



Impact of satellite yaw attitude regime on in-flight calibration of low-Earth orbiter GPS antenna phase center

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Motivation and Background

- Antenna calibration is critical for high-precision GNSS-based precise orbit determination (POD).
 - Simple Phase Center Offset (PCO), or 3-D vector to best-fit sphere is one approach.
 - Phase Center Variations (PCVs) as function of elevation and azimuth proves to be better.
- In-flight calibration of Jason-series has benefited from yaw-steering.
 - Improves coverage and sampling, especially to decouple along-track PCO from clock.
- In-flight calibration of Sentinel-6 A/B and SWOT poses challenges, as both will be flying in fixed yaw only.
- Sentinel-3 A/B satellites already flying in fixed-yaw mode.
 - Can be used to develop and test approaches for Sentinel-6 and SWOT.



Estimation of Jason-3 PCO

Yaw-Steering vs Yaw-Fixed Phases

- Estimates shown as **function of maximum daily yaw angle variations**

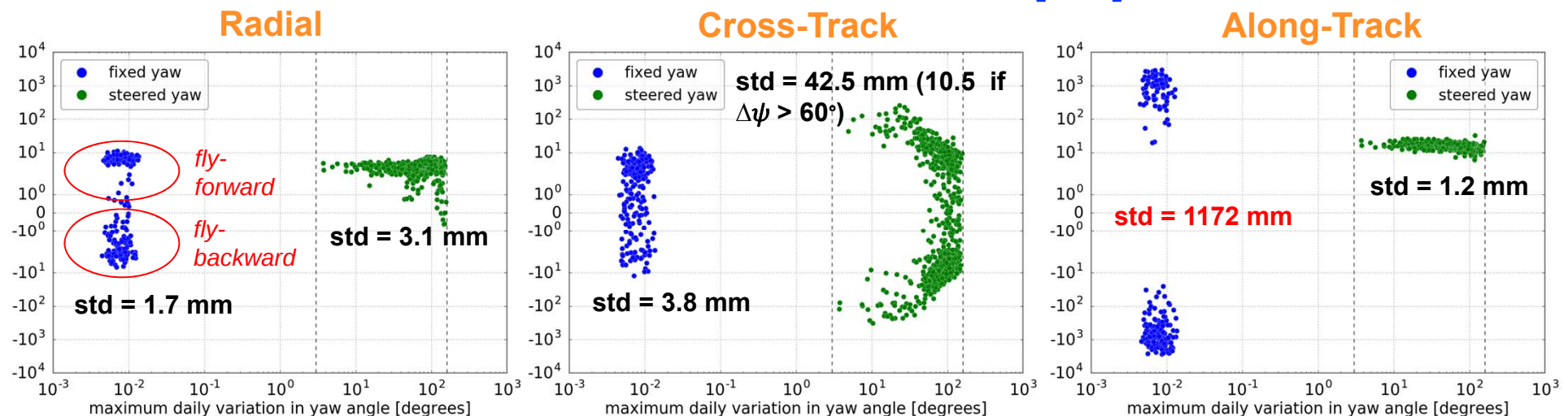
Yaw-Steering case: 787 days included

- PCO well-determined in all 3 directions (provided $\max \Delta\psi > 60^\circ$ in cross-track)

Yaw-Fixed case: 242 days included (AMR calibration days excluded)

- Along-track poorly observable**; cross-track and radial components well determined
- Unexplained **fly-forward/fly-backward discrepancy** in radial direction (also visible to lesser extent in cross-track direction in steered yaw)

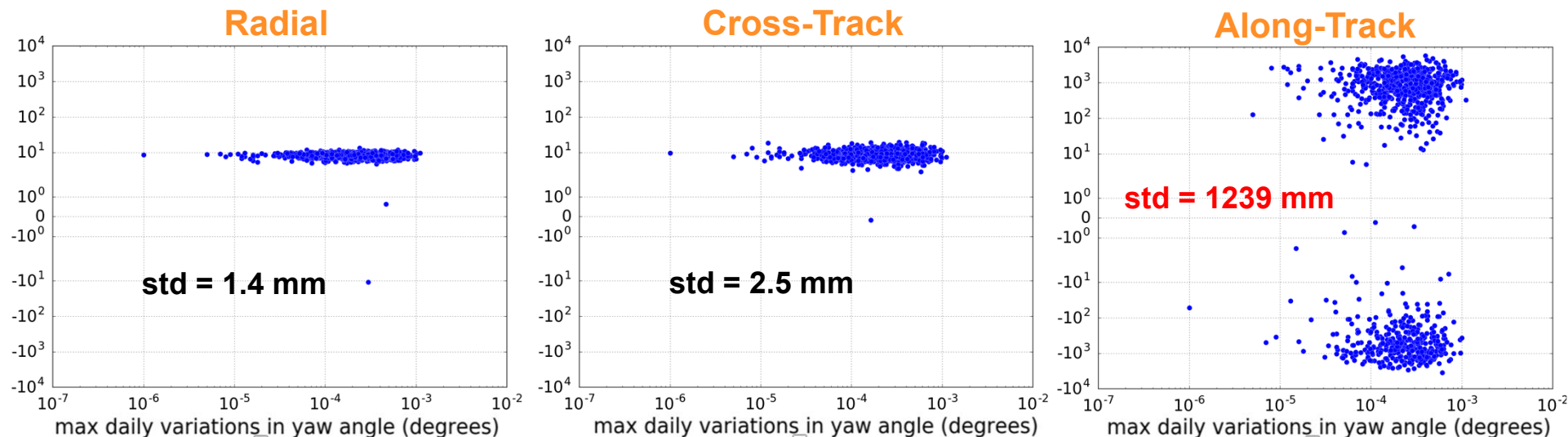
Estimate of Phase Center Offset [mm]



Estimation of Sentinel-3A PCO (Sun-synchronous orbit, fixed-yaw attitude law)

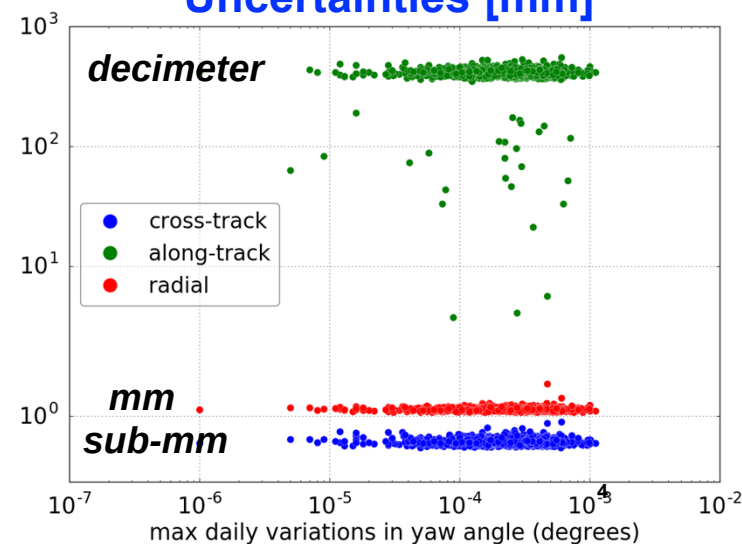


Estimates of Phase Center Offset [mm]



