

The End-of-Mission Climate Quality Calibration for the JMR

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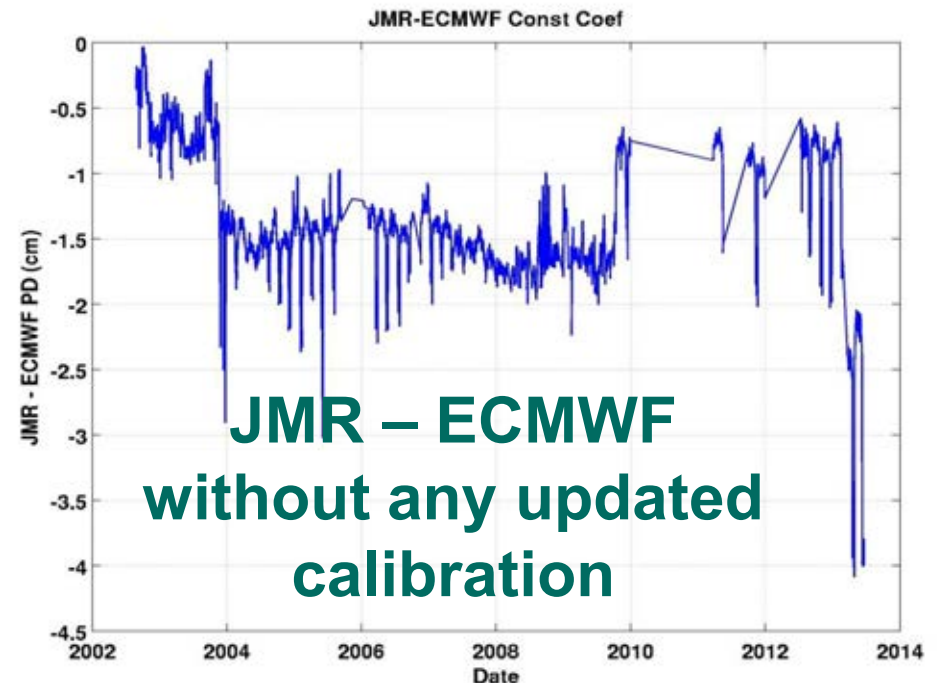
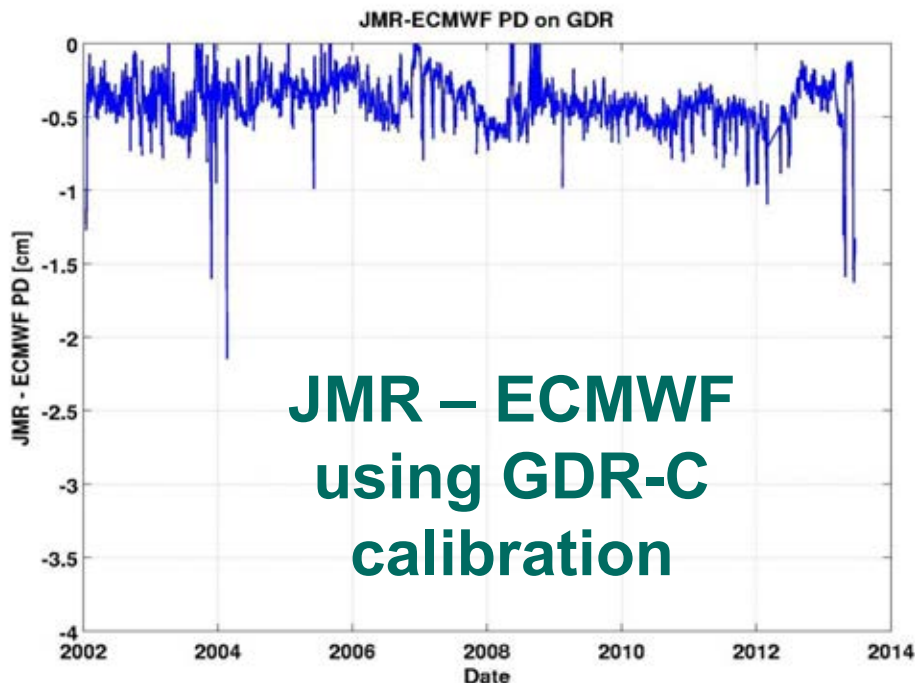
OSTST
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Konstanz, Germany





Overview of JMR GDR-C Calibration

- JMR calibration updated several times during the mission to remove calibration shifts
- 2-4 cm change in PD over mission would be present if nothing had been done

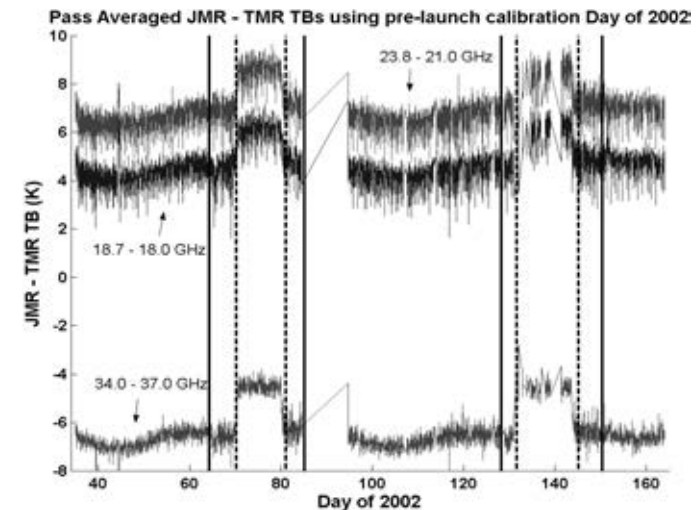




Overview of JMR Calibrations To Date

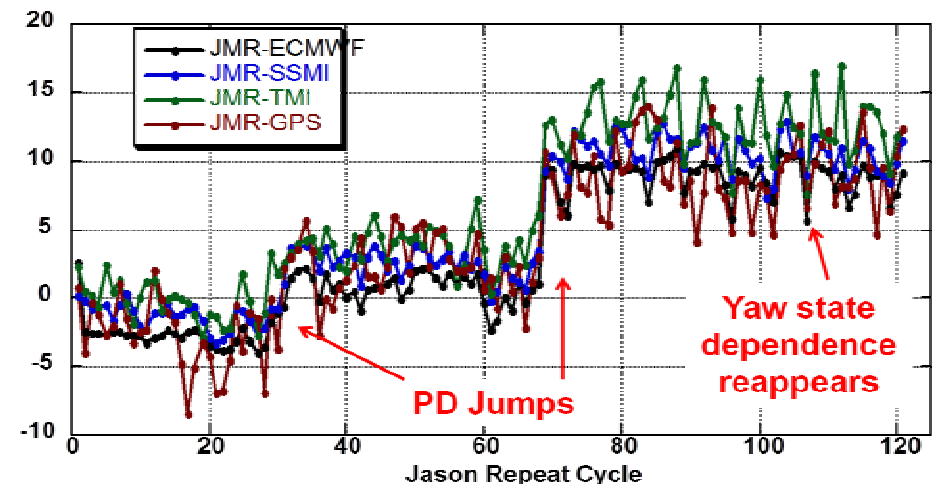
- **July 2002 - GDR-A**

- Pre-launch calibration updated after cal/val phase to remove biases relative to TMR and remove “yaw state” dependence



- **September 2005 - GDR-B**

- Corrected calibration shifts after cycle 30 and cycle 69 using three sets of calibration coefficients.
 - Cycles 1-30, 31-69, 70-present.
- Updated APC algorithm to mitigate geographically correlated errors ~200-500 km from land



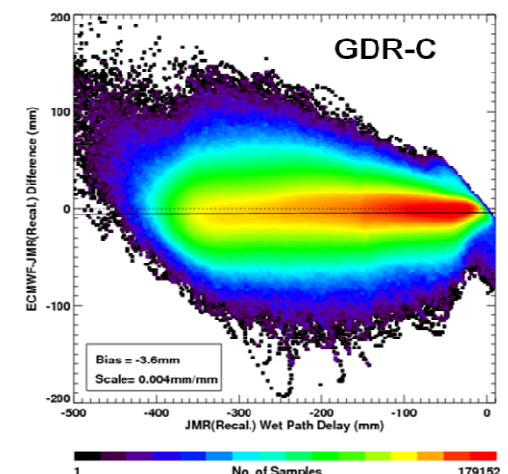
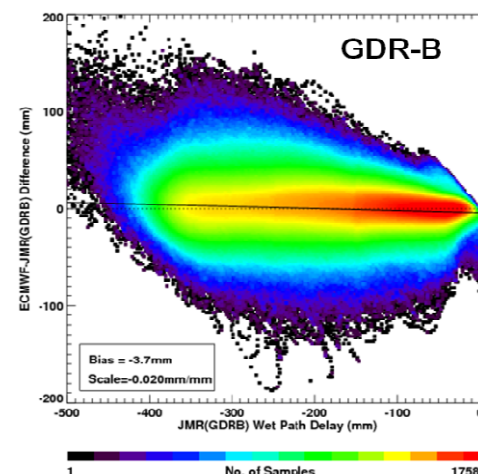
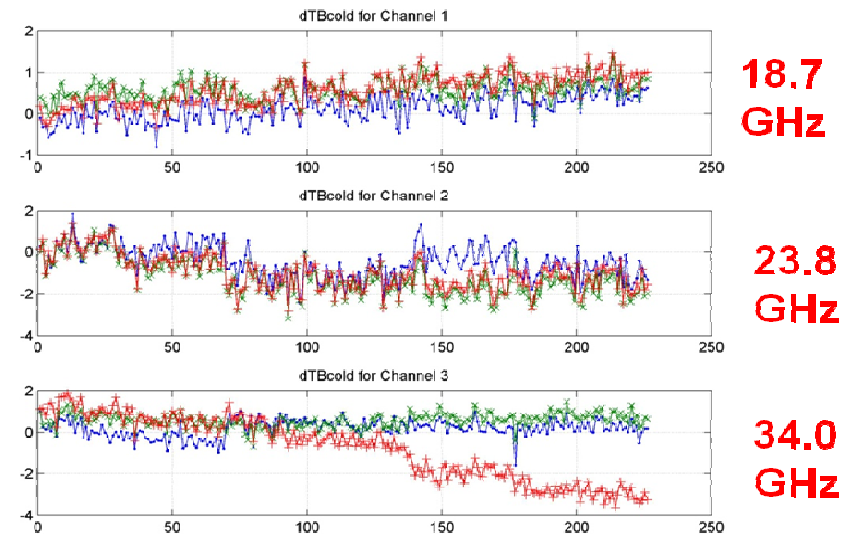


Overview of JMR Calibrations To Date

● April 2008 - GDR-C

- Implemented time-variable calibration coefficients with new coefficients once per cycle.
 - Once per cycle coefficients derived from moving 30-day data window.
- Adjusted path delay algorithm coefficients to remove scale error
 - Error in coefficients carried over from an error in the post-launch calibration of the TMR.

