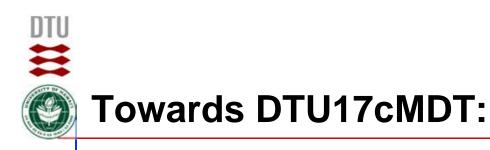


Towards A combined mean dynamic topography model – DTU17cMDT.

Per Knudsen & Ole Andersen, DTU Space

Nikolai Maximenko, U Hawaii







Build on DTU17MDT - a purely geodetic MDT.

- DTU15MSS (improved in coastal and polar areas),
- OGMOC geoid combination/hybrid model (GRACE + GOCE + surface gravity + Eigen-6c4 to d/o 2160),
- Improved filtering (fine tune ½-width and anisotropy).

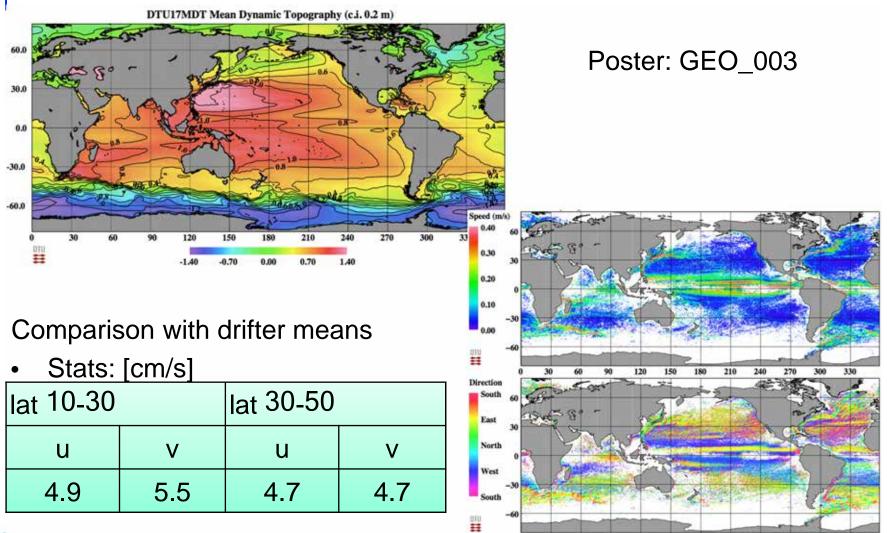
Integration with mean drifter velocities:

- Processing of drifter velocities (Ekman + Aviso GCA (20y)),
- Comparisons and error assessment (MDT and mean velocities),
- Model set-up and inversion (Smoothing).