- PCO best determined in orbit transverse and radial directions (based on scatter in estimates and formal errors).
- Along-track component poorly determined.
- **Consistent with observations made for Jason-3 fixed-yaw attitude regime**

Uncertainties [mm]



Overview of Antenna Calibrations Discussed



Calibration type	Description
PCO	Pre-launch estimate of phase center offset from mission project documents
PRELAUNCH	Pre-launch calibration of GPS antennas. • Jason-3: available • Sentinel-3 A/B: apply pre-launch calibration of the Sentinel-6 RO-POD antenna
INFLIGHT	Sum total of prelaunch and correction computed using in-flight data. • Jason-3: 1310 days (Feb 13, 2016 to Sep 14., 2019) • Sentinel-3A: 1316 days (Feb 23, 2016 to Sep 30, 2019) • Sentinel-3B: 517 days (May 1, 2018 to Sep 30 2019) • Sentinel-3 A/B has along-track PCO correction constrained to 0

Mitigation of Unobservability by Means of Constraint

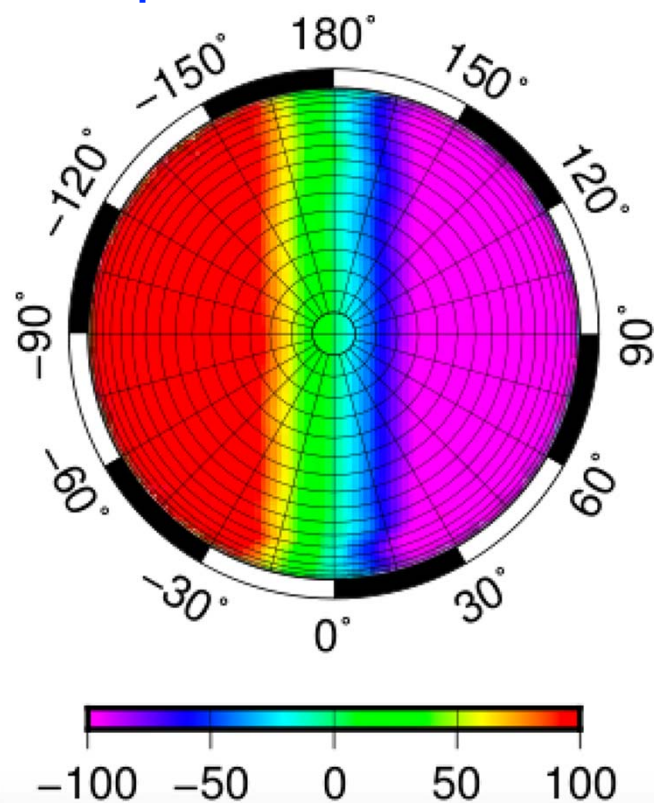
Sentinel-3A example



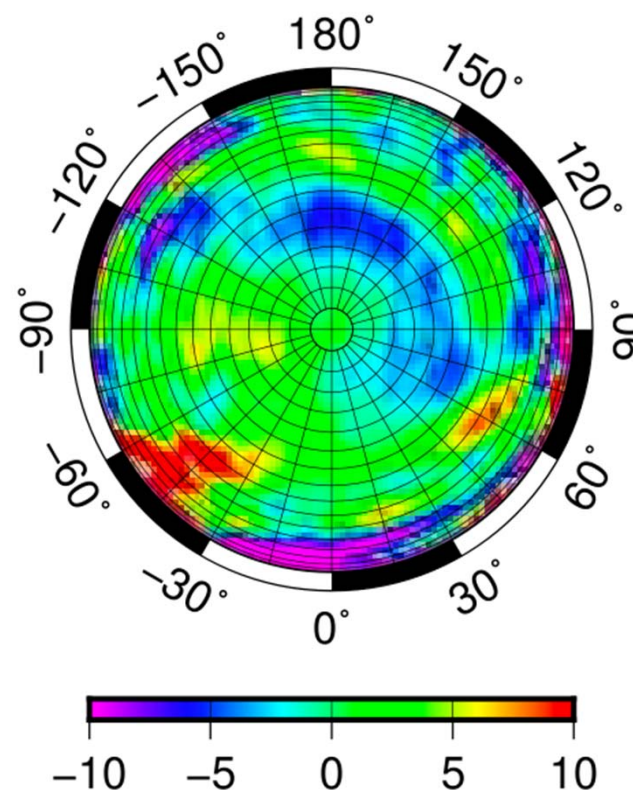
- In-Flight calibration of S3A antenna without constraints results with large (~ 300 mm) estimated PCO in along-track direction.

Even when satellite is flying in fixed-yaw, calibration correction can be achieved.

Unconstrained correction to
prelaunch calibration



Correction to prelaunch calibration after
constraining PCO in along-track direction



mm



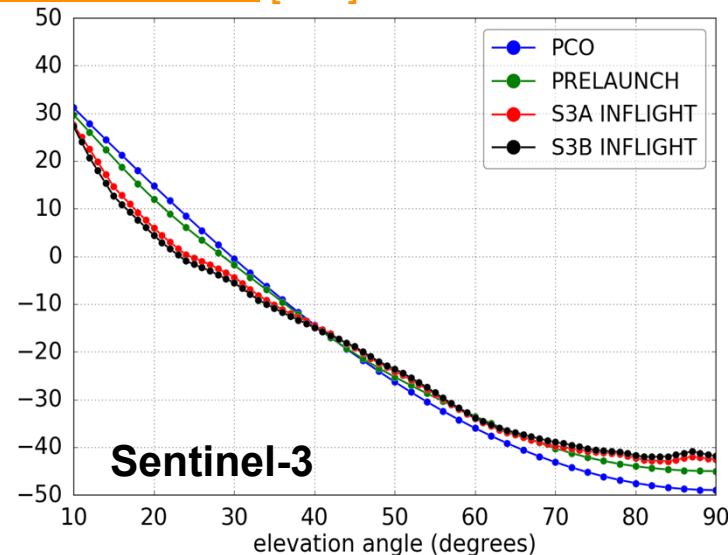
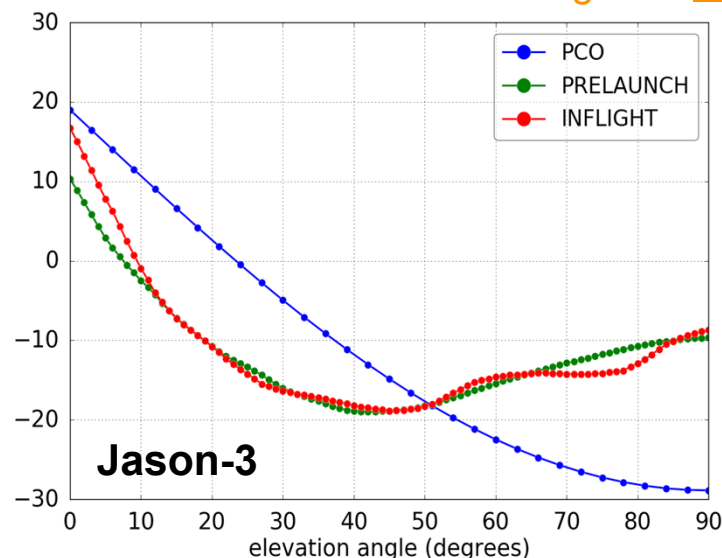
Antenna Calibration Corrections