JMR TB Drift Before Calibration





Overview of JMR Calibrations To Date

- **January 2010**

- ~1cm path delay jump observed after September 2009 safhold event
- 23.8 GHz TB calibration corrected prior to GDR processing

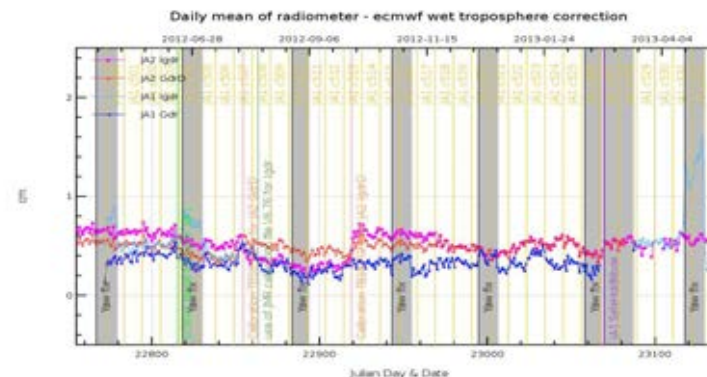
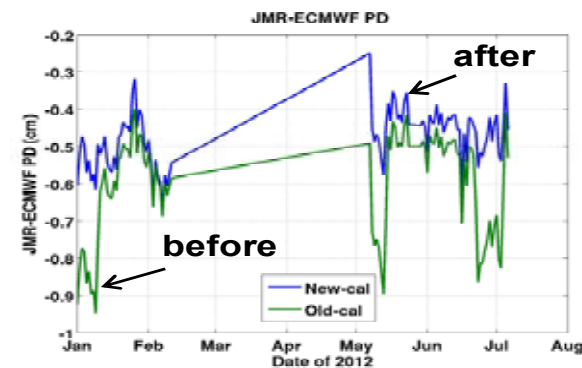
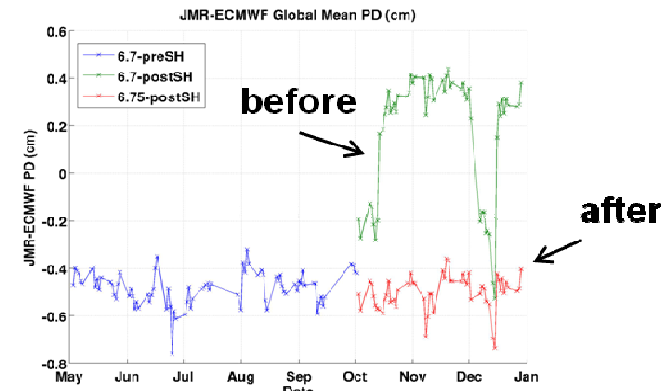
- **July 2012**

- Corrected 23.8 GHz calibration after Feb/March 2012 safhold event to remove ~4mm yaw state dependence

- **July 2013**

- Adjusted calibration after February 2013 safhold to remove 7mm yaw state bias

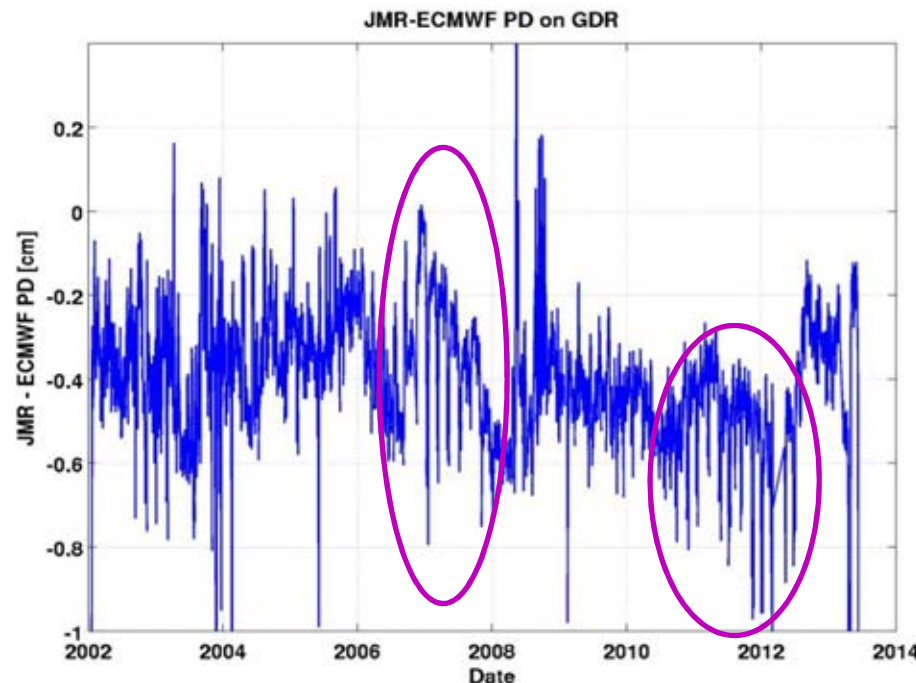
PD Error





End-of-Mission Calibration

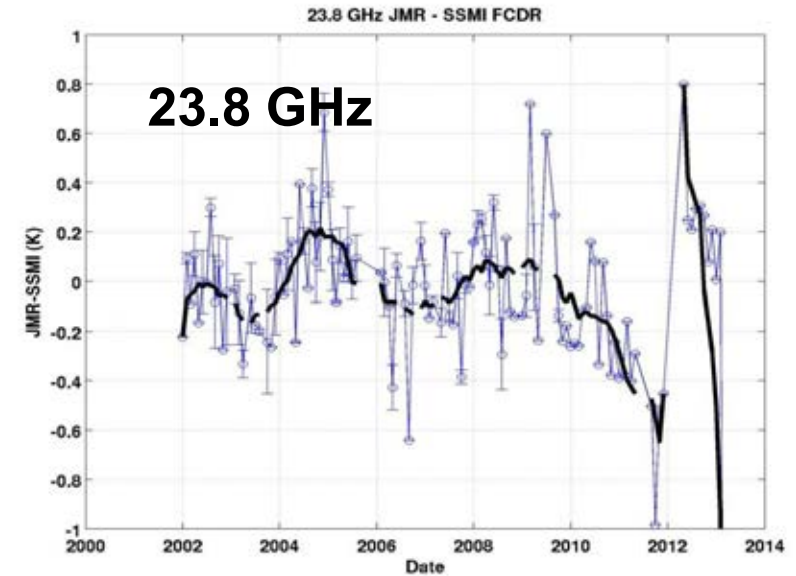
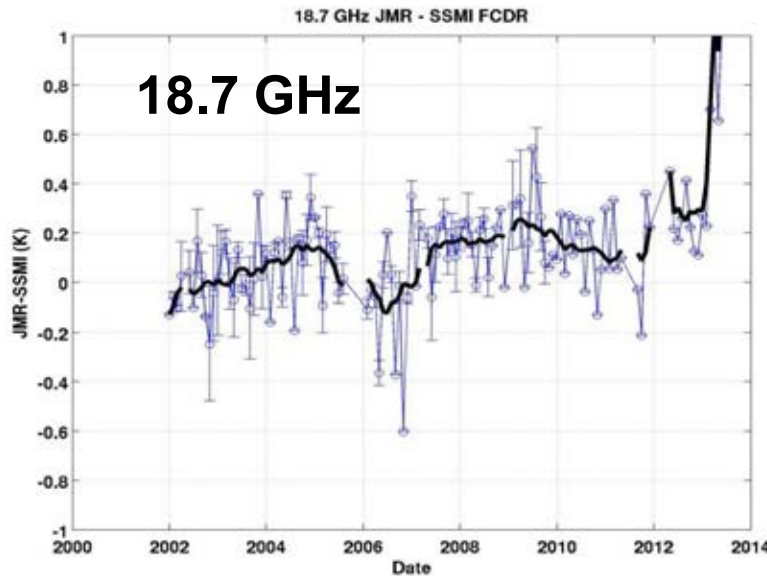
- End of mission re-calibration builds on previous calibration that has been done (e.g. applied on top of existing corrections)
- Remaining issues are to address both short term and long term residual calibration instability evident in the data
 - Long term drift addressed by calibrating the TBs to the SSM/I FCDR
 - Residual yaw state errors derived using PD and WS model comparisons
- Additionally, the algorithms are brought to Jason-2 AMR GDR-D standards



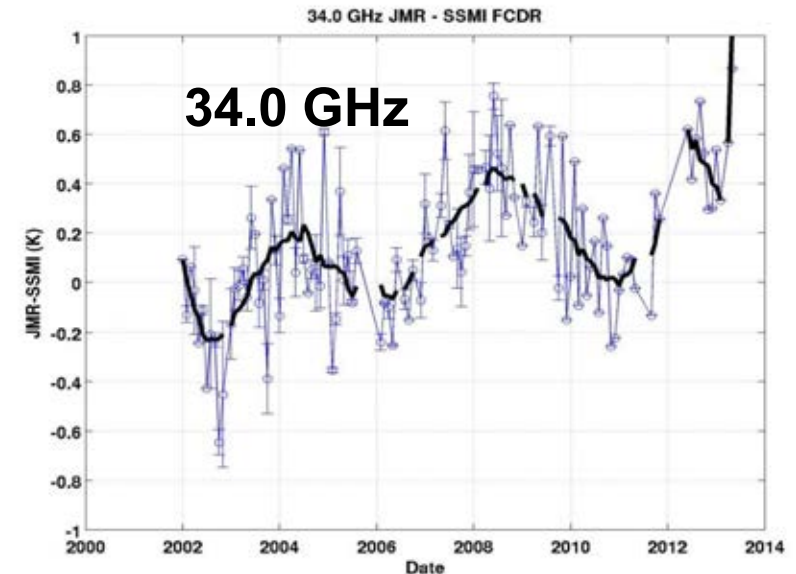
**Both long term
drifts and yaw
state errors
remain**



Cold End TB Drift (Ocean Data)