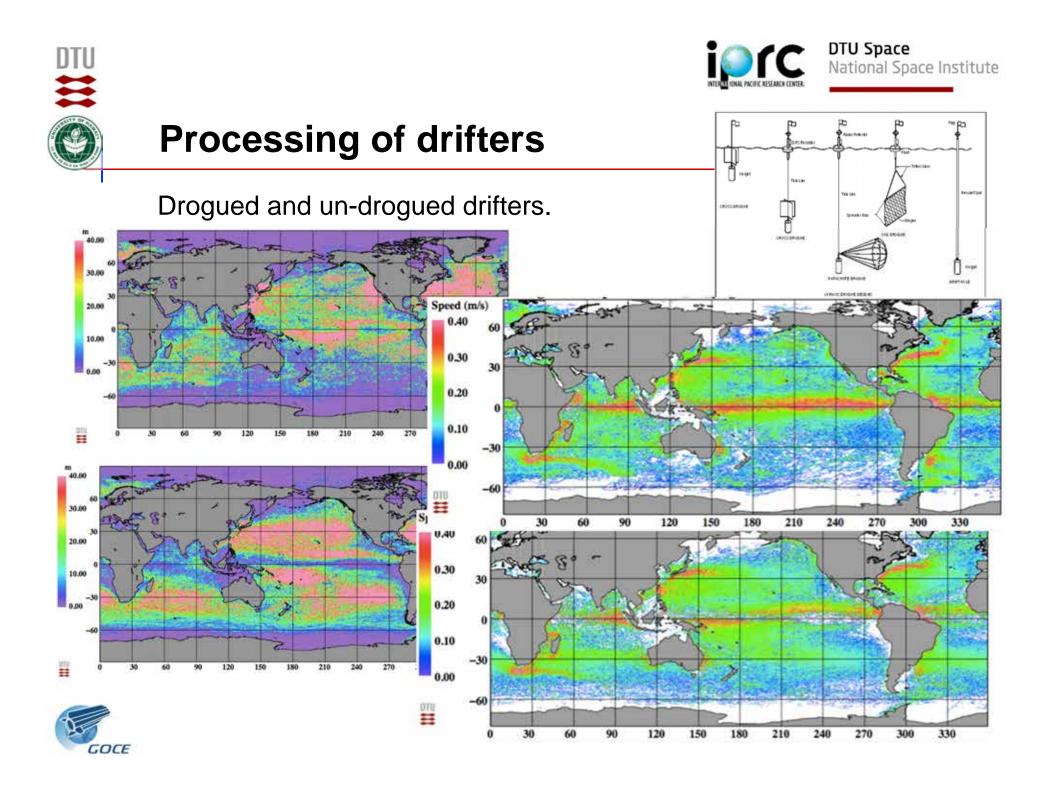
DTU17MDT



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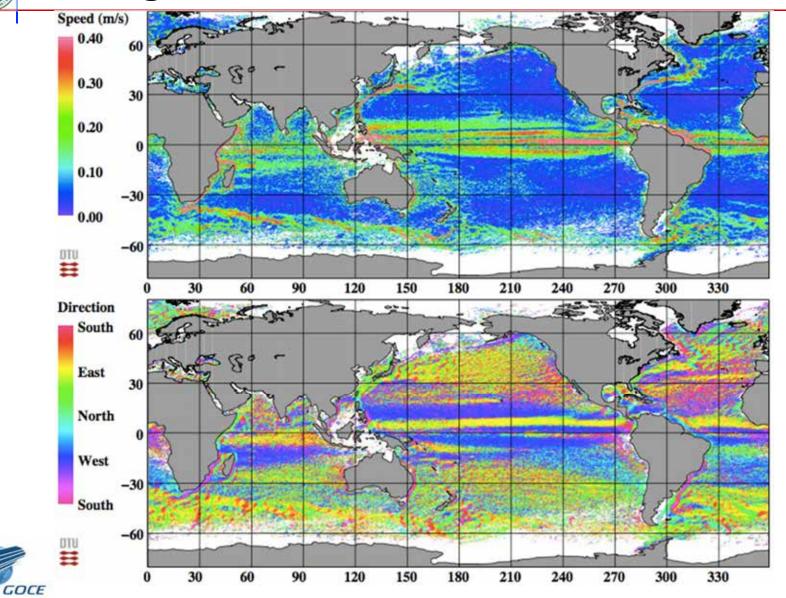








Merged set of mean drifter velocities





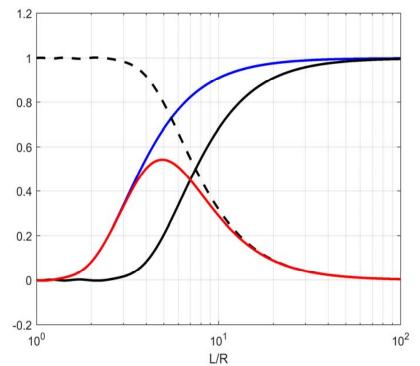


Comparison between mean dynamic topography gradients, derived from DTU17MDT and drifters at different space scales:

16 bands were selected: $L_i = 50 \text{ km} \cdot 2^{i/2}$, I = 0.15 - with the shortest at50 km and longest at 9051 km.

- 1. Drifter MDT
- 2. DTU17MDT
- 3. Differences

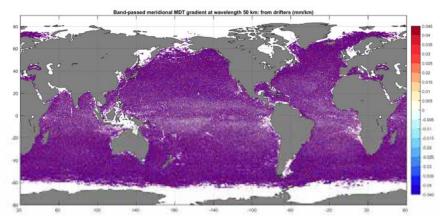
For both zonal and meridional gradients. (96 plots.!)