- Prelaunch calibrations contain PCO and PCV information.
→ Add value relative to prelaunch PCO

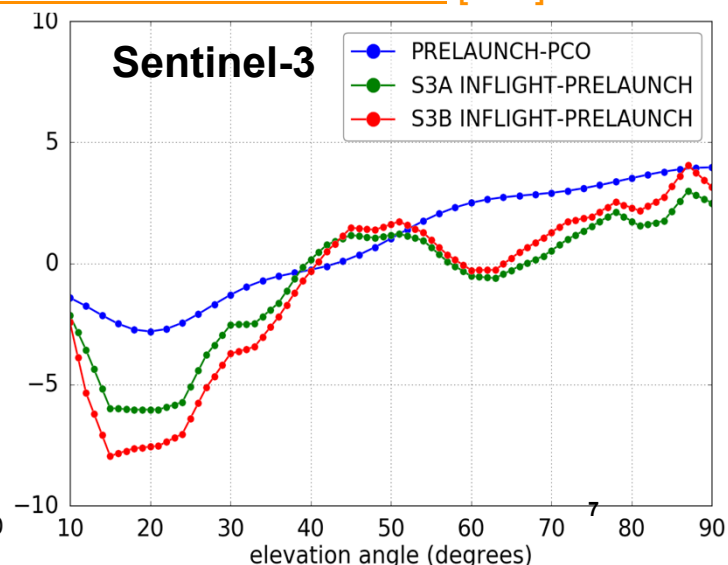
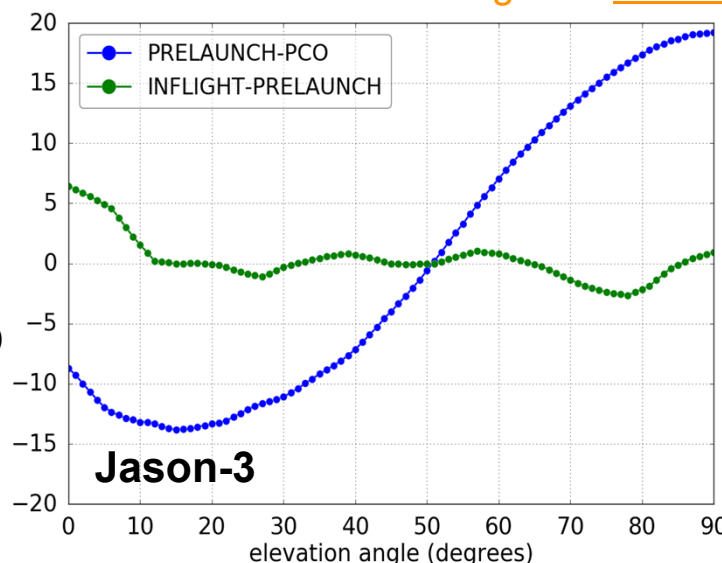
- Significant departure of pre-launch calibration from prelaunch PCO for JA3

- Seemingly small corrections (e.g. estimated from in-flight data) can dramatically impact quality of LEO POD solutions.

Azimuth-averages of CALIBRATIONS [mm]



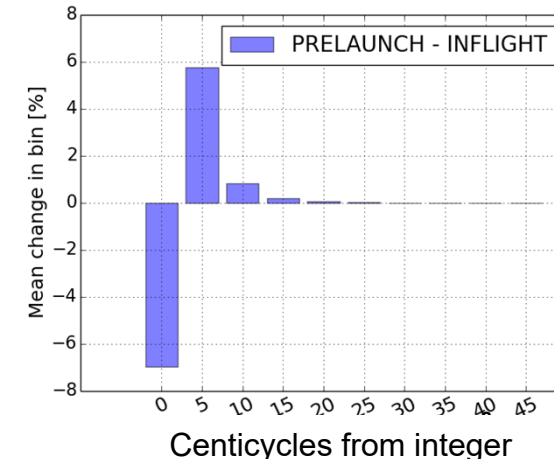
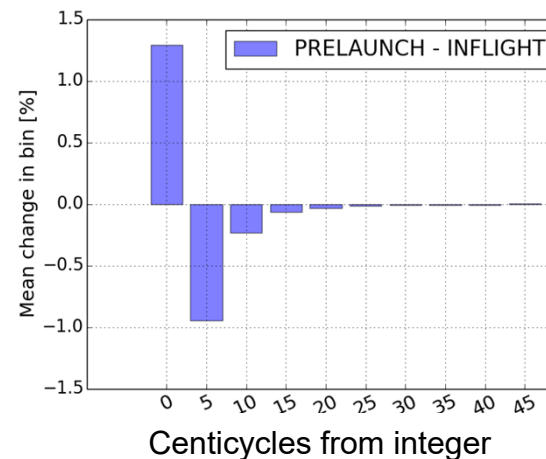
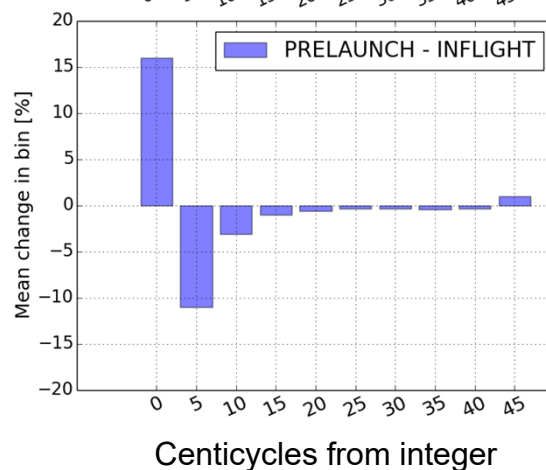
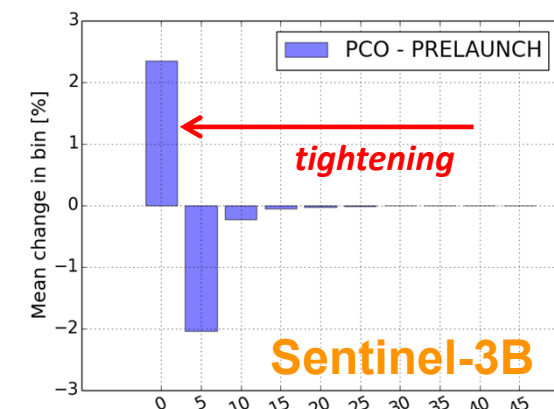
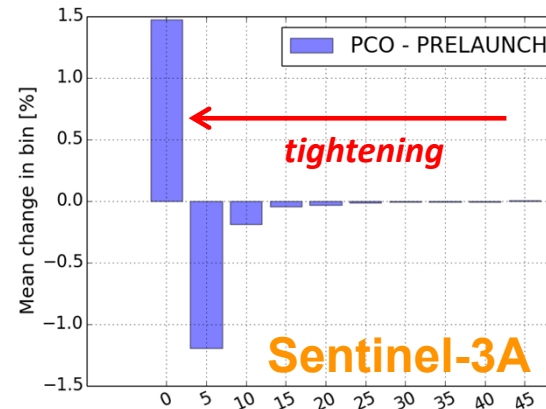
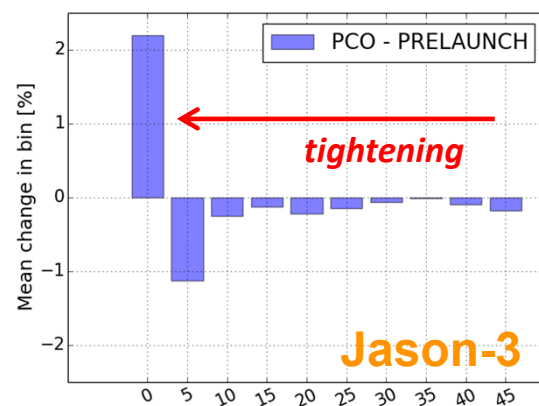
Azimuth-averages of CALIBRATION DIFFERENCES [mm]





