



SARAL Project Status



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Major events since last OSTST (October, 2015)

- July 2016 : New mission phase SARAL-DP
- Satellite major events
 - concerns about station keeping (ground track maintainance)
 - + 1km sma increase before to start the DP phase
 - concerns about RW stiction/friction
- Payload major events
 - None
- Ground major events
 - Better X-Band antenna availability : new antenna in Inuvik

Current SARAL-DP mission Status is OK

Platform Status

The SARAL satellite bus is **OK**

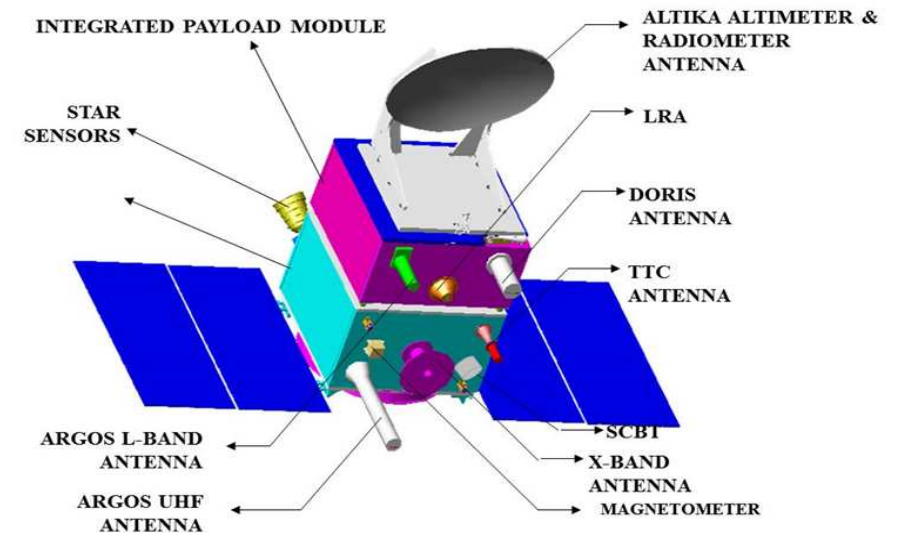
- Command / control , RF :
- Thermal aspects :
- Electrical aspects :
- AOCS (attitude and orbit control system) :
with some concerns on reaction wheels

OK

OK

OK

OK



SARAL bus is operational after 3,5 years in orbit

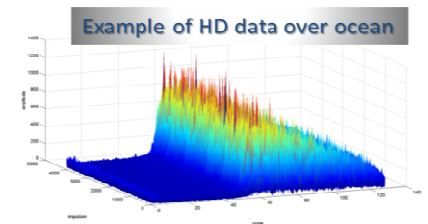
Payload Status since last OSTST (October, 2015)

- 100% available

- **AltiKa**

- routine calibrations PTR, LPF
- quarterly CNG calibrations I^2+Q^2
- specific calibrations over sea & ice (HD mode)

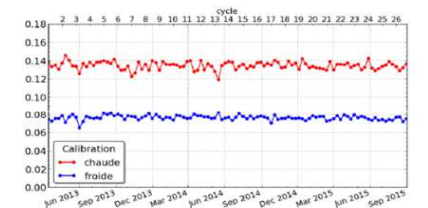
OK



- **Radiometer**

- Very good stability & sensitivity
- 6 March, 15 May & 6 August : temporary radiometer K band saturation over South Africa due to weather radar
- 29 August : same, over Hamburg (Germany)