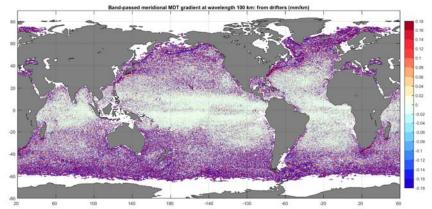


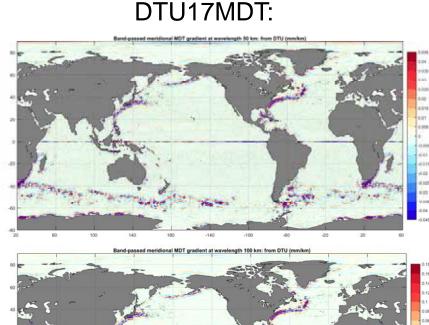




Meridional gradients at 50 km and 100 km Drifter MDT and





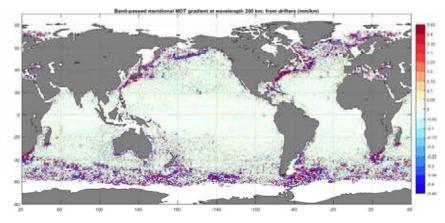


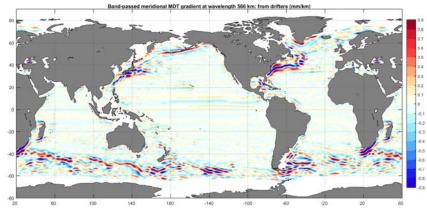


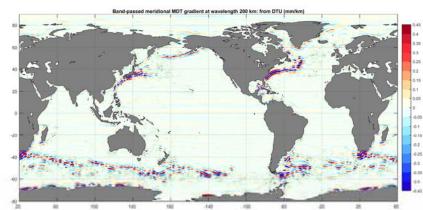




Meridional gradients at 200 km and 400 km Drifter MDT and



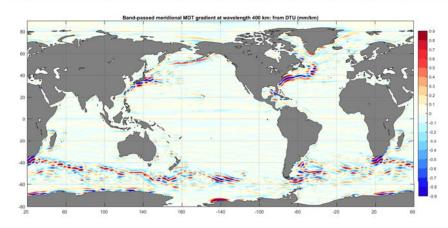




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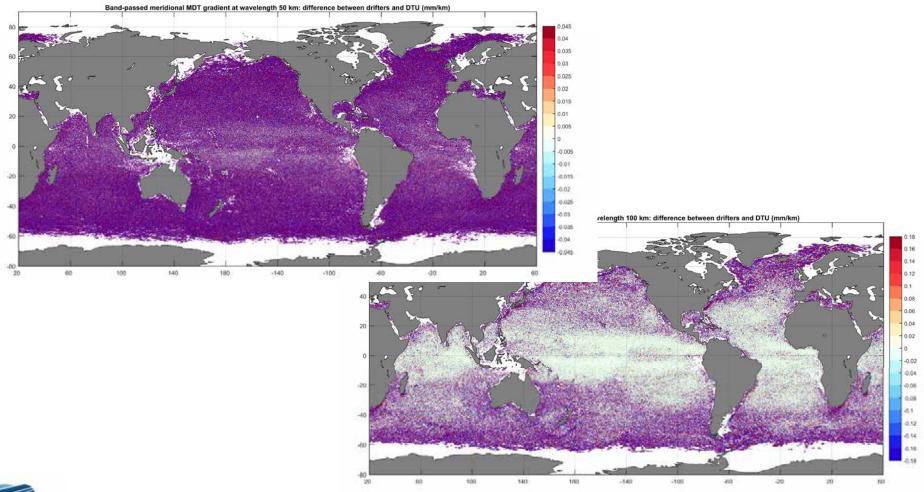