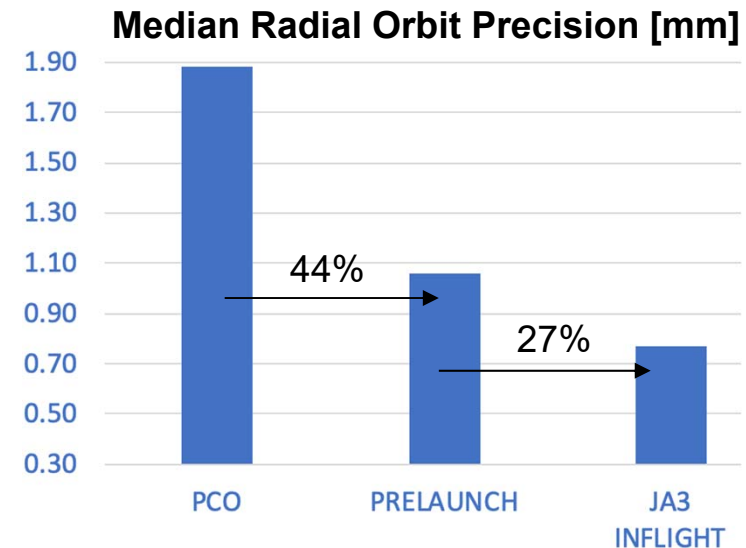
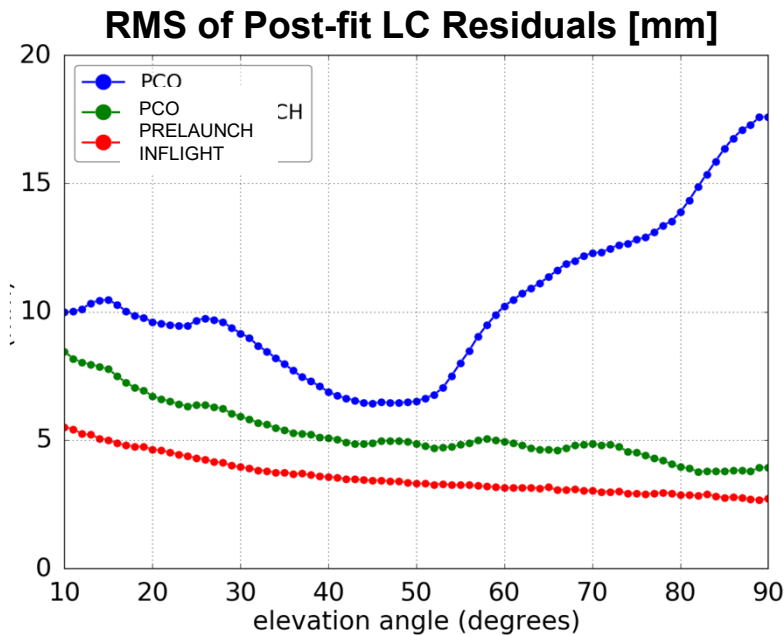
Measurement Model Improvement

- Improvement in **resolution of phase ambiguities** = **better measurement modeling**
- Overall tightening of the histograms closer to integer for solutions
 - For all 3 satellites when **using prelaunch calibration relative to PCO model**.
 - Additional improvement when **using inflight vs. prelaunch**: significantly larger for JA3, equal for S3A, marginal for S3B

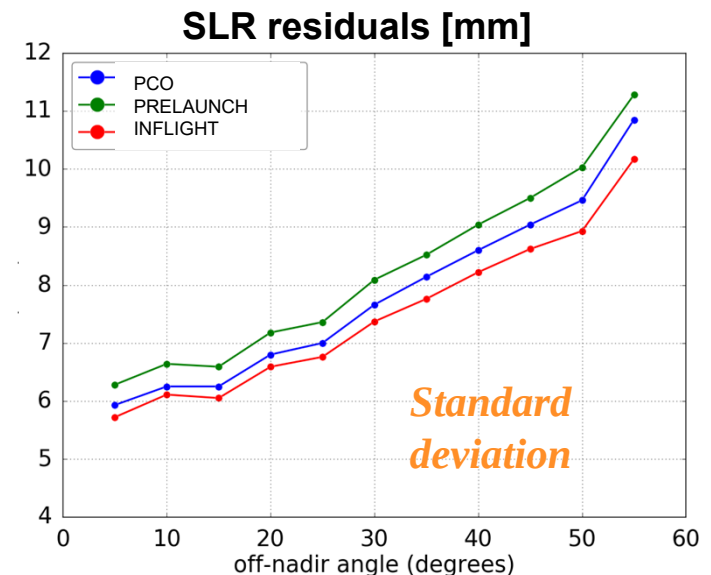




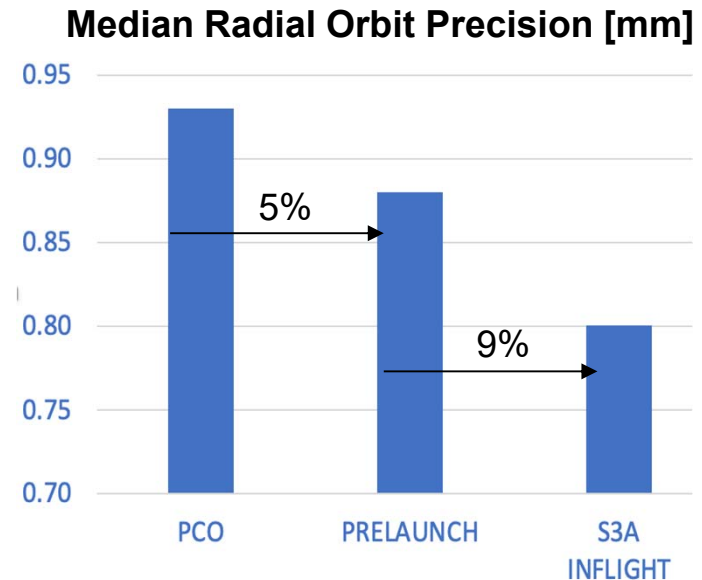
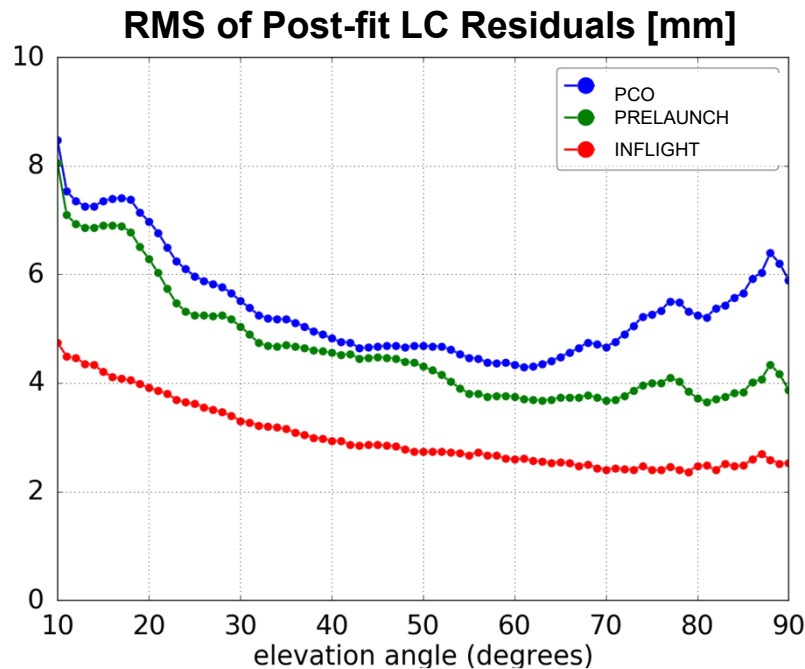
POD Performance Assessment: Jason-3