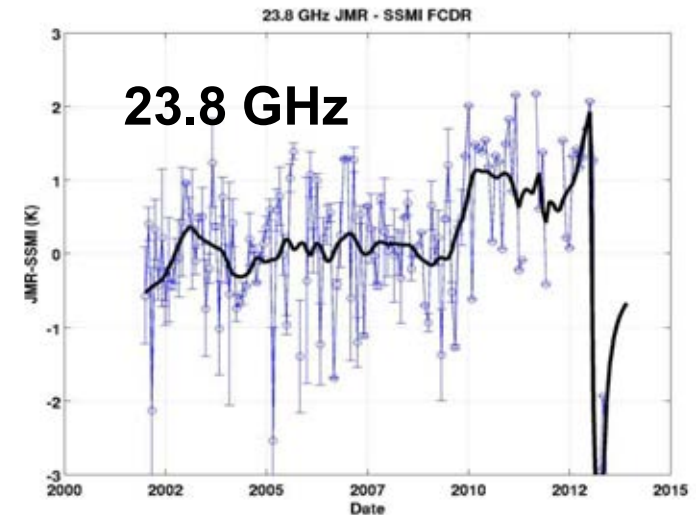
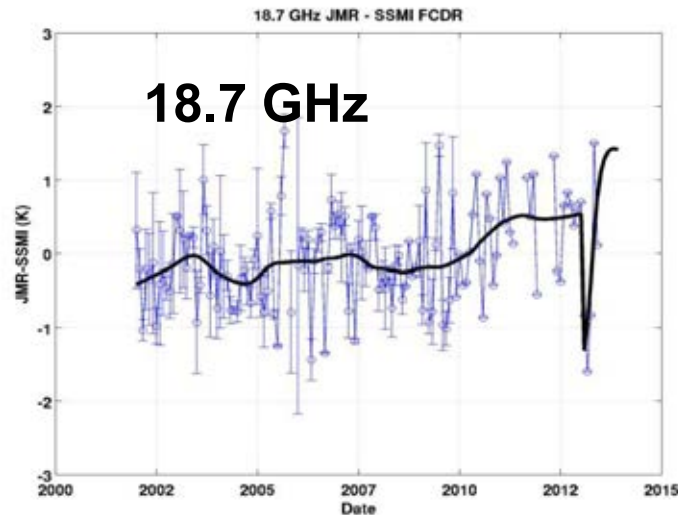
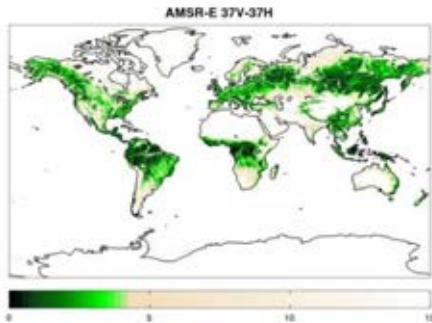


- For each month, computed average JMR calibration bias using SSMI FCDR over ocean
- Applied 12-month running average to isolate long term component
 - Short term component removed separately

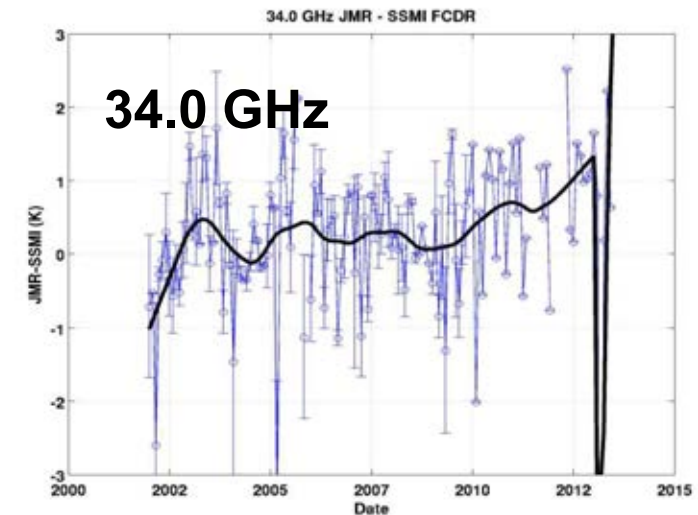




Warm End TB Drift (Rainforest Data)



- Computed differences between JMR TBs and SSMI over heavily vegetated land regions (e.g. rainforest) to constrain the warm end TB drift (~280K)
- Warm end comparisons noisier
 - 2-year running average fit to data
- Largest change (during prime mission) was 1K jump in the 23.8 GHz channel in 2010





Drift Correction



- Drift correction is applied to final GDR –C calibration
- Takes the form of a time variable scale and offset correction

$$TB(ch, t)_{corrected} = TB(ch, t)_{uncorrected} - \Delta T_B(ch, t)$$

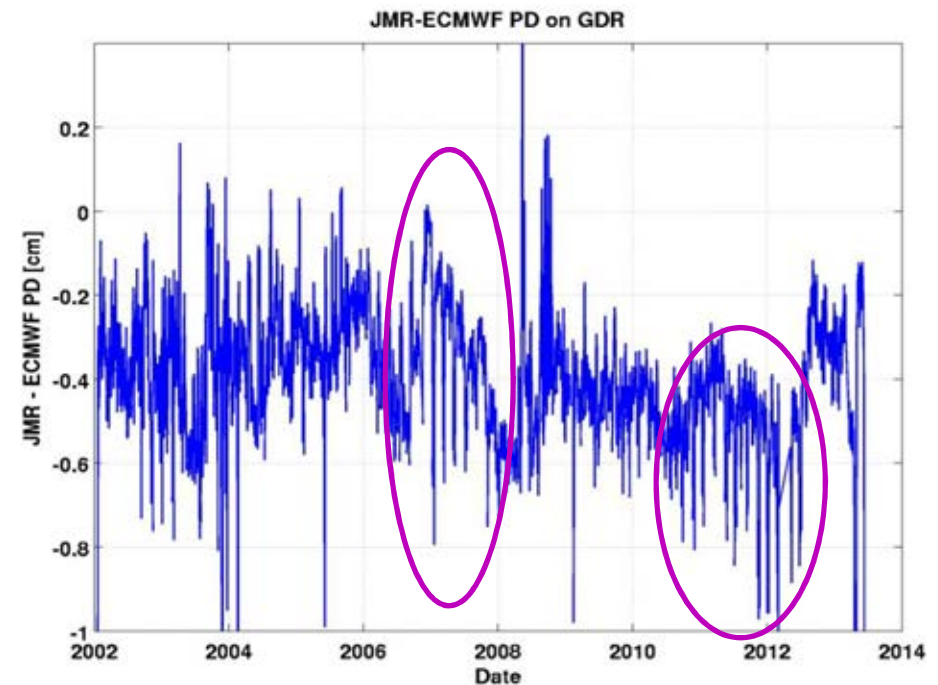
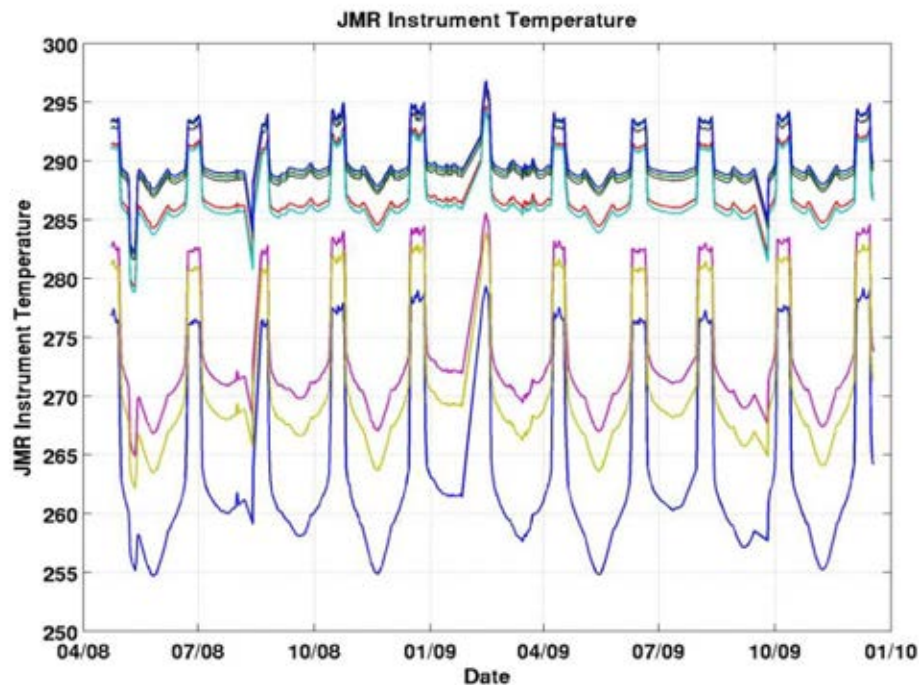
$$\Delta T_B(ch, t) = c_0(ch, t) + c_1(ch, t)TB(ch, t)_{uncorrected}$$

- Coefficients are derived by forcing agreement with the running average of the SSM/I FCDR biases over the ocean (cold end) and over the rainforest (warm end)



Instrument Temperature Correction

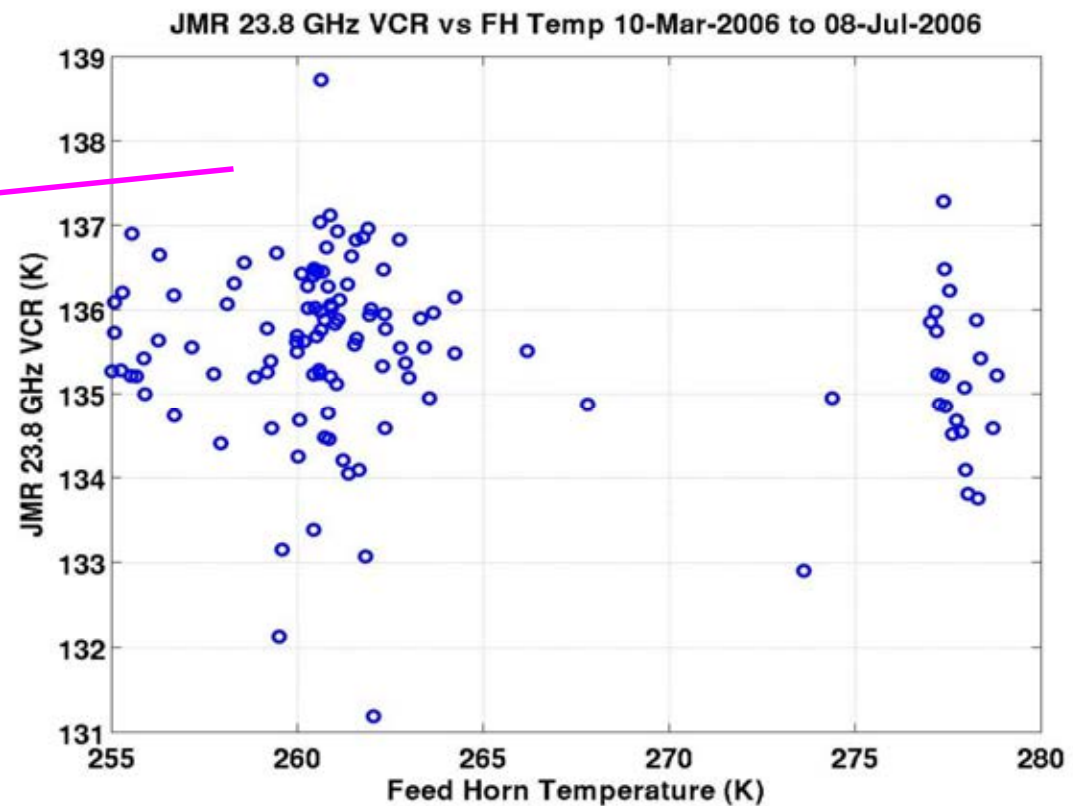
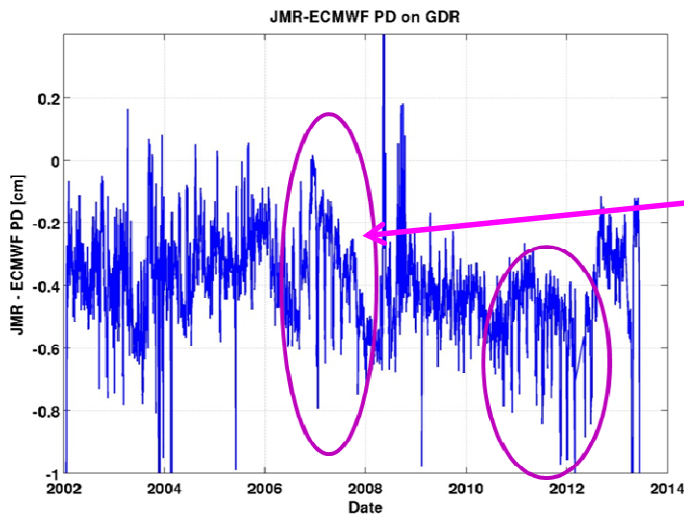
- “Yaw-state” dependence periodically resurfaces (creates 60-day signal)
- Results from instrument temperature dependency of calibration changing over time