Meridional gradients at 50 km and 100 km of differences

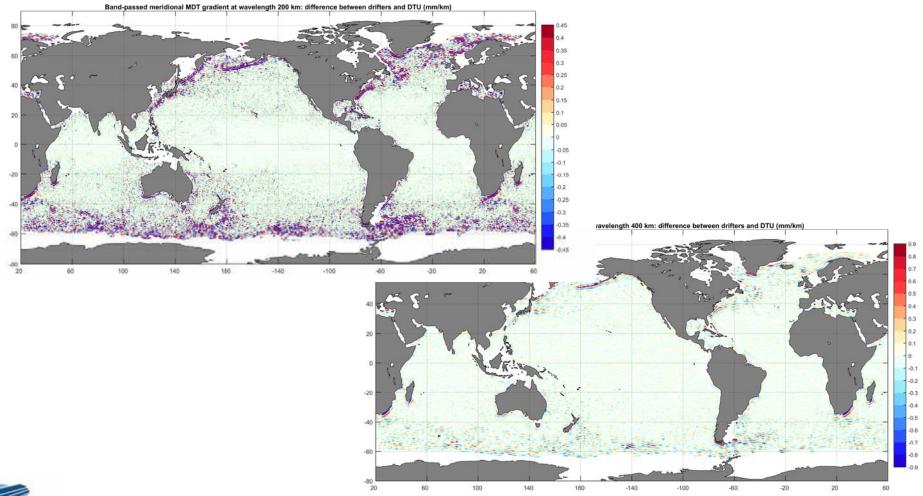








Meridional gradients at 200 km and 400 km of differences

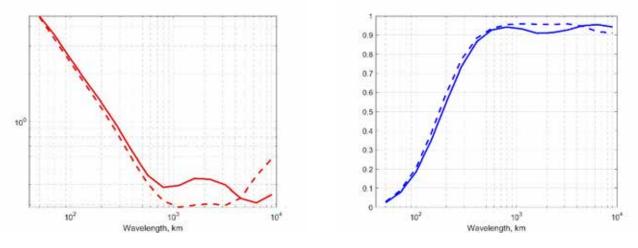








Comparison between mean dynamic topography gradients, derived from DTU17MDT and drifters at different space scales:



- (a) Ralative r.m.s. difference between zonal (solid line) and meridional (dashed line) MDT gradient estimates.
- (b) Correlation coefficient between zonal (solid line) and meridional (dashed line) band-passed signals from oceanographic and geodetic MDT gradient products





Inversion



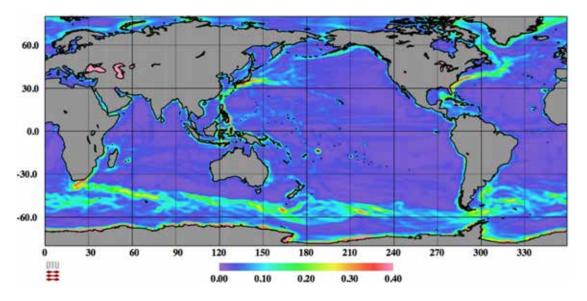
Model: MDT heights at nodes of a regular 1/4 by 1/4 deg grid.

Minimizing the cost function:

 $\mathbf{F} = \sum (MDT - MDT_{geodetic})^2 + C_{gradient} \cdot \sum (\nabla MDT - \nabla MDT_{oceanographic})^2 + C_{smoothness} \cdot \sum (\Delta MDT)^2$

Consider errors

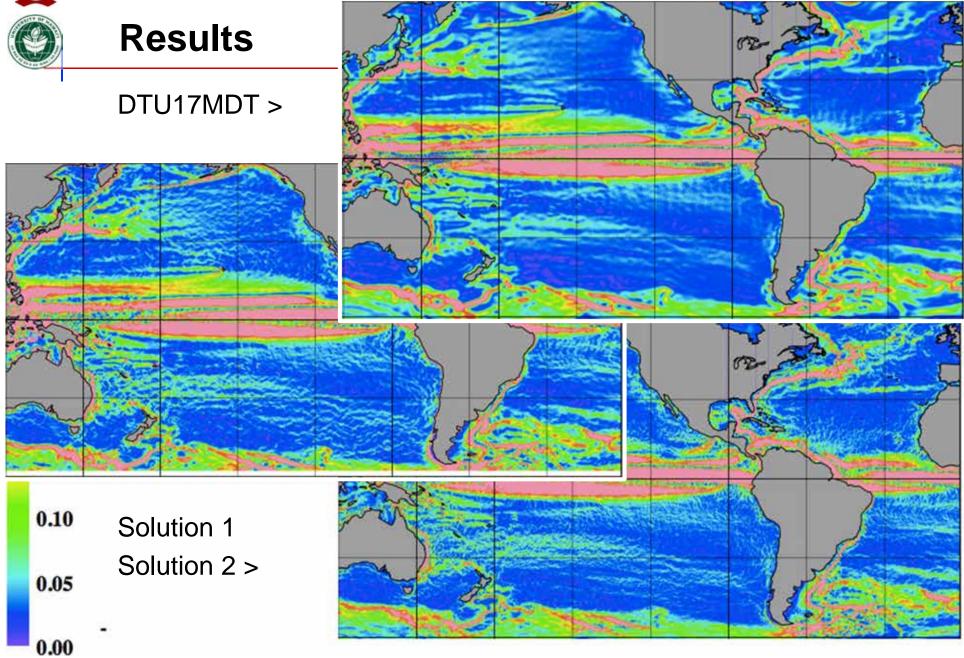
- Mean drifter velocities: e ~ 1/sqrt(n)
- MDT error:

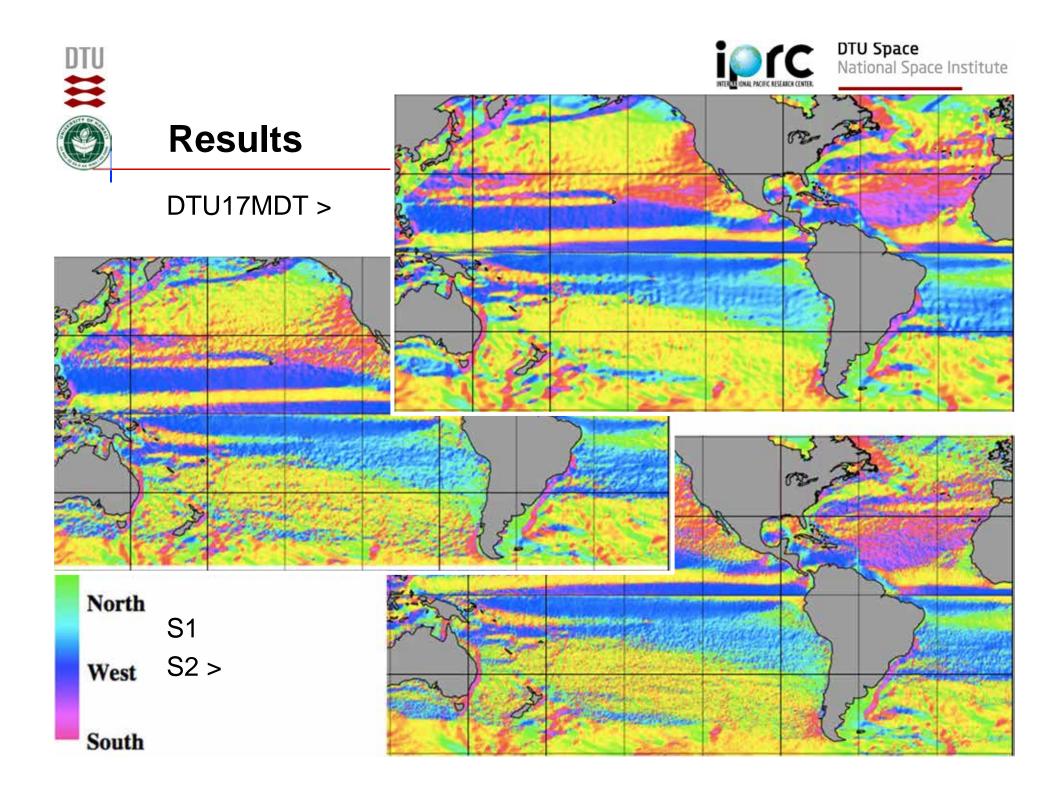


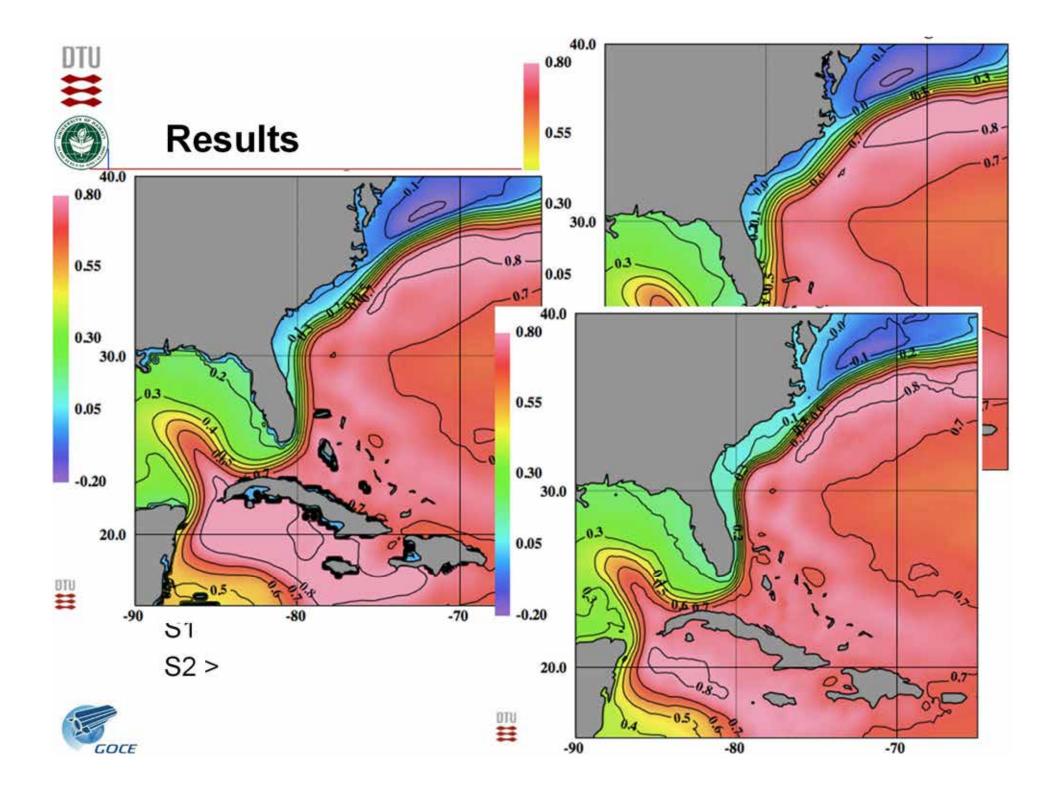