OK



- **DORIS**

- Nominal

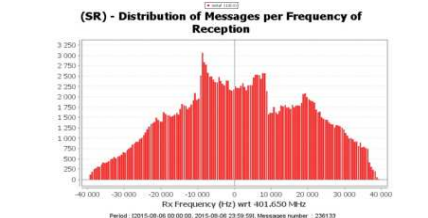
OK



- **ARGOS**

- Nominal; performance similar to other satellites

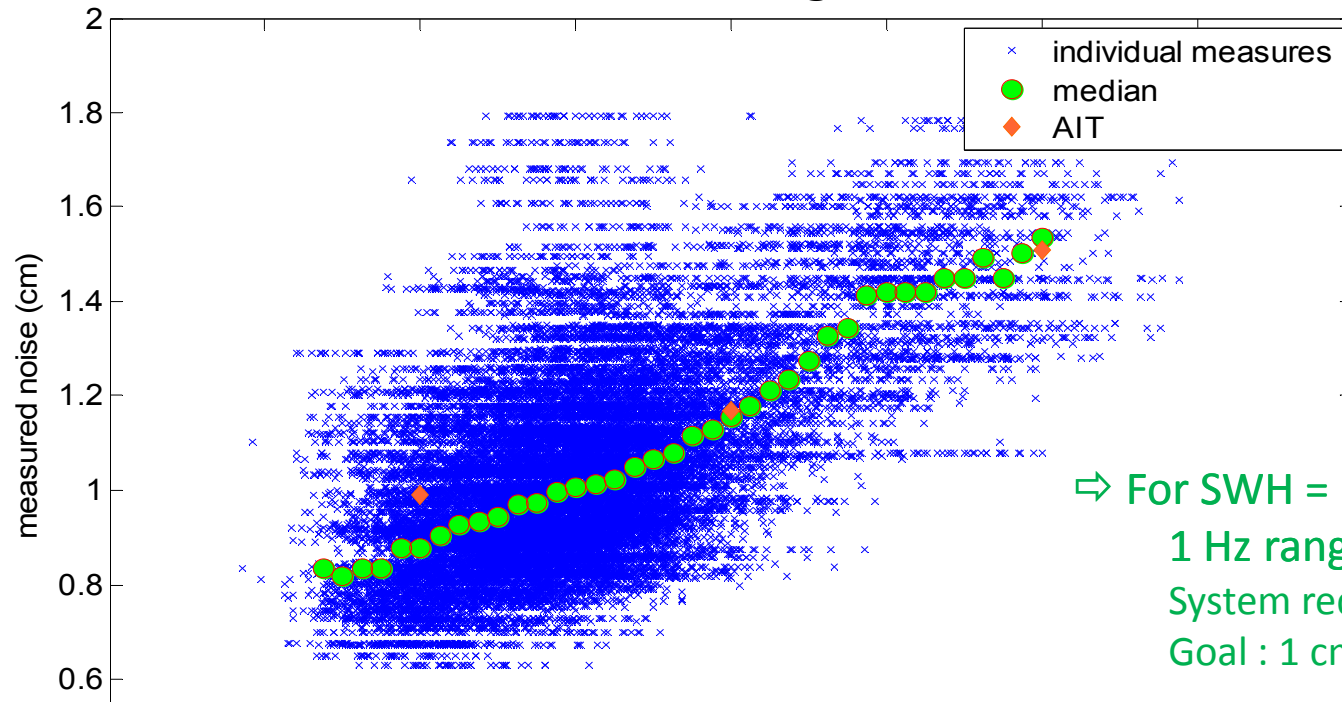
OK



➔ **fully OPERATIONAL**

Altimeter performances – range noise

RANGE NOISE @ 1Hz



⇒ For SWH = 2 m

1 Hz range : 0,9 cm

System requirement : 1,5 cm

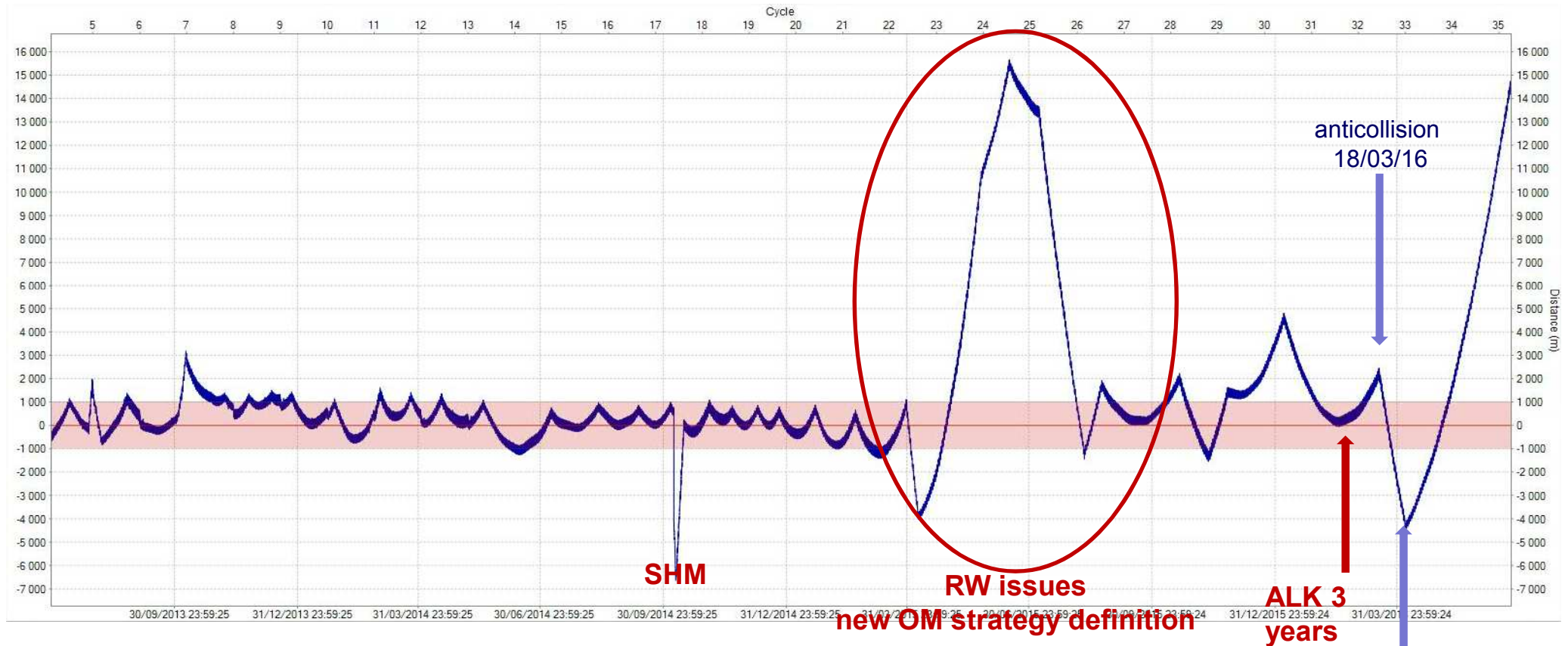
Goal : 1 cm

Altimeter parameter	Specifications	Measured on ground	In flight data
1 Hz range	1.5 cm	0.9 cm	0.9 cm
1Hz SWH	6.3 cm	5.7 cm	5 cm
1 Hz Sigma0	0.2 dB*	N/A	0.012 dB

Ground & Operations - Status and performances

- Earth terminals :
 - ISRO band-S (Bangalore, Lucknow) OK
 - ISRO band-X (Shadnagar) OK
 - CNES band-X (Kiruna and Inuvik) OK
- Control Centers :
 - ISRO/ISTRAC Control center OK
- Instrument Commanding and Monitoring Centers :
 - SSALTO for Altimetry OK
 - ARGOS PC for ARGOS OK

