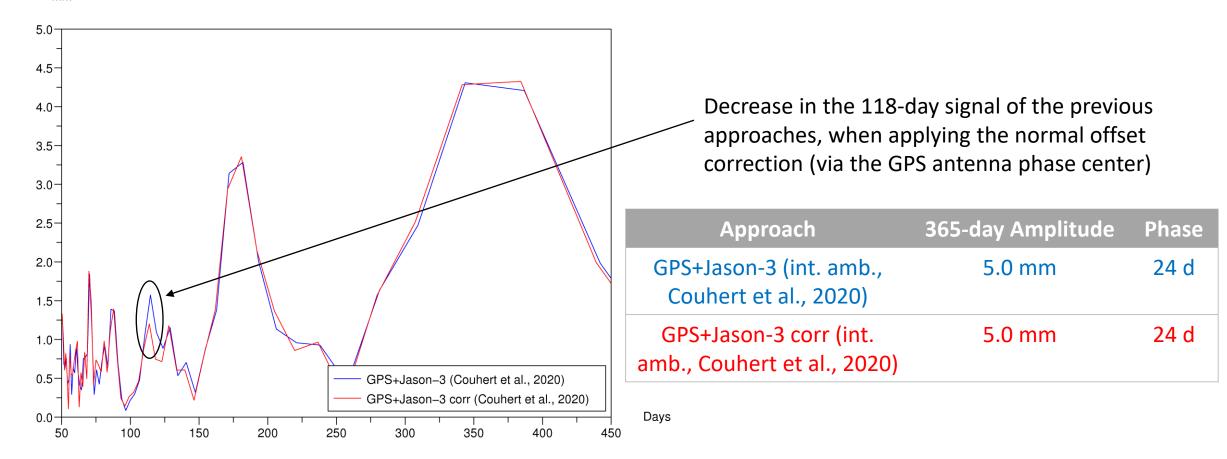
Nota: the two groups of colors (blue/orange) denote the forward and backward flying attitude regimes

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Normal offset (GPS int. ambiguity)

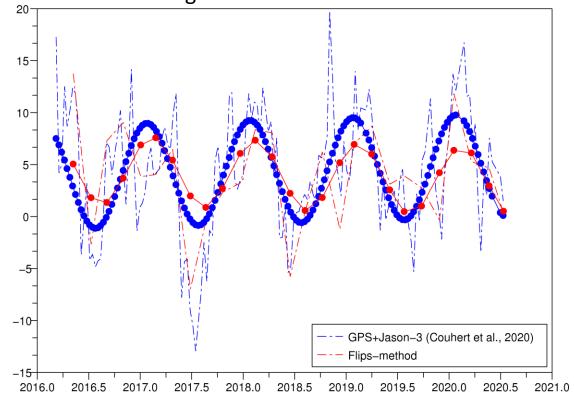
 Tz_{mm}

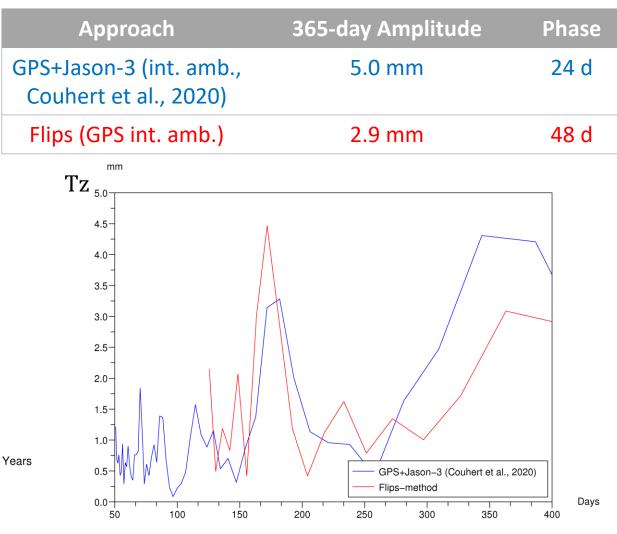




Flips approach (GPS int. ambiguity)

 Tz_{mm} Common normal acceleration biases estimated on both sides of the flips reflecting the North-South miscentering of the Jason-3 orbit