Instrument Temperature Correction

- This effect can be typically removed by binning TB references as a function of instrument temperature and removing the slope
- Because the time period was short, and the temperature dependency was a variable with time, the TB comparisons were too noisy to use this approach



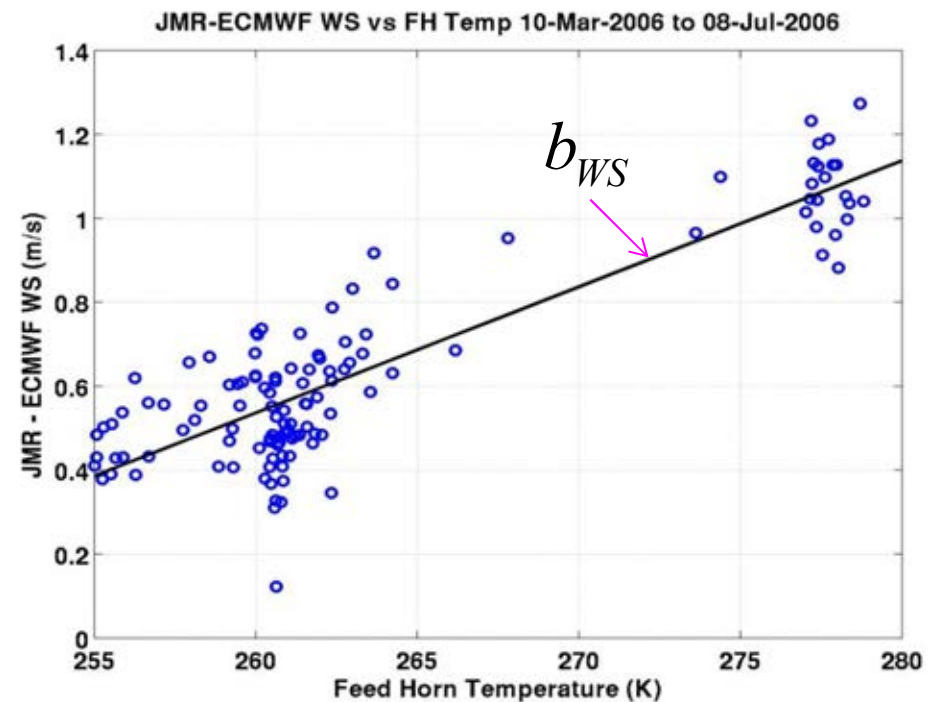
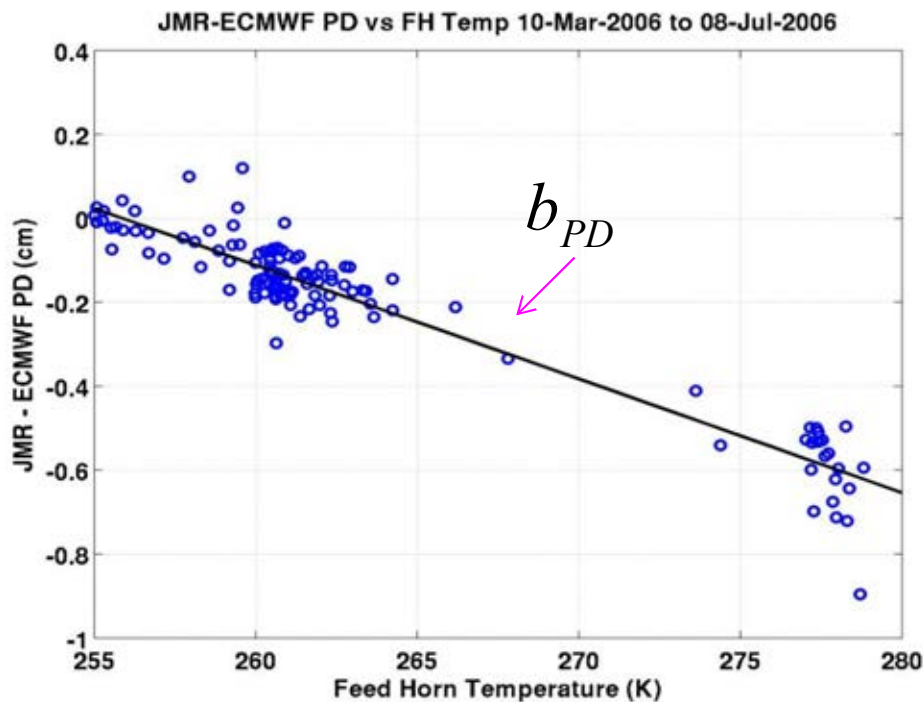


Instrument Temperature Correction

- Alternative approach was developed using both the path delay and wind speed comparisons to the model to determine TB instrument temperature dependency

$$\begin{bmatrix} b_{TB18} \\ b_{TB23} \end{bmatrix} = \begin{bmatrix} c_{18}^{PD} & c_{23}^{PD} \\ c_{18}^{WS} & c_{23}^{WS} \end{bmatrix}^{-1} \begin{bmatrix} b_{PD} \\ b_{WS} \end{bmatrix}$$

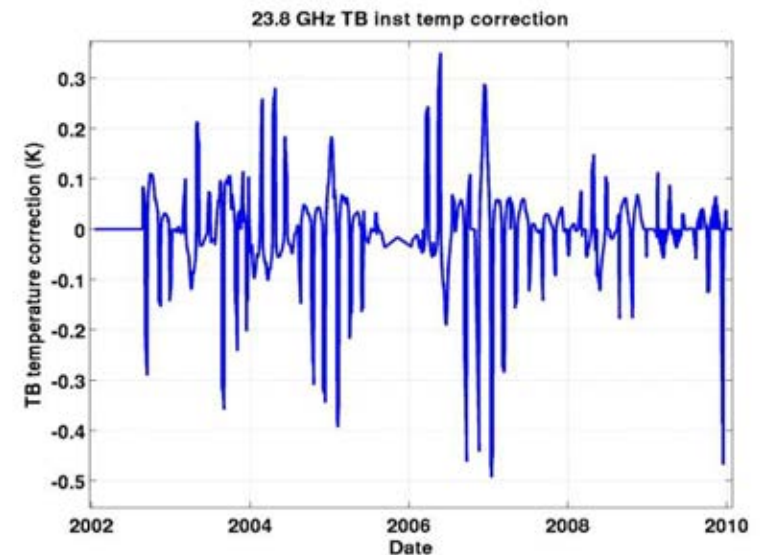
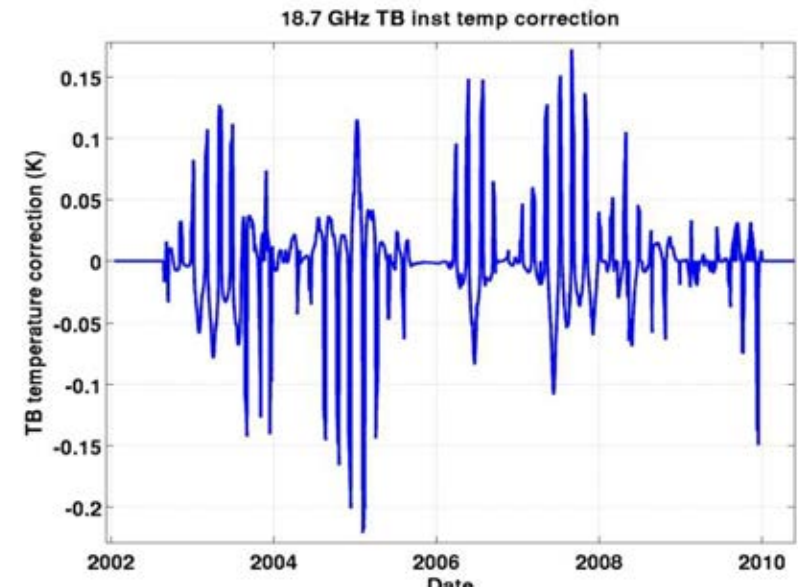
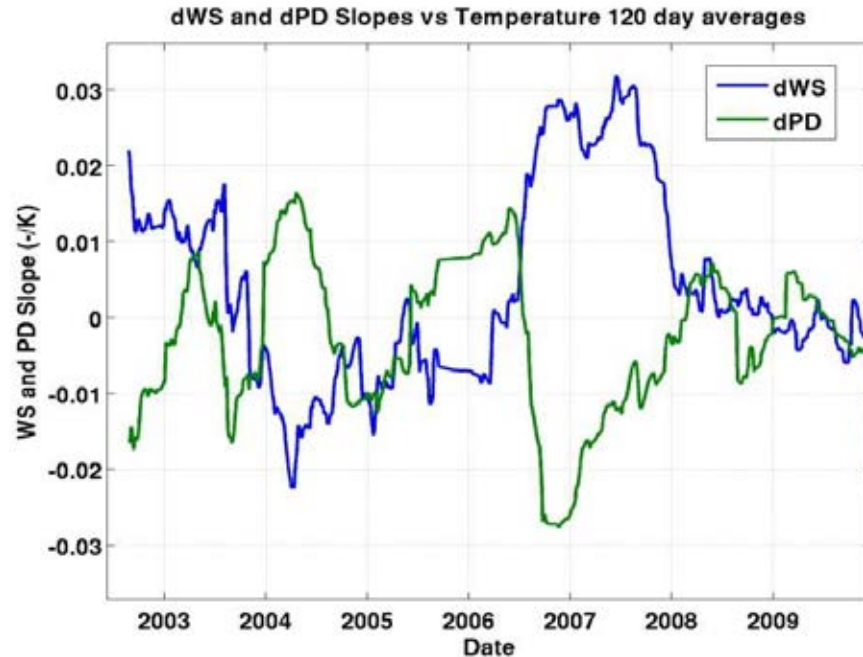
Coefficients are from linearized global retrieval algorithm