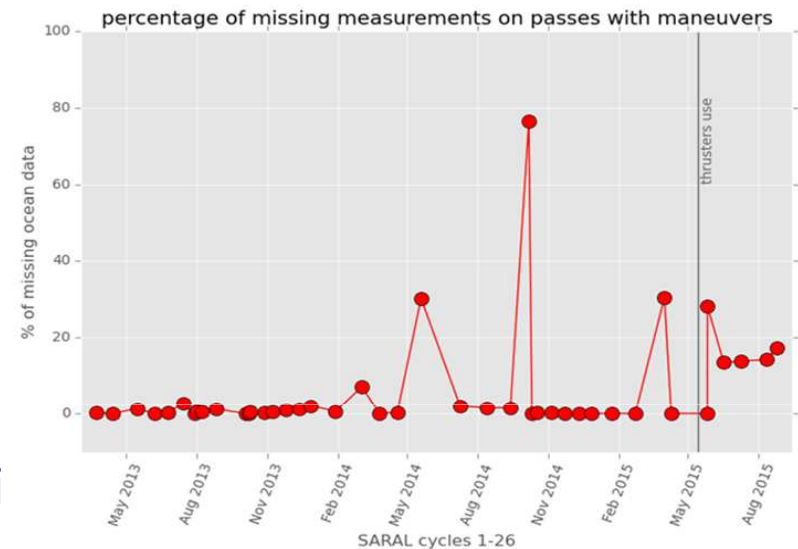
SARAL Drifting Phase



Before March 2015, 90% of time in the ground track

SARAL Drifting Phase history

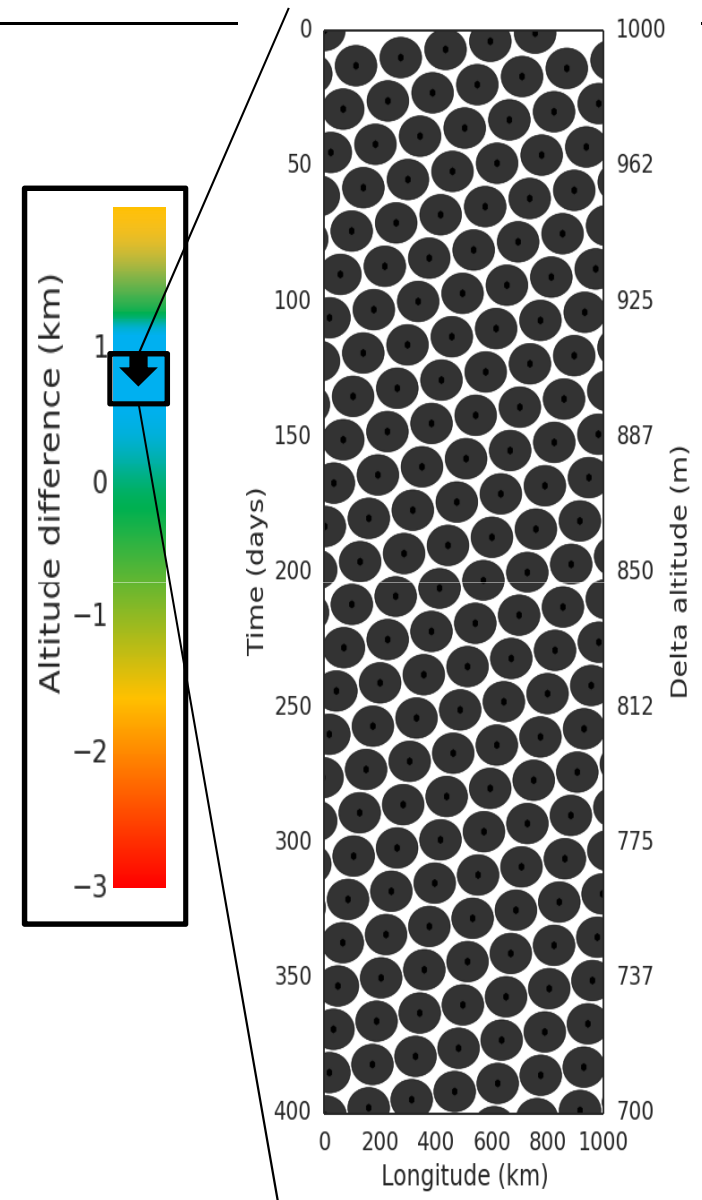
- Since March 2015, maneuvers with thrusters in place with concerns for OPS team, altimetry, ARGOS
- October 2015 : 2 recommendations from the OSTST
- 25 February 2016 : SARAL/AltiKa 3 years in orbit
- Early 2016 : CNES study for determining the optimum orbit
- April 2016 : ISRO and CNES decide to implement a new phase for SARAL – **SARAL Drifting Phase**
- **4 July 2016 : start of the new phase**



WHY INCREASE THE ALTITUDE ?