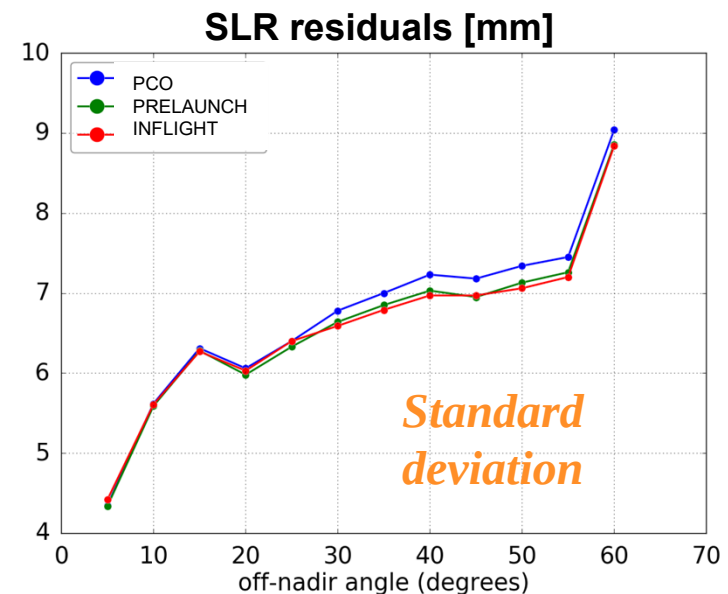
- use of prelaunch or inflight calibration yields better fit at all elevation angles
- dramatic improvement of data fit for elevations $> 50^\circ$
- radial orbit precision gradually improves when using prelaunch and corrected prelaunch calibrations
- SLR residuals show orbit radial accuracy:
 - improves when using inflight calibration
 - worsens when using prelaunch calibration



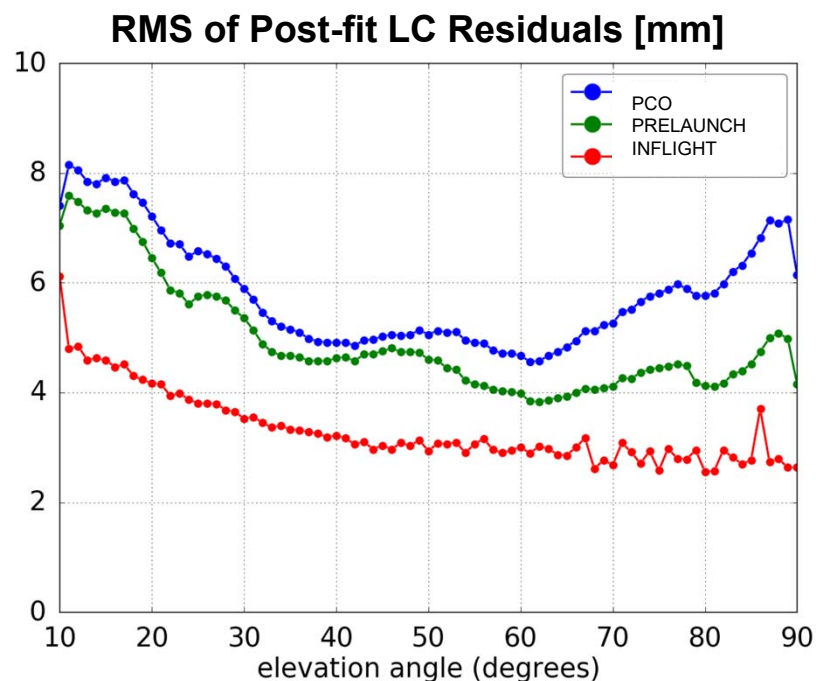
POD Performance Assessment: Sentinel-3A



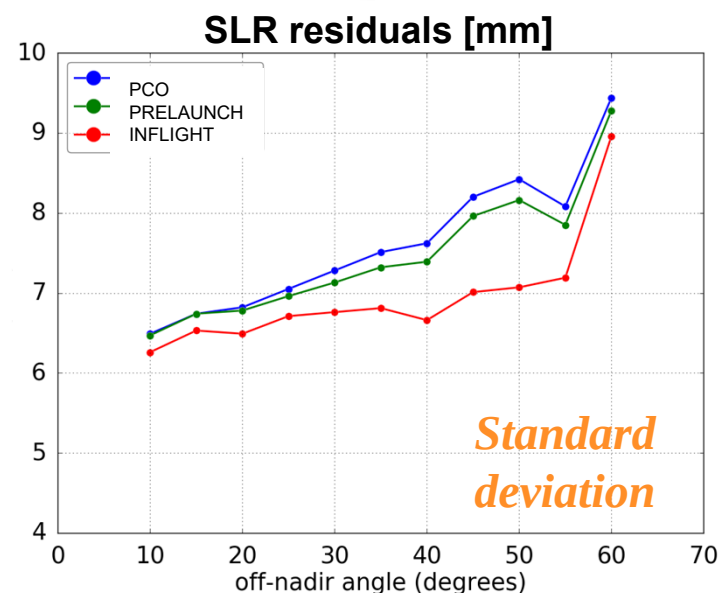
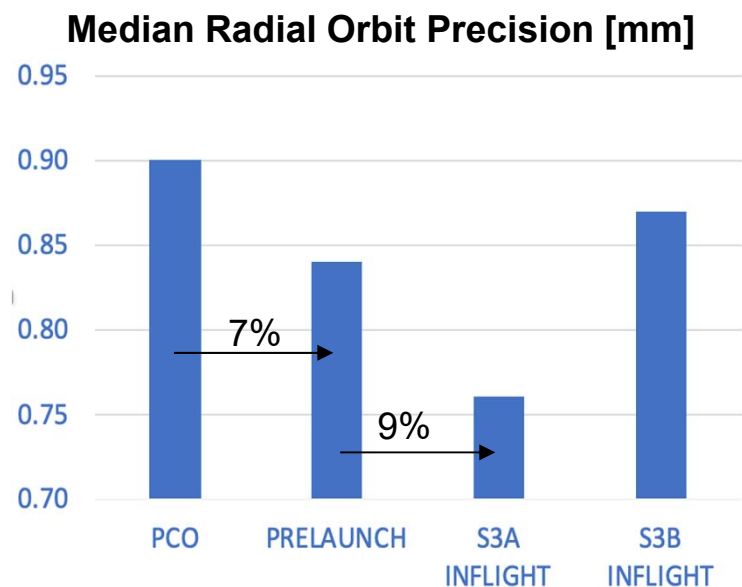
- Improved performance seen for all 3 metrics:
 - when using prelaunch calibration relative to PCO model
 - when applying corrections estimated from in-flight data to prelaunch calibration
- Similar to JA3, impact on data fit of using prelaunch over PCO increases for elev. $> 50^\circ$



POD Performance Assessment: Sentinel-3B



- Impact of in-flight correction on orbit accuracy is largest at higher off-nadir angles (lower elevation angles).
- S3B orbit precision better when applying S3A inflight calibration than when applying S3B inflight calibration.