Instrument Temperature Correction

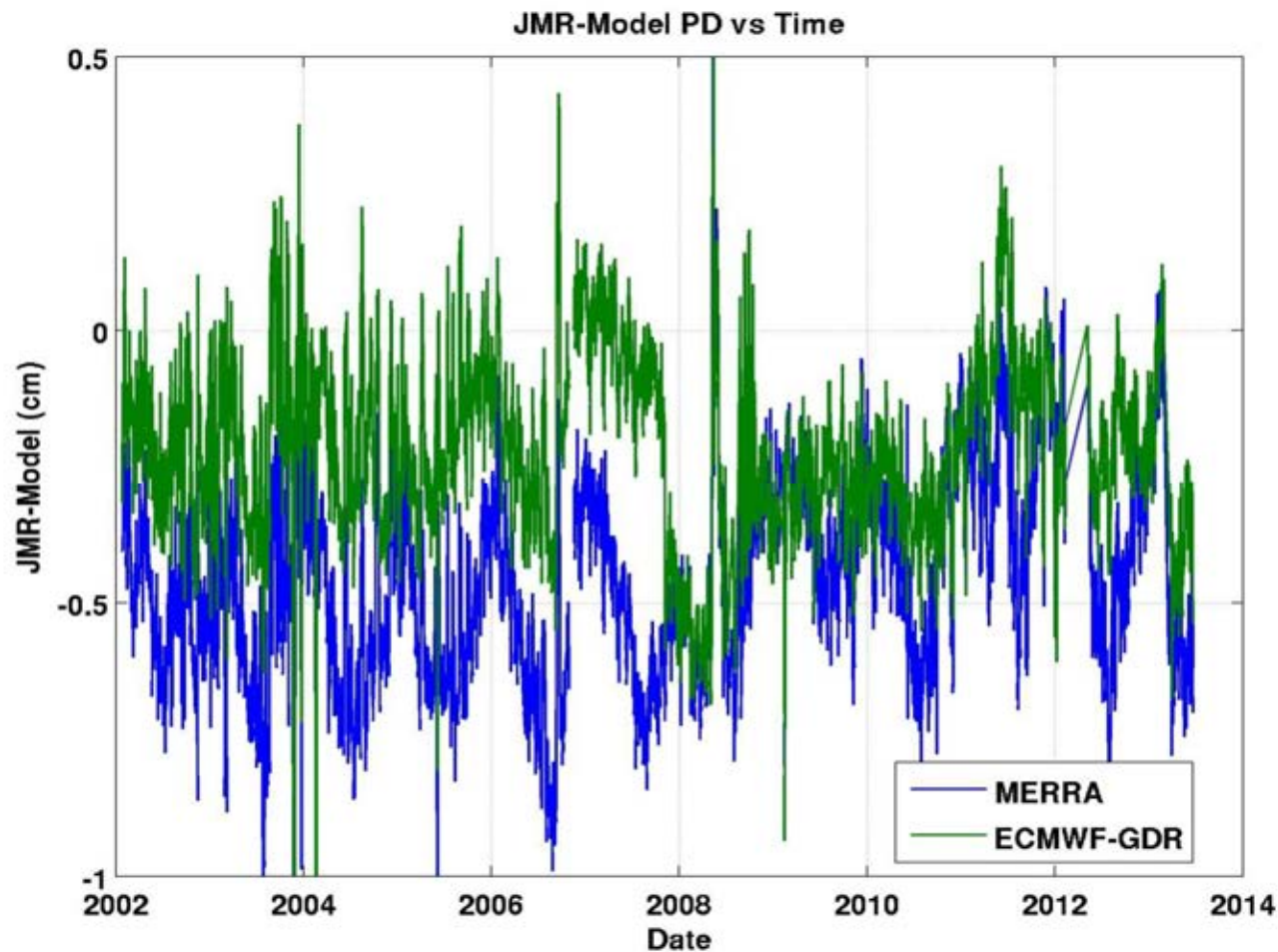
- Slopes computed using running 120-day window
- Applied to TB time series in addition to long term drift
 - $< 0.2\text{K}$ correction in 18.7 GHz channel
 - Up to 0.4K in 23.8 GHz channel





PD Validation

- PD compared to time series from ECMWF and MERRA
- Long term drift $< 1\text{ mm/decade}$ compared to these models



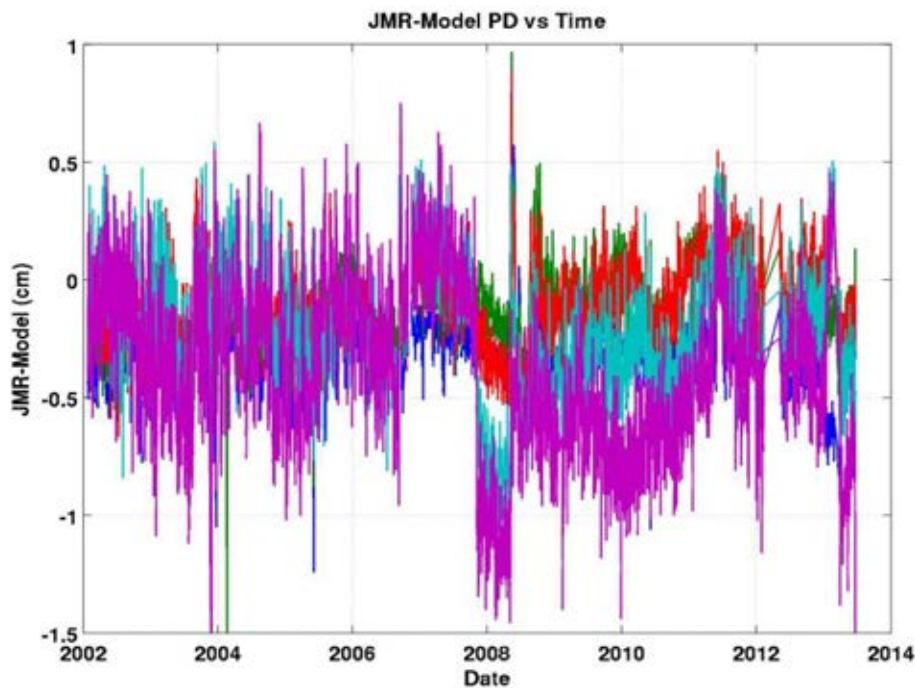
ECMWF-GDR
MERRA



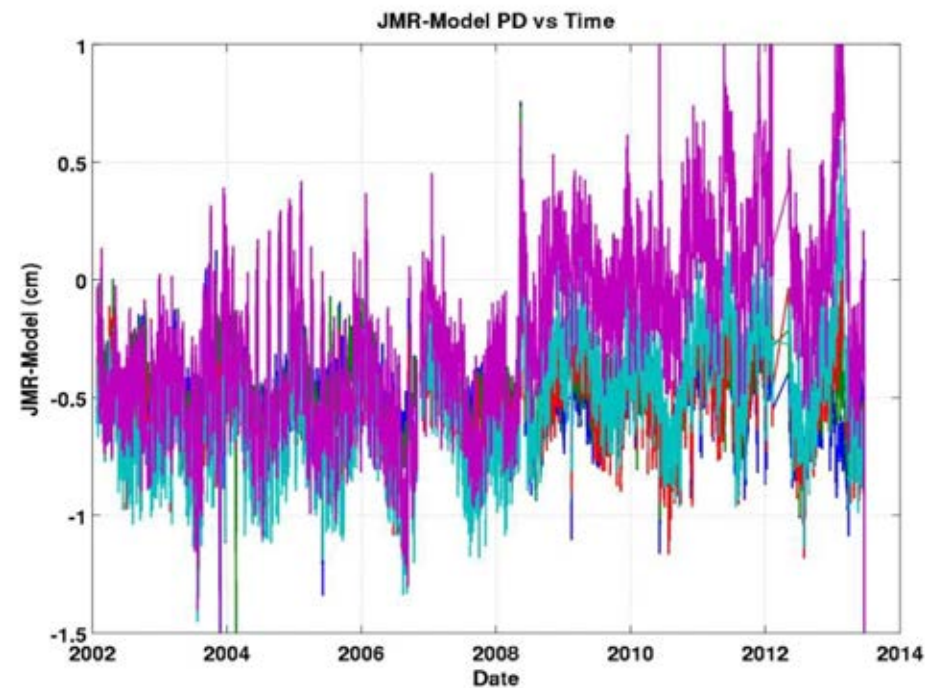
PD Validation Stratified

- PD compared to model for low, medium and high PD ranges to assess any geographically correlated drift
- No definitive drift over all PD ranges