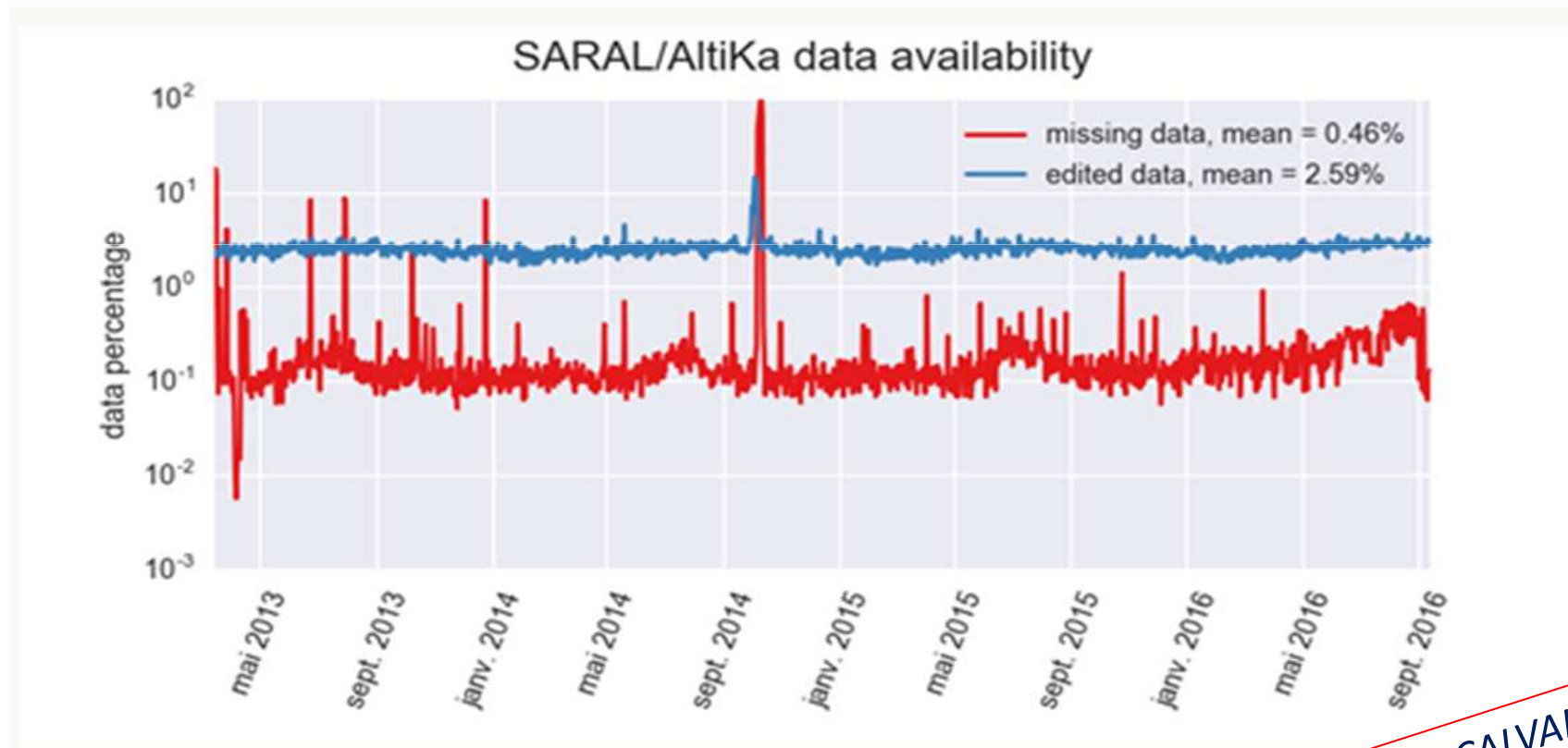
- No overlap between circles
- Excellent balance between space and time
- Altimeter tracks are well positioned thanks to the 16-day sub-cycle

➔ Mesoscale sampling is **excellent** for at least 3 years



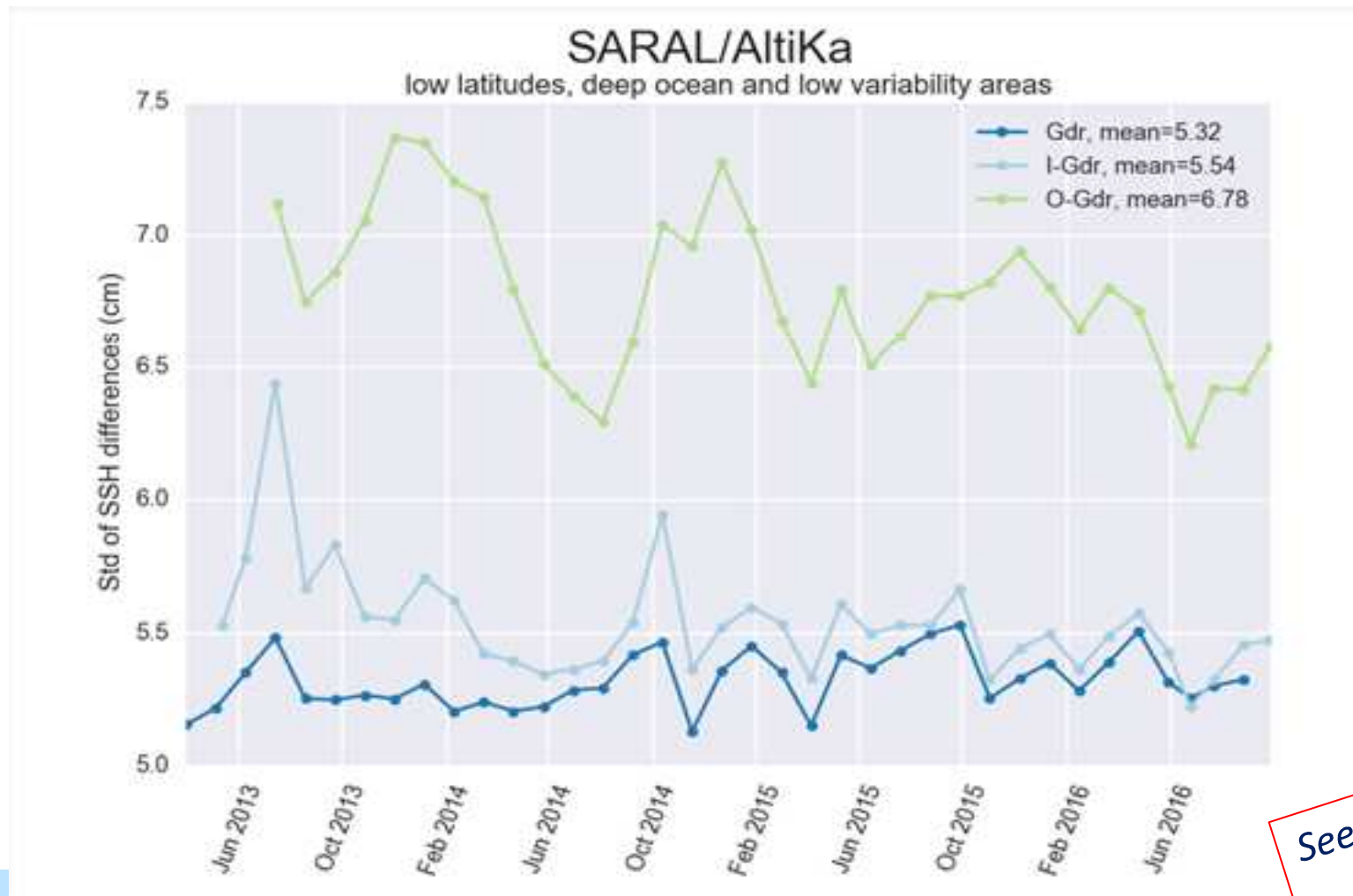
Performances : Data availability – ocean only