Conclusion



- **Recommend use of full antenna calibration (PCO+PCV) over use of PCO vector only**
 - Demonstrated benefit of using prelaunch calibration over simple PCO model,
 - Shown added benefit of applying corrections estimated from in-flight data to prelaunch calibration
- Challenges associated with poor observability of PCO vector in satellite's direction of motion when flying in fixed-yaw can be mitigated in 2 ways:
 - use **prelaunch** antenna calibration,
 - **constrain along-track component of PCO** to prelaunch calibration value when estimating correction to a priori antenna calibration

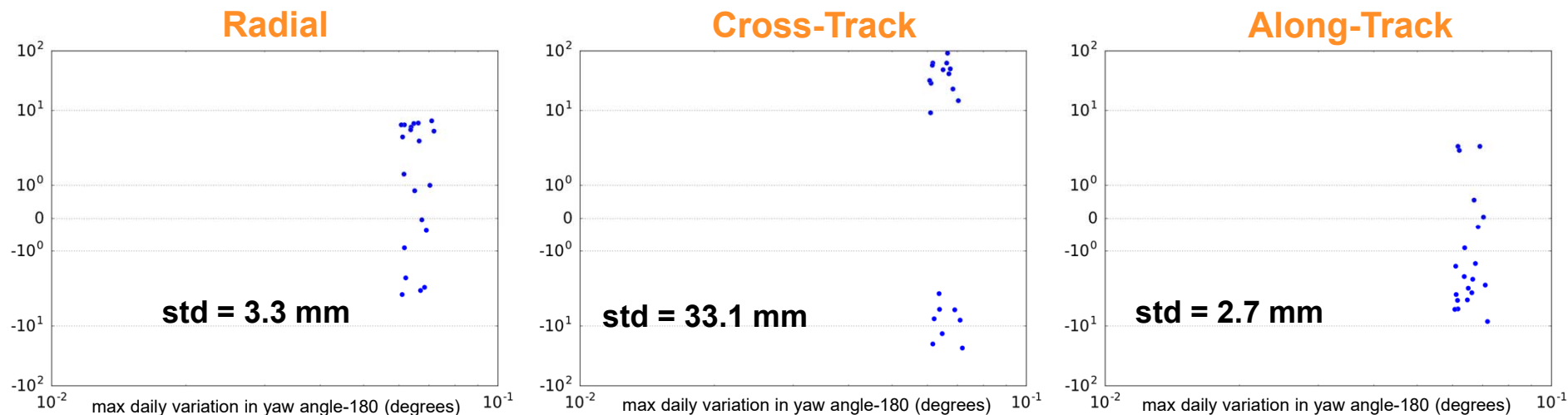


Backup Slides

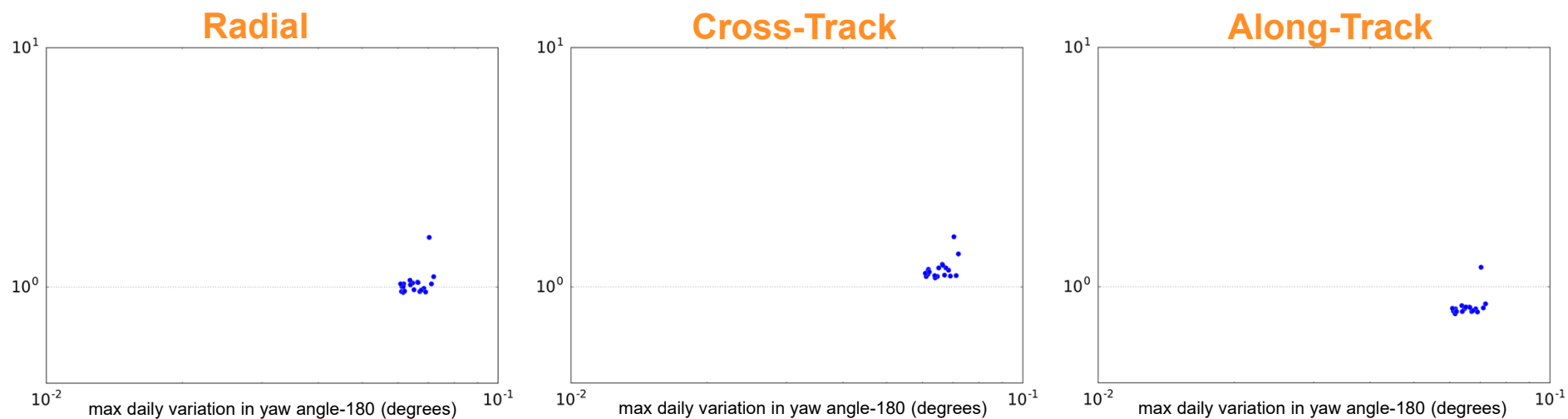


Yaw Flip Events

Estimate of Phase Center Offset [mm]



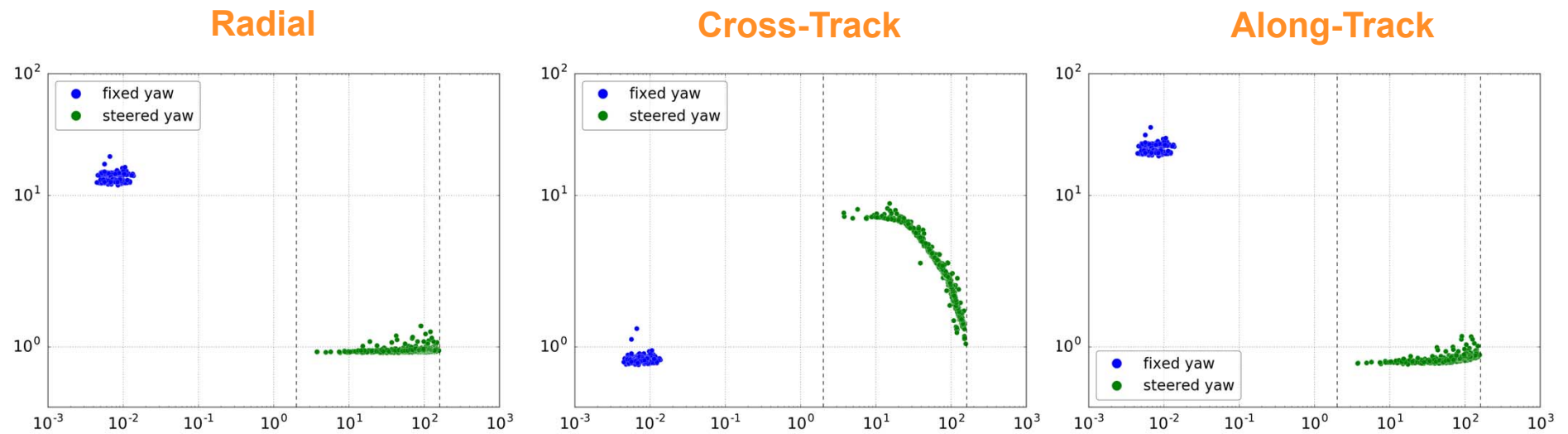
Formal Error of Phase Center Offset Estimates [mm]