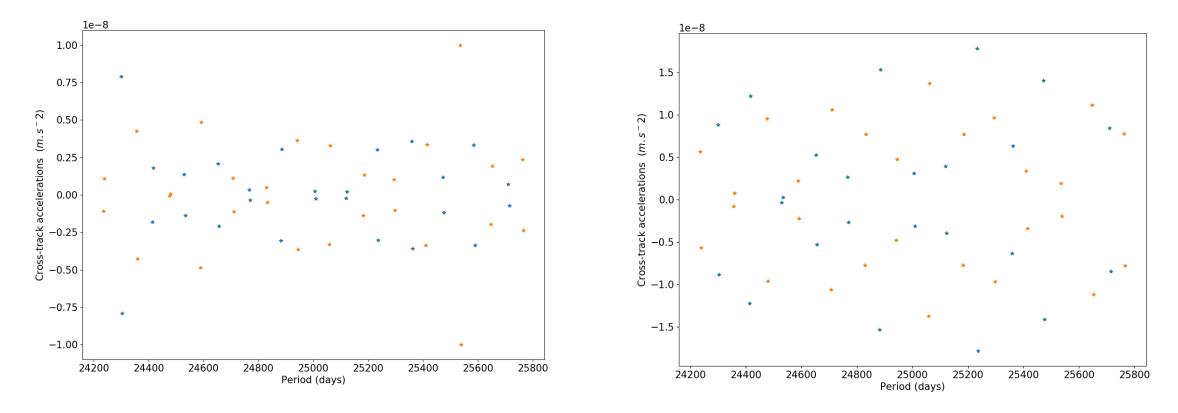
OSTST 2020



Normal offset (other measurements)

GPS measurements: float ambiguity

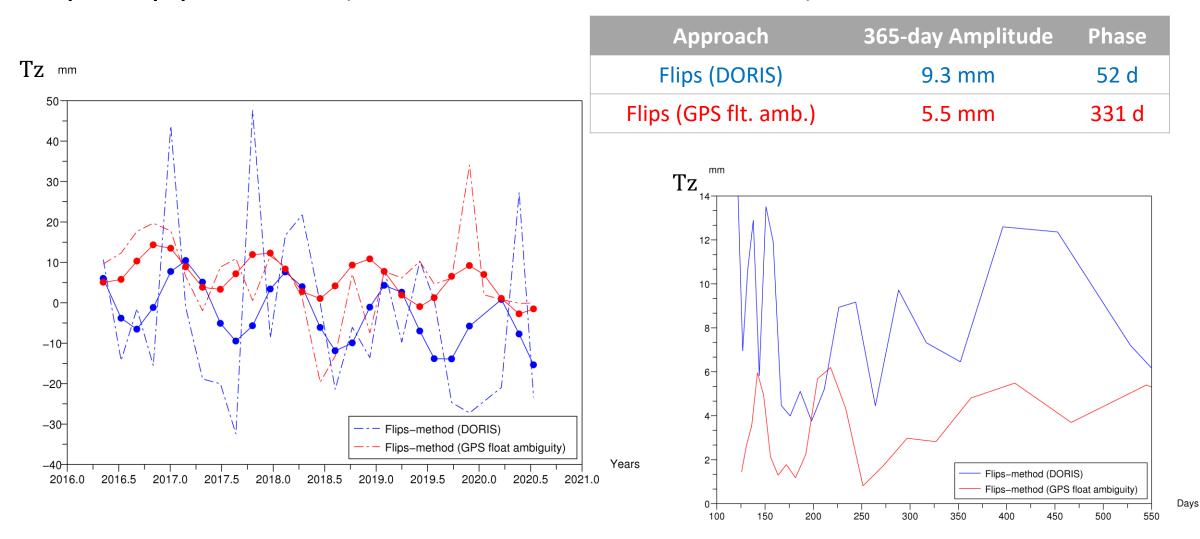
DORIS measurements



The observability of these measurements in the crosstrack direction is not strong enough



Flips approach (other measurements)



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Conclusion

- The flips approach allows us to observe specifically the geocenter motion along the Z (North-South) axis.
- The 60-day sampling and/or residual errors in the modelling of solar-reflected/Earth-emitted radiations could explain the differences in the annual TZ geocenter estimates between the flips and previous approaches.
- Yaw flips are specific to the T/P and Jason missions. A recommendation of the OSTST POD group is to maintain the yaw flips for the Sentinel-6/Jason-CS mission.