- Exceeds mission requirements : **99.5%**



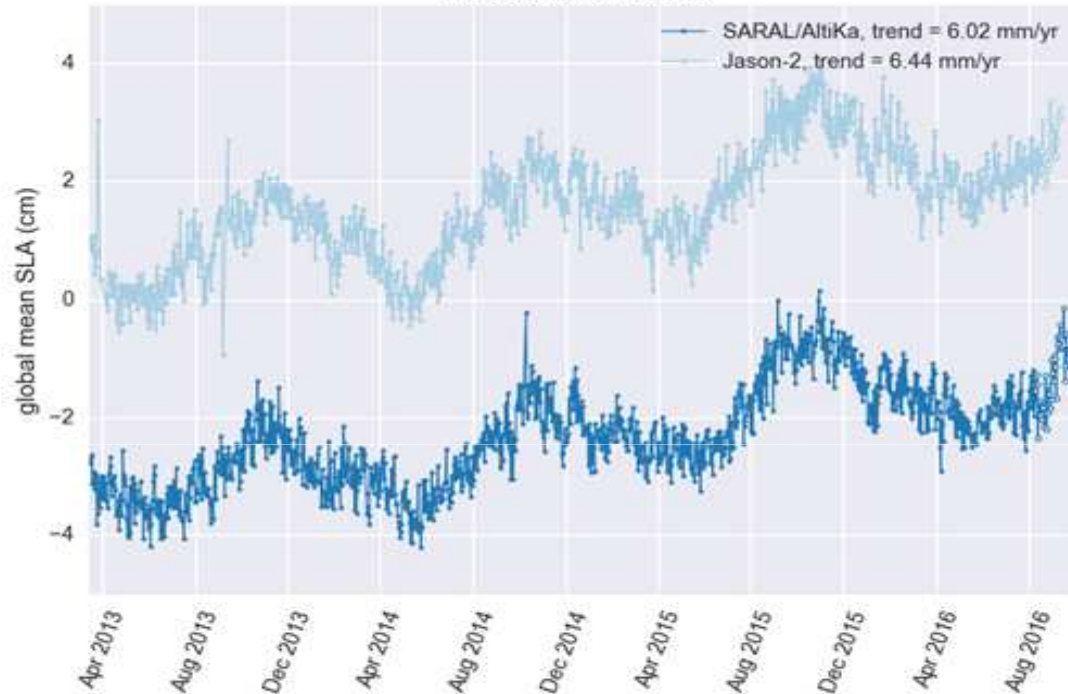
See CALVAL poster
CVL-015
- 10 -

Performances : Xover - 5.32 cm for GDRs



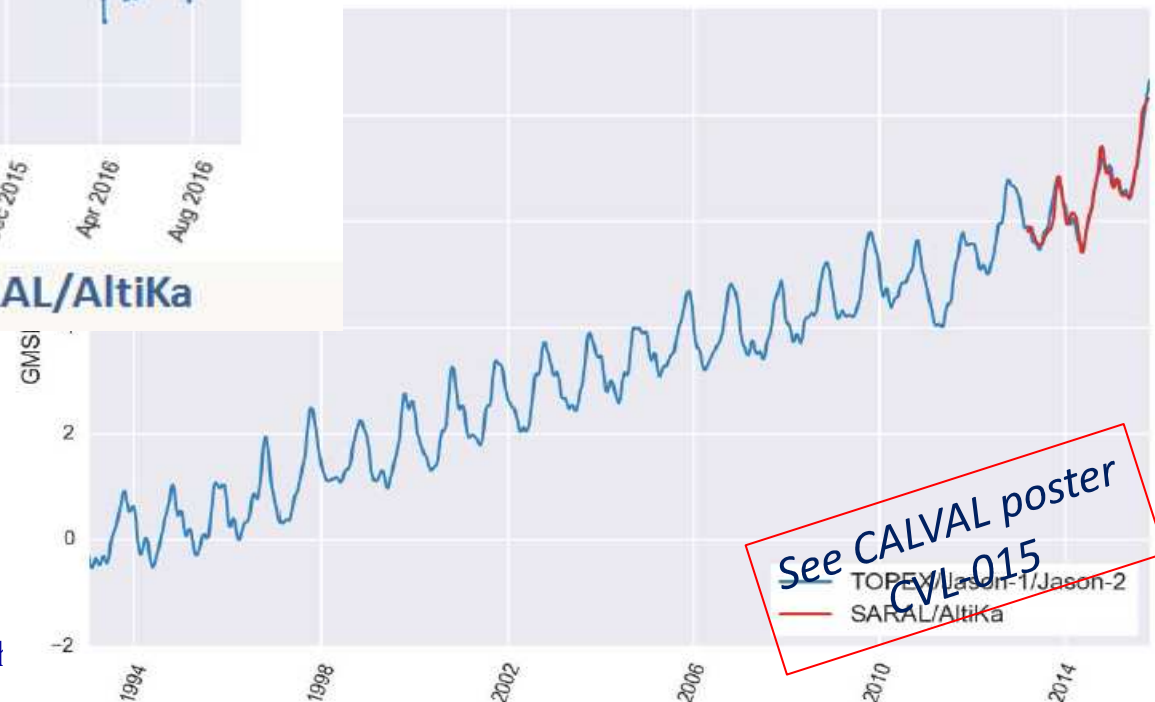
See CALVAL poster
CVL-015

Global Mean Sea Level latitudes lower than 66°



GMSL records for Jason-2 and SARAL/AltiKa