Jason-3 Formal Errors Yaw-Fixed vs Yaw Steering



Formal Errors of Phase Center Offset Estimates [mm]

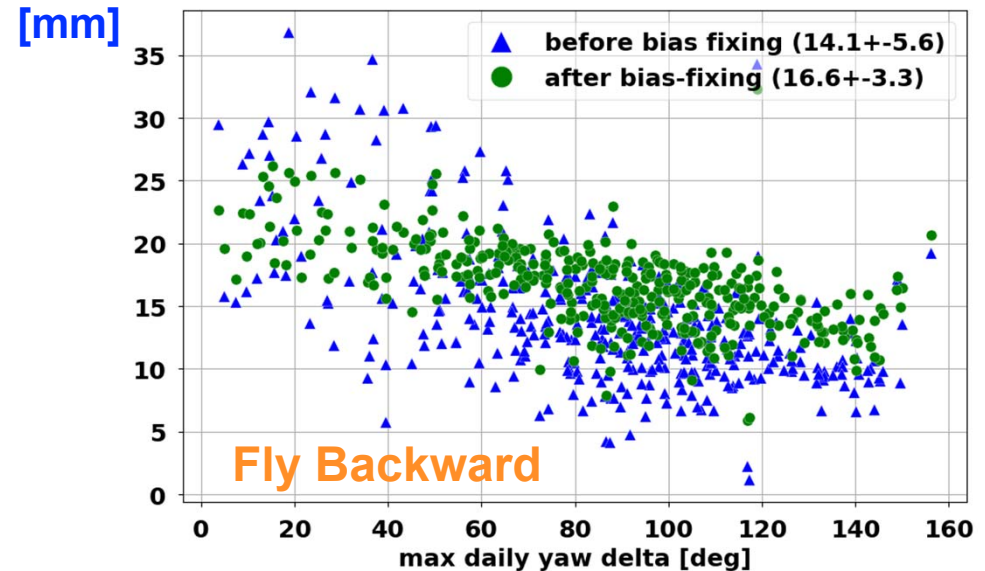
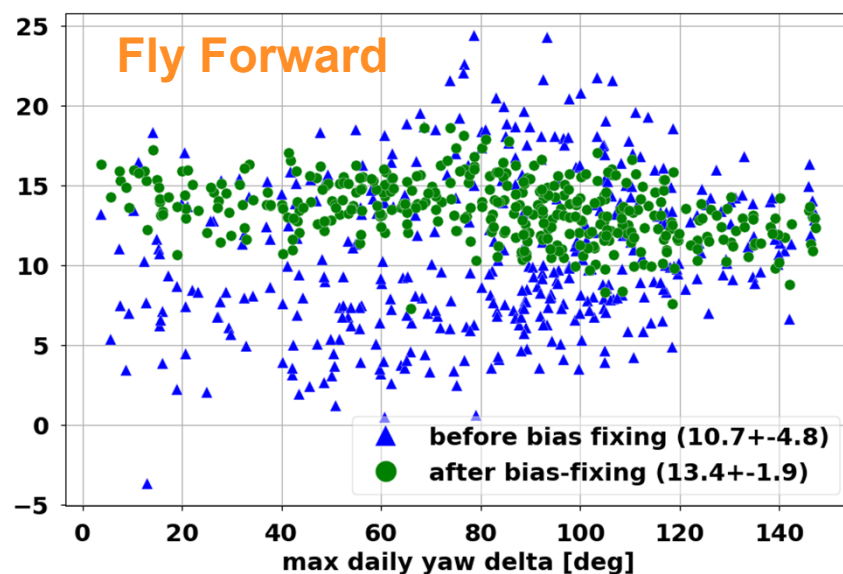


Impact of Ambiguity Resolution on PCO Determination



- Bias fixing reduces the scatter in the PCO estimates, esp. along-track
- Formal errors are reduced in all 3 directions after ambiguities are resolved.

Estimates of Phase Center Offset in Along-Track Direction during Steered Yaw Phases



Ambiguity resolution has impact
on estimated value of PCO,
esp. along-track

	X [mm] σ_x [mm]	Y [mm] σ_y [mm]	Z [mm] σ_z [mm]
Before bias fixing	12.7 0.08	0.5 0.12	-0.23 0.04
After bias fixing	15.6 0.03	-1.2 0.03	0.8 0.03

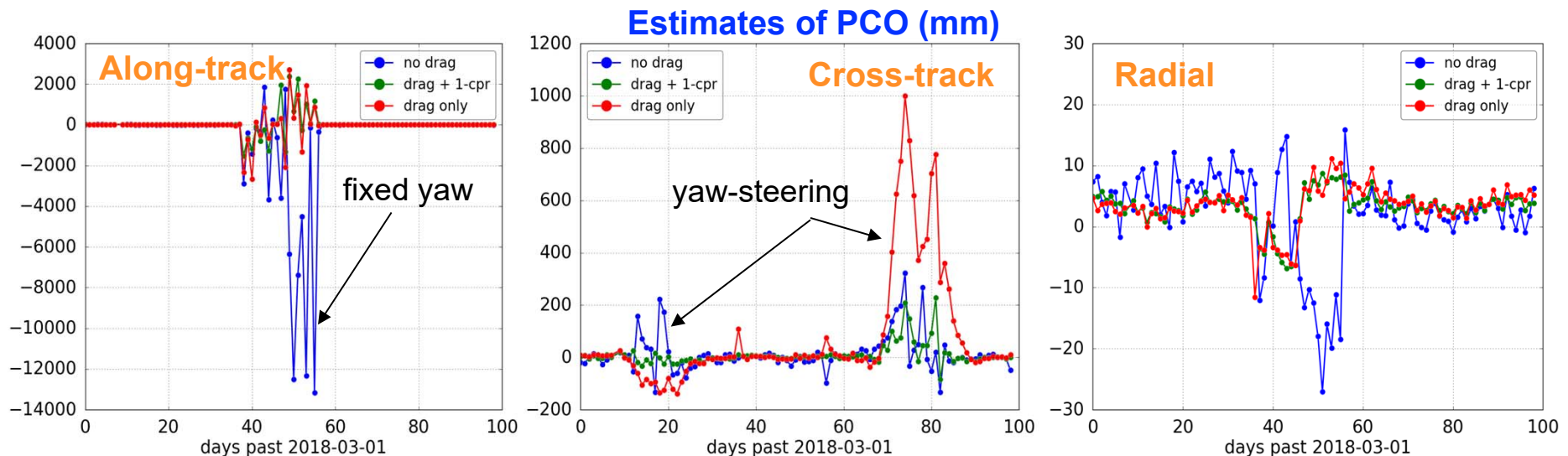
Sensitivity of PCO Determination to Dynamic Parameterization