ECMWF-GDR



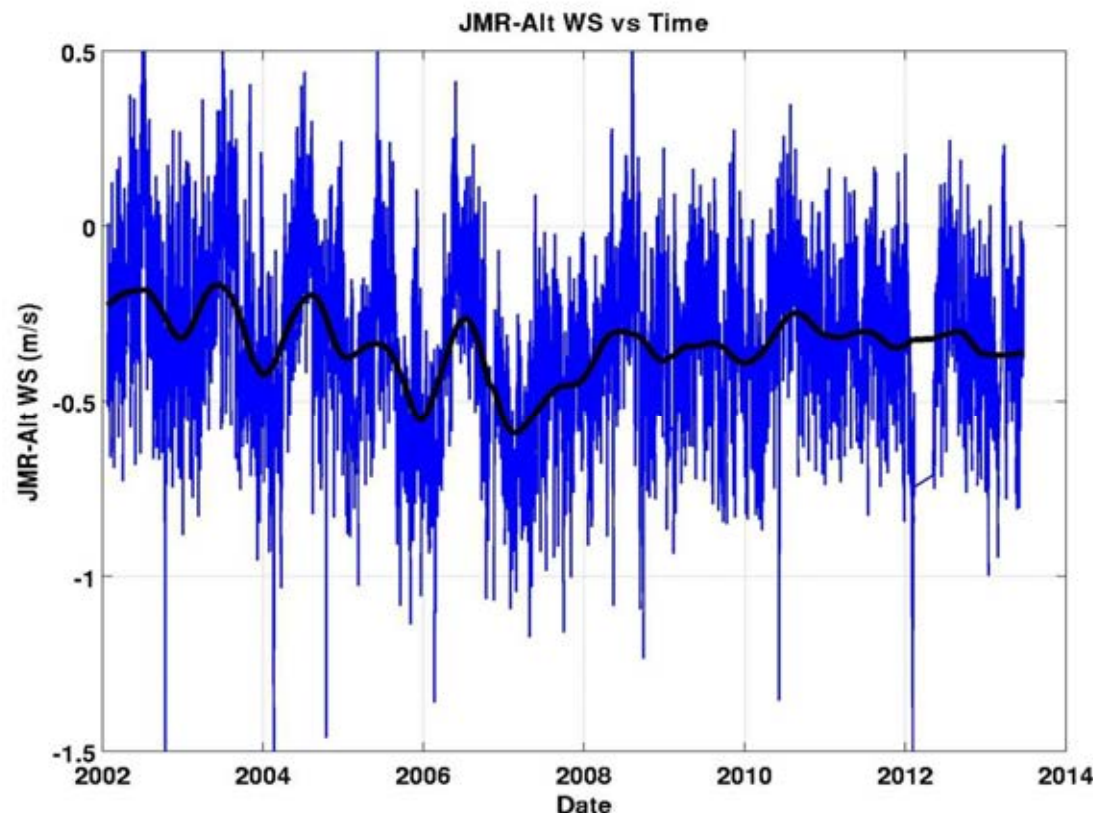
MERRA





Wind Speed Time Series

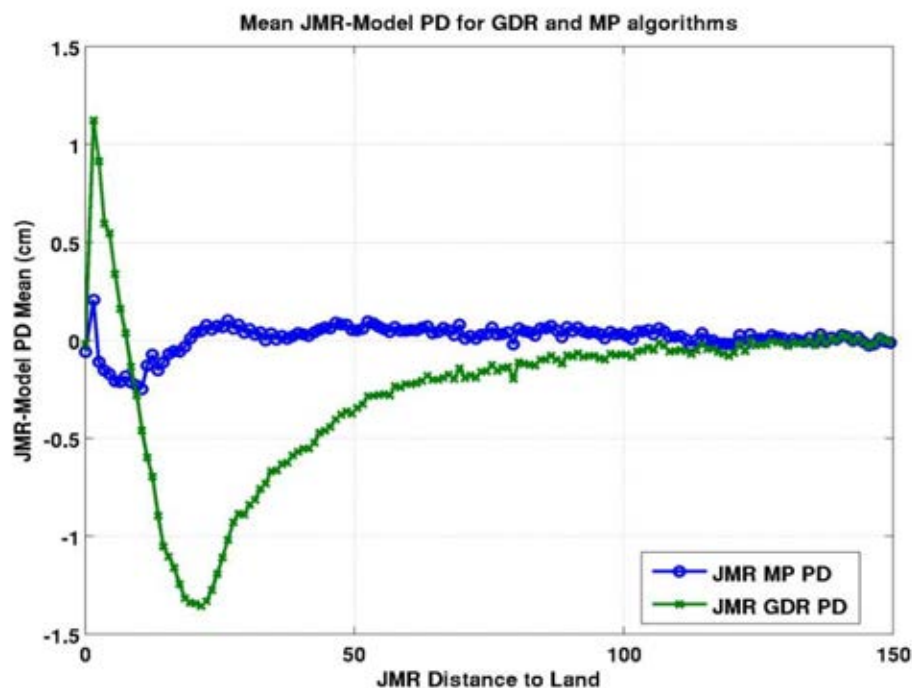
- Wind speed compared to altimeter vs time shows < 0.2 m/s drift over mission
- Independent comparison that is consistent with < 1 mm PD drift over mission



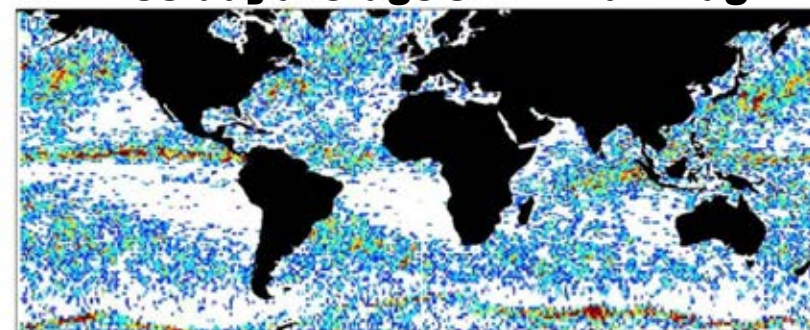


Algorithm Updates

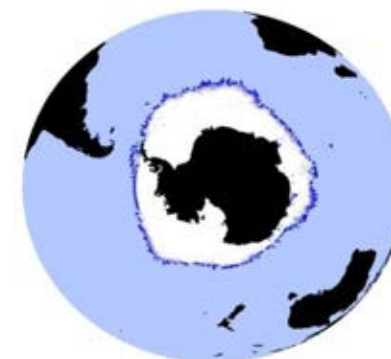
- JMR algorithms updated to Jason-2 AMR standards
 - All-weather sigma-0 attenuation correction algorithm
 - Consistent sea ice and rain flagging
 - Near land path delay retrieval algorithm



200-day average of AMR rain flag



Cycle 1-5 average of AMR sea ice flag





Summary



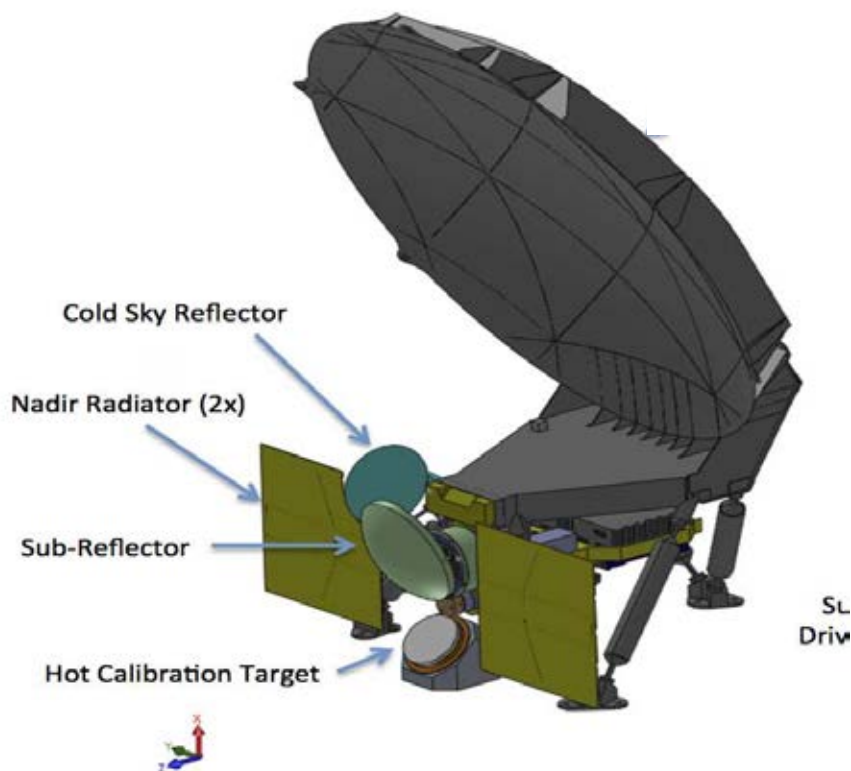
- JMR end-of-mission re-calibration effort is complete
 - Long term calibration constrained by inter-satellite calibration to the SSM/I FCDR and on-Earth references
 - Residual time variable yaw-state (60 day) dependencies removed
- Month-to-month calibration uncertainty about 0.2K (~2mm in PD)
 - 2 mm/yr uncertainty for any 1 year
 - < 1 mm/yr uncertainty for time spans greater than 2 years
 - << 1 mm/yr for mission
- Algorithms updated to Jason-2 GDR-D standard
- **The need for this type of *a posteriori* calibration will be reduced for Jason-3 (cold sky calibration) and eliminated for Jason-CS (complete 2-point external calibration)**



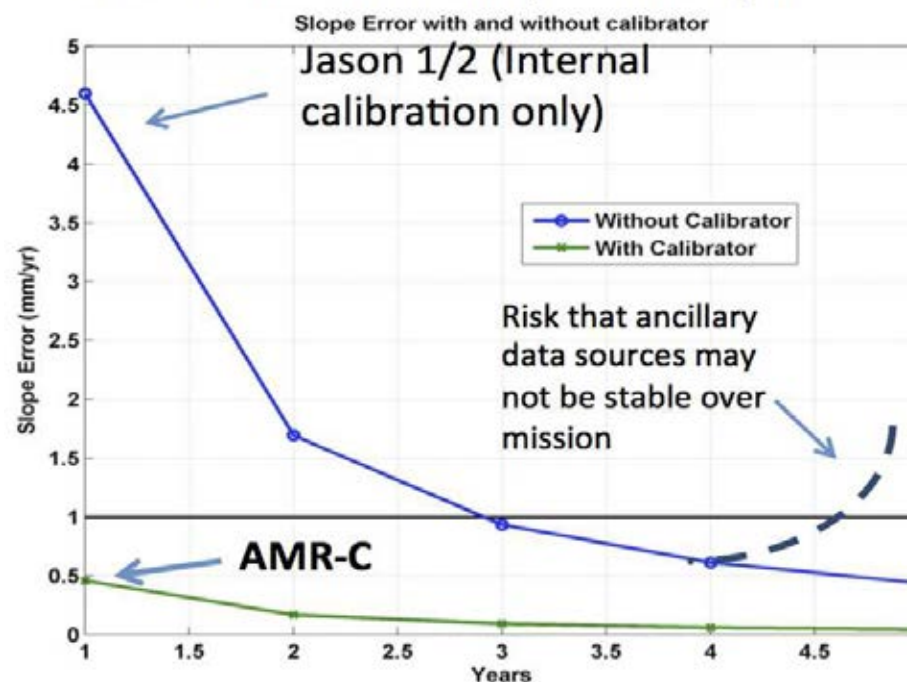
Backup



- AMR-C concept includes secondary reflector to perform end-to-end calibration using stable blackbody calibration targets similar to SSM/I, AMSR-E, AMSU, etc.
- Wet PD long term stability estimated to be better than 0.3mm for any one year period and eliminates reliance on ancillary data sources for calibration



Wet PD Drift Uncertainty vs Time Span





Overview



- Current status of the JMR calibration
- End-of-mission recalibration approach
- Initial comparison with the SSMI FCDR



Jason-1 Jason Microwave Radiometer (JMR) 2002 - 2013



- **Jason-1 JMR maintained same measurement requirements as TMR**
 - 1.2 cm RMS error for PD measurement
 - No requirement for long term stability
- **JMR used noise diodes for calibration to eliminate the need for a cold sky horn**
 - First spaceborne radiometer to use NDs
 - Paved way for Aquarius, SMOS, SMAP and of course AMR
 - JMR ND implementation and thermal environment presents calibration challenges
- **Maintained same antenna design as TMR with partial blockage from struts**
 - Results in larger sidelobes (creates geographically correlated errors)