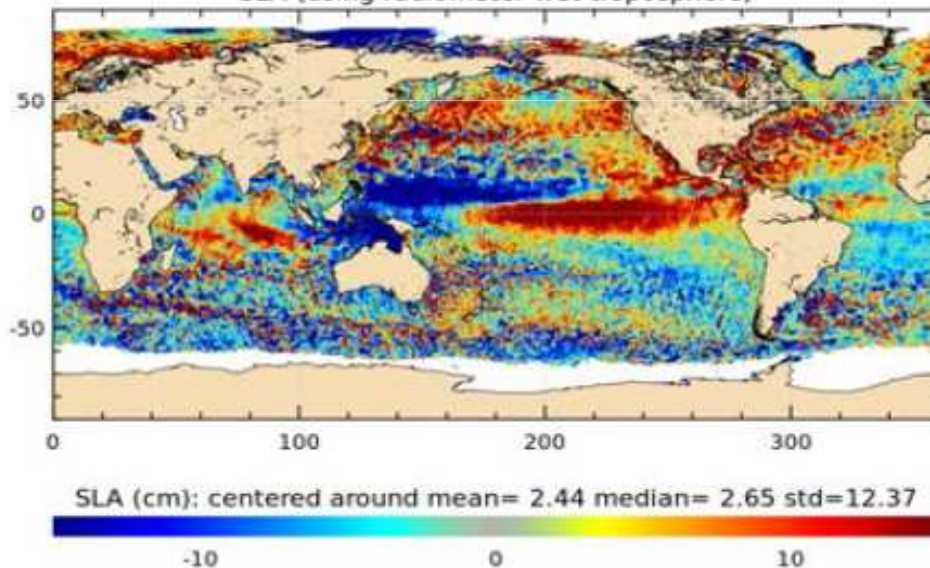
Mean Sea Level
same pattern than Jason-2



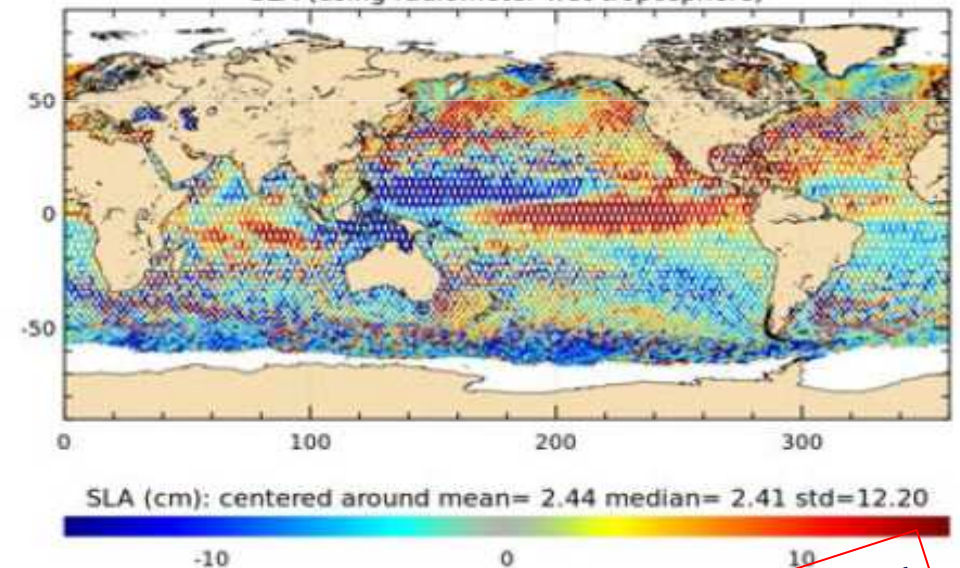
Sea-level anomaly performances (Altika vs Jason-2)

Very limited differences; Good agreement

Altika (2015-09-10 to 2015-10-15)
SLA (using radiometer wet troposphere)