- 30-hour-long solutions, centered on 12PM, dynamic orbits , 0° elevation cut-off
- Various dynamics parameterizations tested

✓ = estimate as good as baseline ; ✗ = estimate degraded relative to baseline

	Along-track (L)	Cross-track (C)	Radial (H)
drag + 1-cpr along H/L	JPL's operational strategy (baseline)		
drag only	✓	✗	✓
1-cpr along H/L (no drag)	✗	✗	✗
drag + const. acc. H/C/L	✗	✗	✗
drag + 1cpr along H/L + const. acc. H/C/L	✓	✗	✗

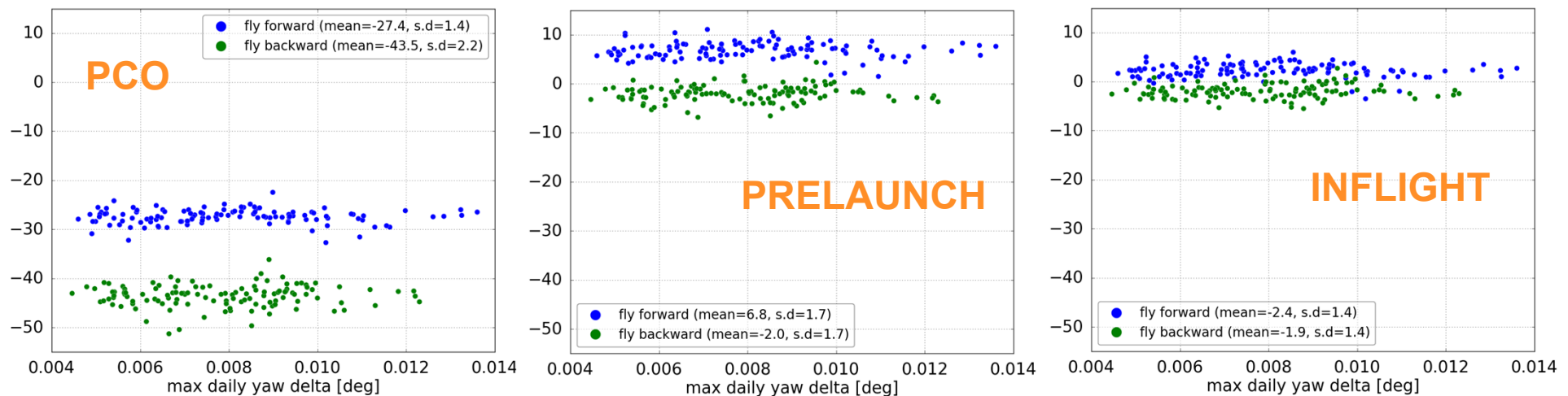


Sensitivity of PCO Determination to A Priori Antenna Calibration



- Overall reduction in scatter for 3 components for different attitude regimes when:
 - Using prelaunch calibration over PCO calibration
 - Using post-launch estimated correction to prelaunch calibration
- Conspicuous reduction of (unexplained) bias between fly-forward and fly-backward estimates of the PCO; e.g. in the radial direction when s/c flying in fixed-yaw

Estimates of Radial Component of Phase Center Offset in Fixed Yaw Mode [mm]



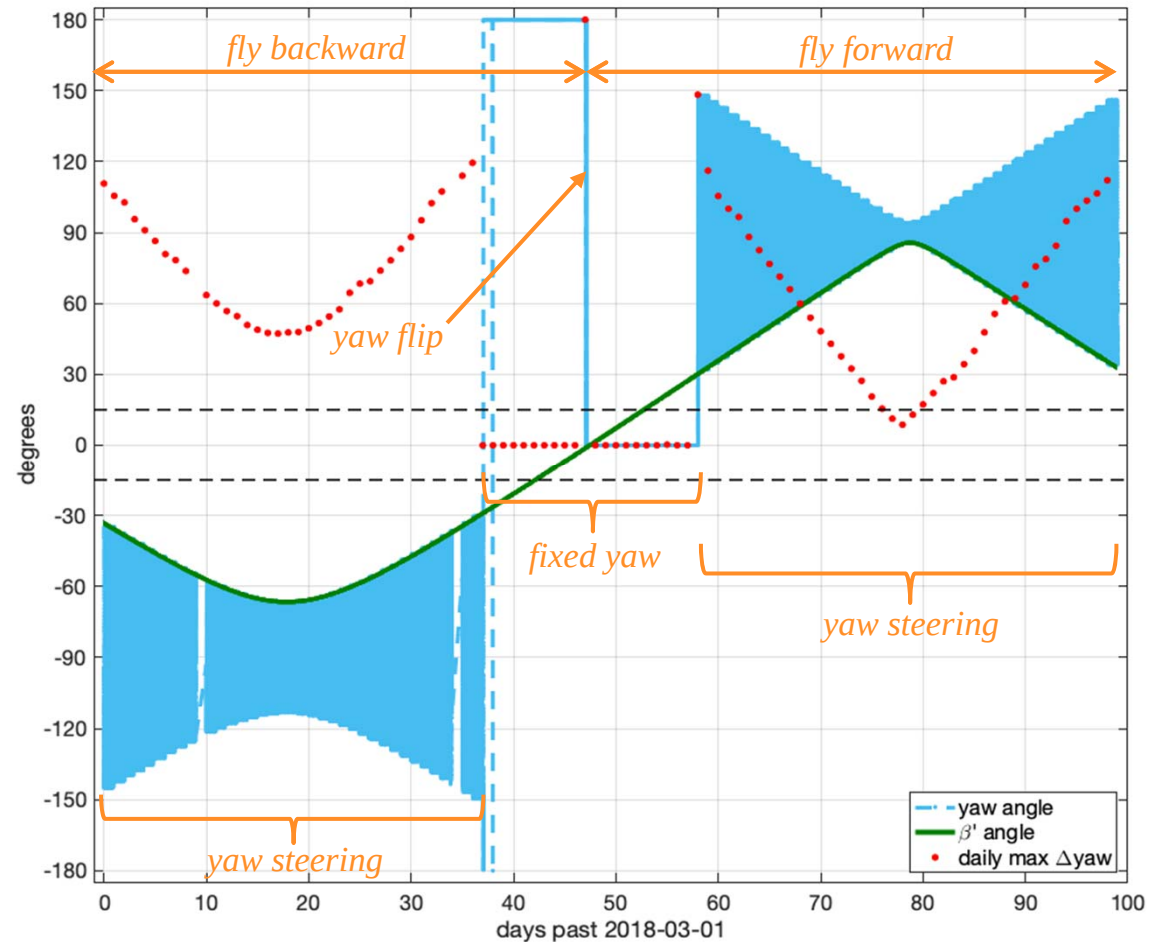


Jason-3 attitude sequence

Attitude laws for Jason-3:

- $|\beta'| > 15^\circ$: yaw steering mode
- $|\beta'| \leq 15^\circ$: fixed yaw mode
- $\beta' = 0^\circ$: yaw flip (180° yaw variation)

s/c alternates between:
fly-forward (FF) and
fly-backward (FB)
between yaw flip events.





Jason-3 SLR Residuals