End-of-Mission Calibration Plan

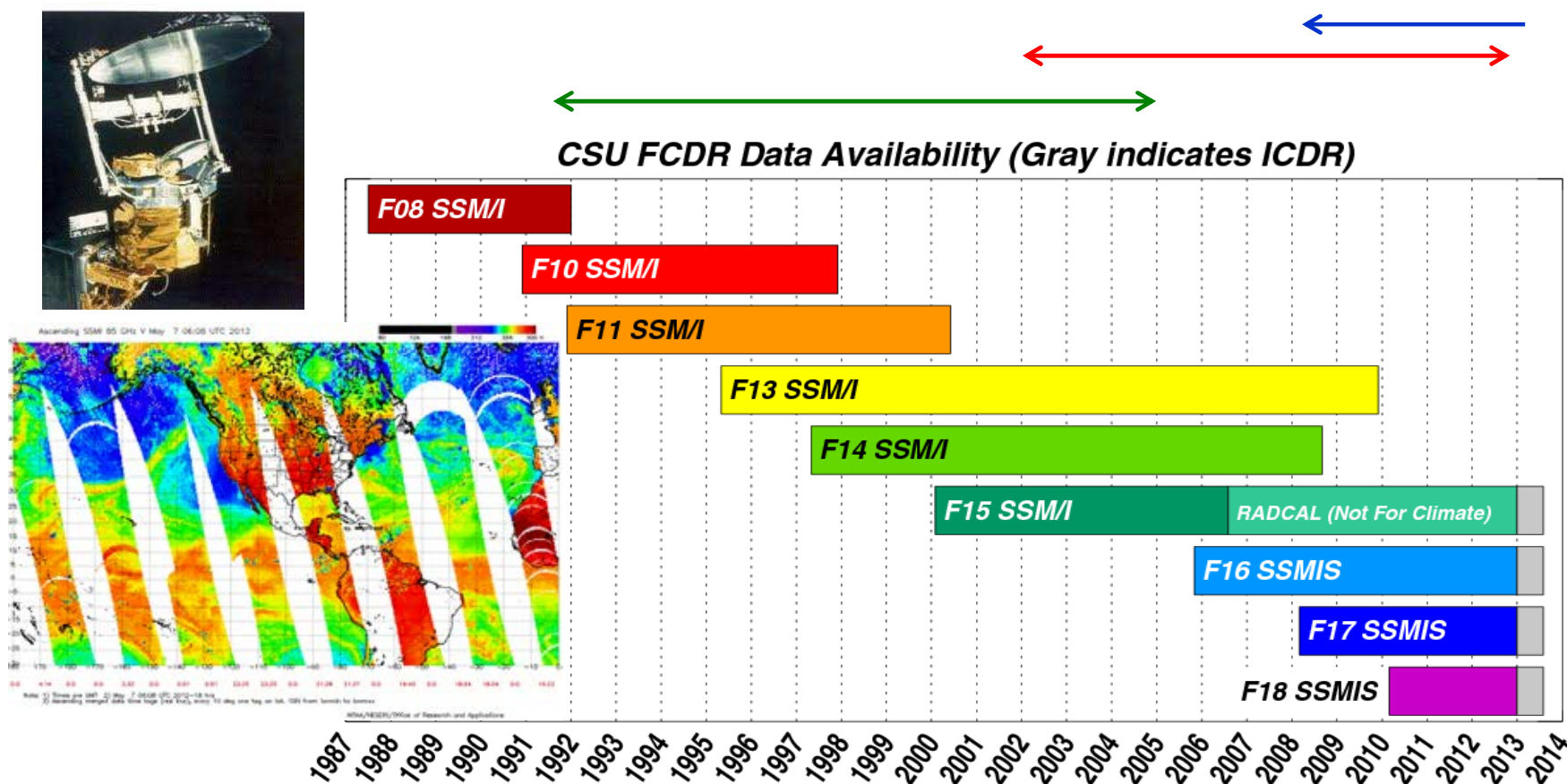


- Previous calibration relied upon on-Earth hot and cold T_b references
 - Vicarious Cold Reference (*Ruf, 2000, TGARS*)
 - Amazon pseudo-blackbody regions (*Brown and Ruf, 2005, JTECH*)
 - On-orbit references sensitive to climate variability; require corrections; risk of aliasing geophysical signals
- Complementary inter-sensor TB calibration approach recently developed and applied to AMR (Brown, 2012, TGRS)
 - Uses polynomial regression to transfer one sensor's measurement to another
 - Requires stability of other systems
 - Presents independent means to monitor the long term TB calibration
- Compare geophysical retrievals to in-situ measurements, models and other sensors
 - Dependent on long term stability of other sensors/models
 - Need to use re-analysis products from models to ensure a consistent long term record
- Demonstrated consistency between independent methods ensures a “climate-quality” long term calibration
 - the agreement, or lack thereof, between the different references provides a means to assess the uncertainty of the long term calibration



SSM/I FCDR

- The SSM/I series of radiometers have operated since 1987, spanning the Topex/Jason altimeter record
- A newly released SSM/I Fundamental Climate Data Record is a reprocessed well inter-calibrated record of brightness temperature ideal for inter-satellite calibration with JMR
- SSMI F13, F14 and F17 used in this analysis

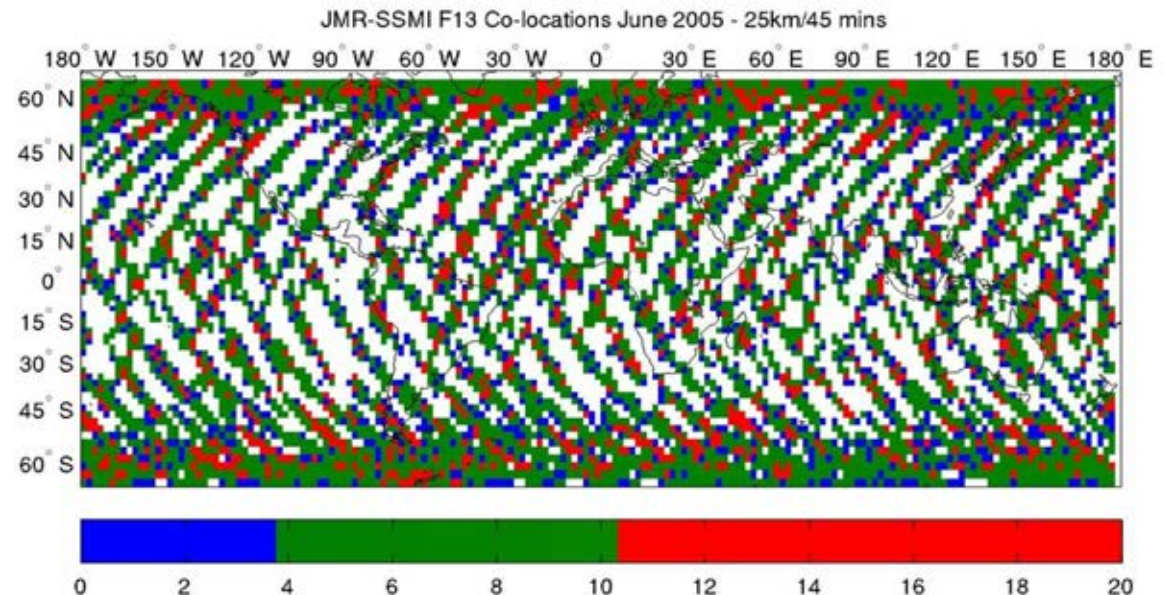
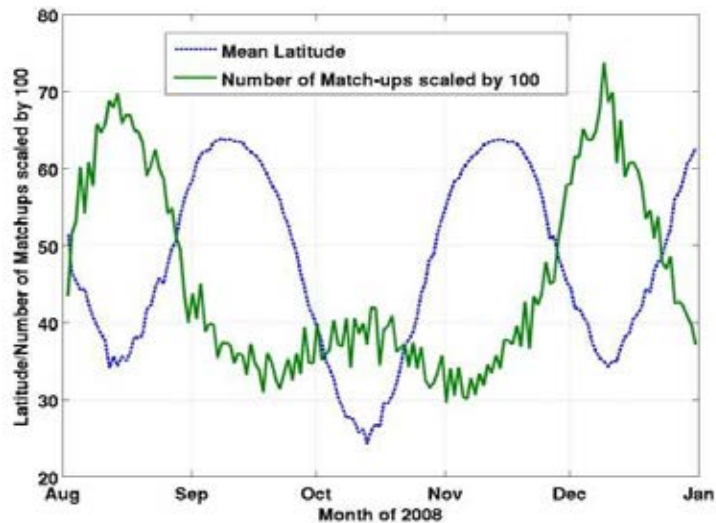


TMR
JMR
AMR



Match-up Process

- A database of co-locations is generated by finding JMR and SSM/I observations that occur within 25 km and 45 minutes of each other
- The match-ups cluster between high and low latitudes as a function of time





JMR Equivalent TBs from SSMI



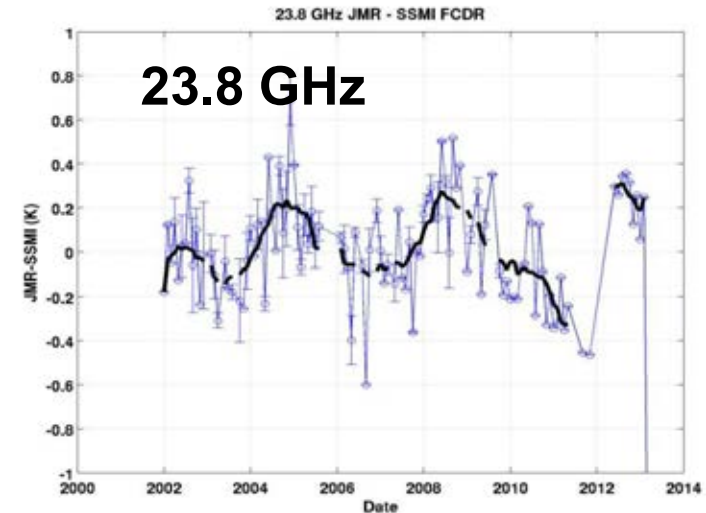
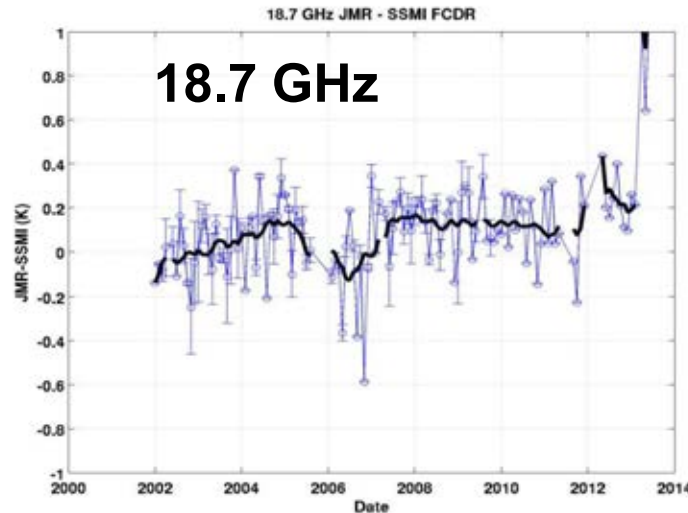
- Polynomial regression used to transfer SSM/I TBs to JMR equivalent TBs
 - Uses 19, 22 and 37 GHz TBs from SSMI
- Coefficients derived from AMR used in this analysis
 - Ensures consistent cross-calibration between AMR and JMR

$$T_{B_ocean}^{AMR} = c_0 + c_1 T_B^{19V} + c_2 T_B^{19H} + c_3 T_B^{22/24V} + c_4 \left(T_B^{22/24V} \right)^2 + c_5 T_B^{37V} + c_6 T_B^{37H}$$