Jason-2 (2015-09-10 to 2015-10-15)
SLA (using radiometer wet troposphere)



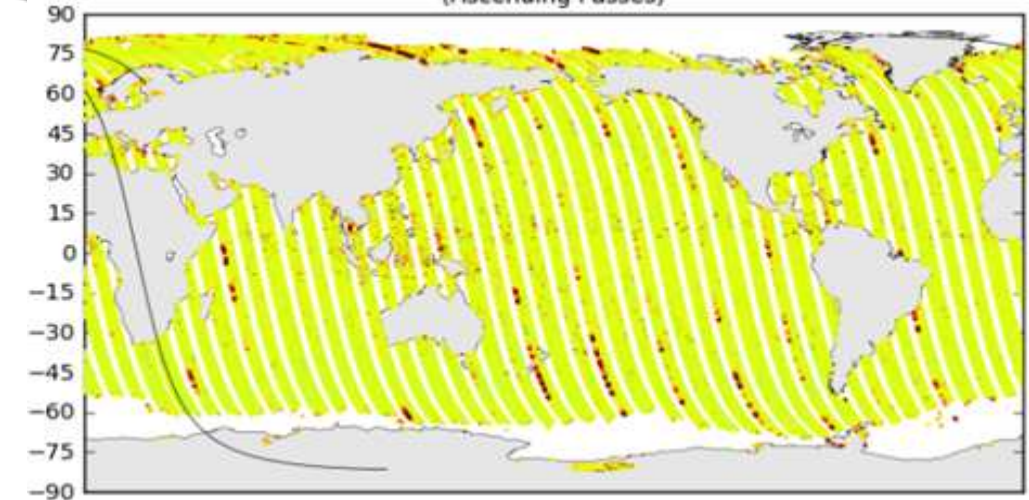
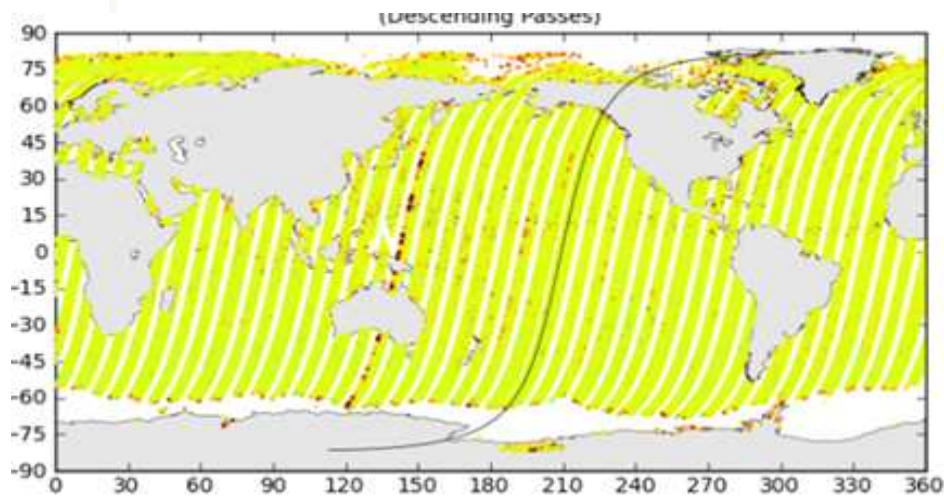
See CALVAL poster
CVL-015

products latency

Product	Requirement	Effective performance for REVEX period		
		Revex#1	Revex#2	from 1/10/2015 to 30/9/2016
OGDR	75% ≤ 3 hours 95% ≤ 5 hours	97% < 3 hours ¹ 97% < 5 hours	97.6% < 3 hours 98% < 5 hours	97% < 3 hours 99.3% < 5 hours
IGDR	< 3 days (objective : 1 or 1,5 days max)	95,65% < 1,5d 99,7% < 3d	97,18% < 1,5d 99,61% < 3d	97,05% < 1,5d 99,5% < 3d
GDR	~40 days	compliant for 9 cycles over 12	compliant (average: 35 days)	compliant (average: 34 days)

Still some issues with nadir pointing

waveform mispointing



System Requirements and Performances

from October 2015 until October 2016

⇒ **satellite unavailability**

~0 % < **4% req**

– bus : 0%

altimeter : 0%

Doris : 0%

radiometer : 0%

⇒ **ground unavailability**

~0 % < **1% req**

➔ **Global SARAL system availability : 99.7 %**

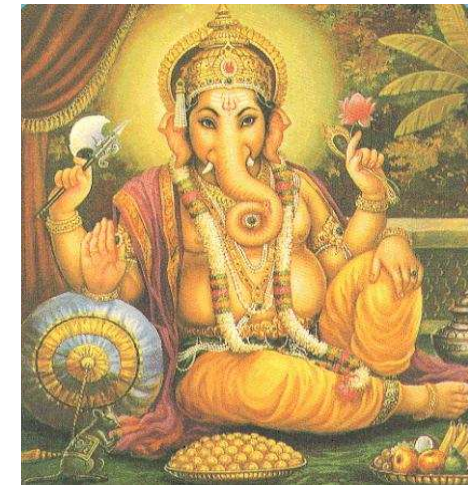
NB : GDR data availability vs theory (from 2015 annual CALVAL report)

All surfaces : 96.7 %

Over Ocean : 99.5 %

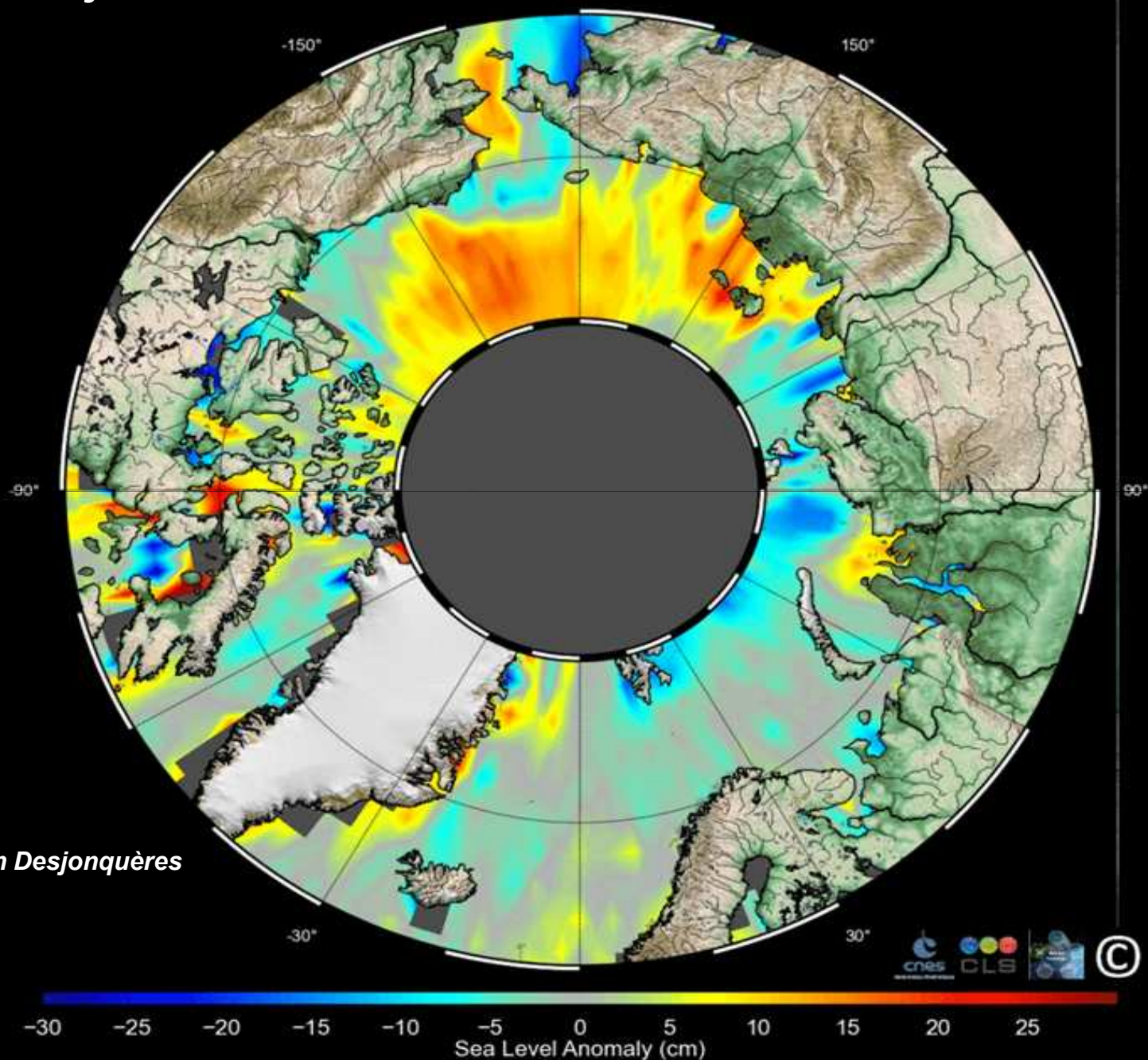
Conclusion

- SARAL satellite is performing well
- AltiKa and ARGOS performances are excellent
- ISRO and CNES have implemented the 2015 OSTST recommendations
→ Drifting Phase since July 2016
- Mission extension process for period [2018-2019]



Thank you for your attention and and also to the contributors !!

- ISRO team
- EUMETSAT team
- CNES Team
 - S. Mazeau
 - D. Delacroix
 - N. Steunou
 - I. Denis
 - N. Picot
 - Jean-Damien Desjonquères
 - F. Didelot
- CLS team



Backup slides

New scenario

- After REVEX #2, CNES has lead a dedicated study. It confirms the scenario proposed in October → move to a drifting orbit

- Oceanography (mesoscale)

Stopping maneuvers on SARAL will not degrade the sampling for 3 years

Recommended to stay within [-0.9 km, +1.2 km] of current altitude

Recommended to increase the altitude by 1 km before the drifting phase

No benefit in a maneuver after the drift starts

Results are the same for all values of solar activity

- Geodesy

Uncontrolled drift provides a random sampling (decent but suboptimal)

Performing maneuvers (even 1/year) is highly undesirable

Results are the same for all values of solar activity

- Link between both applications

Short term: leaving the 1km control band increases SLA error budget (undesirable but not a showstopper on ocean)

Long term: using a drifting orbit helps improving MSS models along uncharted tracks (e.g. SWOT, Sentinel-3, CFOsat)

SARAL 35 days orbit

Influence of sub-cycles on mesoscale sampling

- Altimeter tracks are displayed in the space / time plane (black dots)
- The circle around each dot is the region and period where the track is useful for mesoscale monitoring (correlation > 0.5)
- Sub-cycles control the circles alignments (here 3, 16 and 19 days)
- **Good mesoscale sampling:**
 - Minimizes the white areas (unsampled regions/periods)
 - No overlap between circles (information is not duplicated)
- **Bad mesoscale sampling:**
 - Circles overlap in space or in time (information is duplicated)