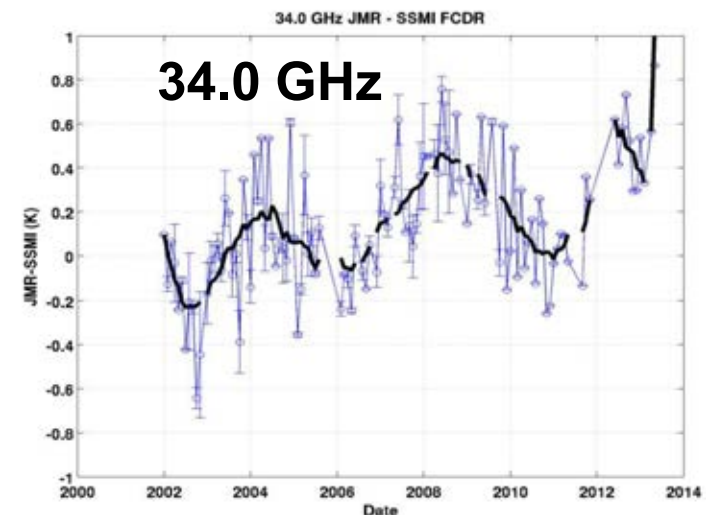
- JMR-SSMI biases correlated with latitude are removed to ensure no signals due to the sampling are aliased into the trend
 - Biases with latitude computed using the entire record
- JMR-SSMI TB differences greater than 8K (5-sigma) were removed from the match-up database



JMR-SSMI TBs



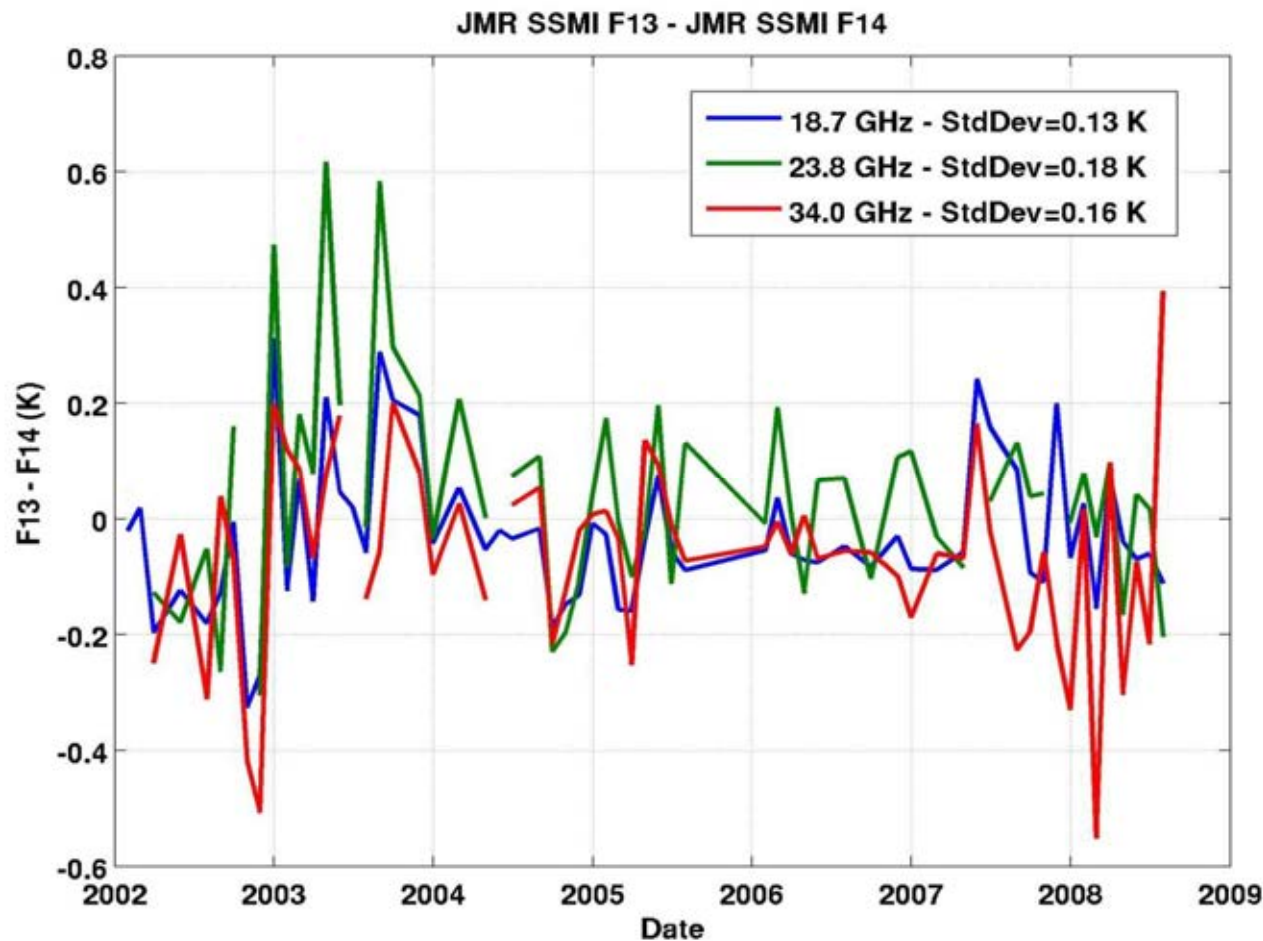
- Computed monthly averages of the JMR – SSMI TB bias for each channel
- Overall excellent consistency between SSMI F13 and F14
- **Small, but statistically significant, residual instability evident in all channels (< 0.5 K)**





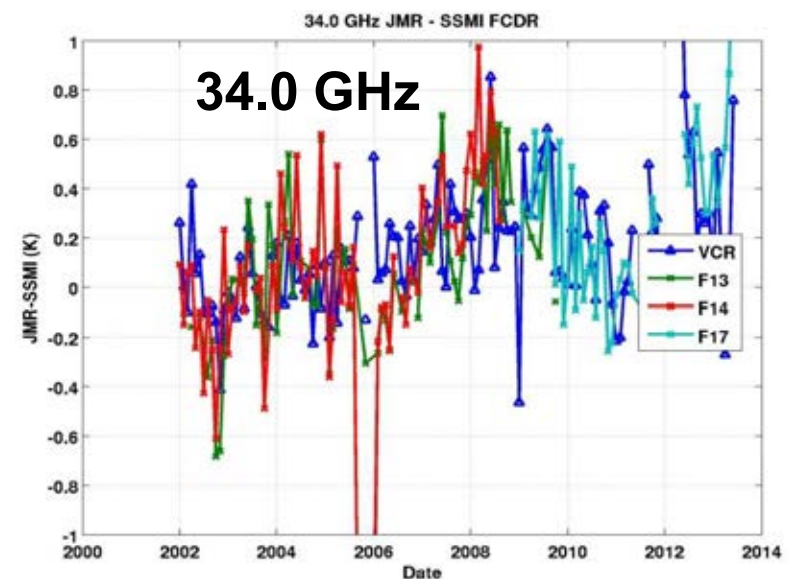
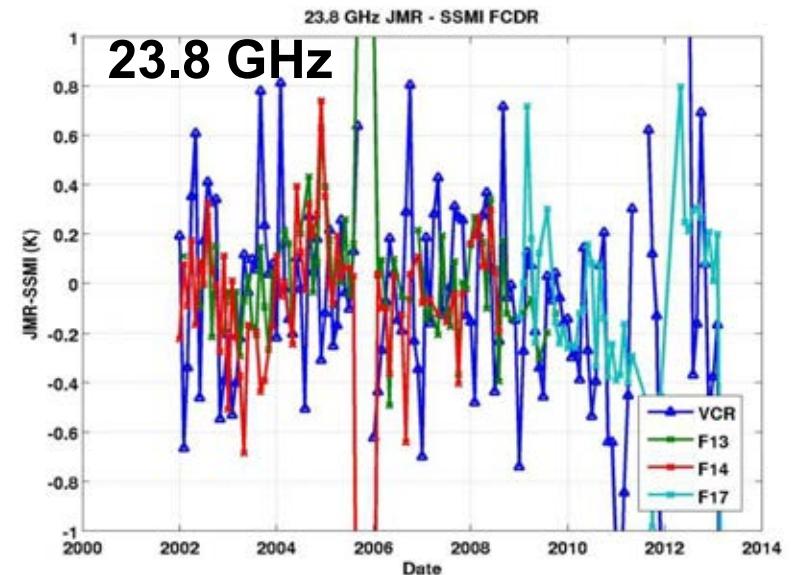
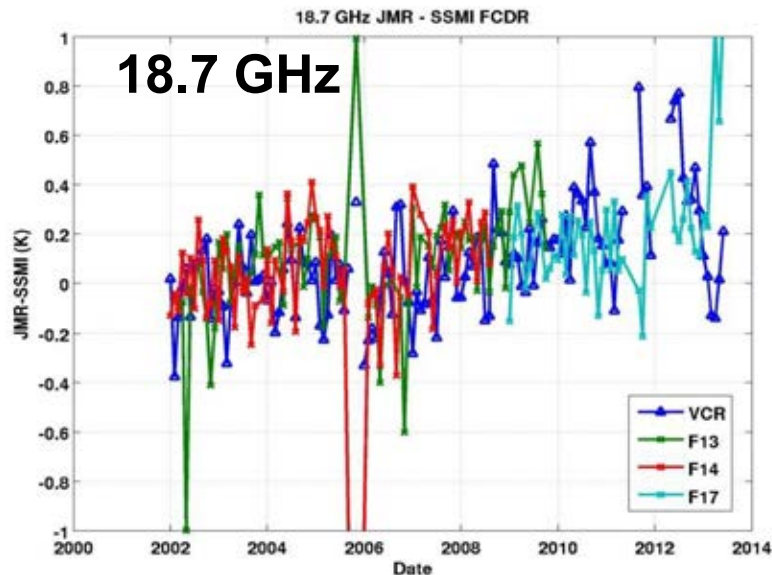
Monthly Consistency

- $< 0.2\text{K}$ standard deviation of monthly JMR biases computed from SSMI F13 and F14 with no discernible trend





Comparison with Ocean Reference



- Dark blue line shows monthly averaged vicarious cold reference with biases from SSMI
- Consistency observed between these independent references increasing confidence in the long term trends