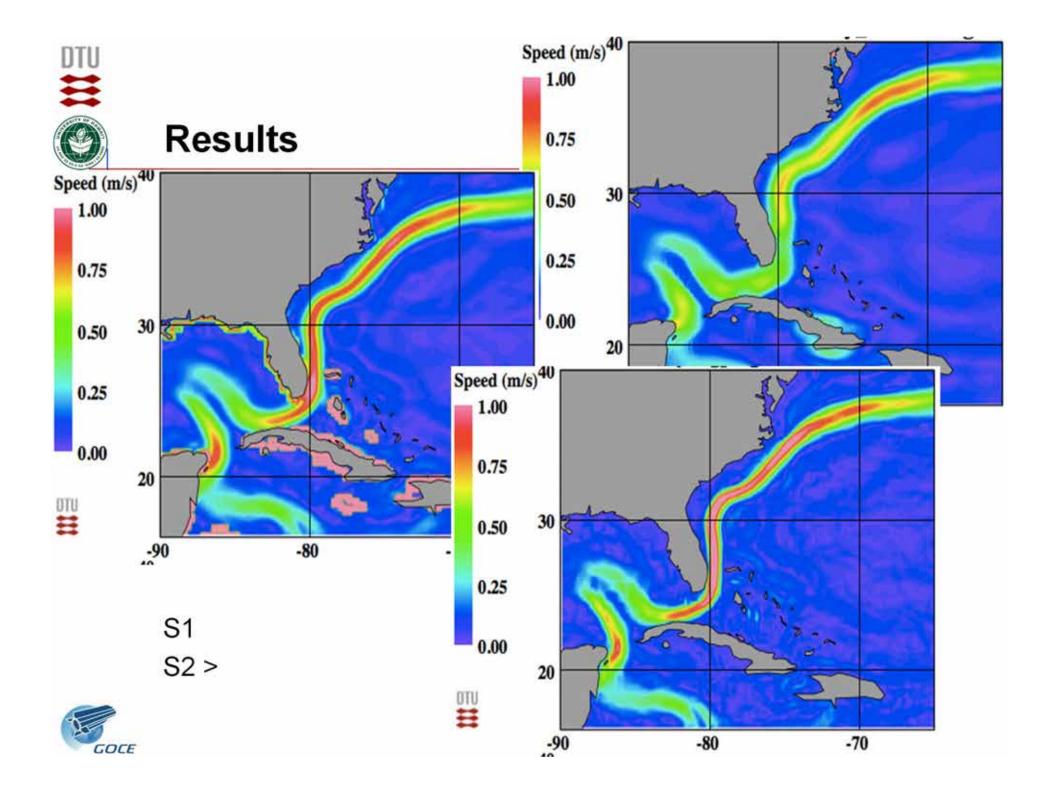


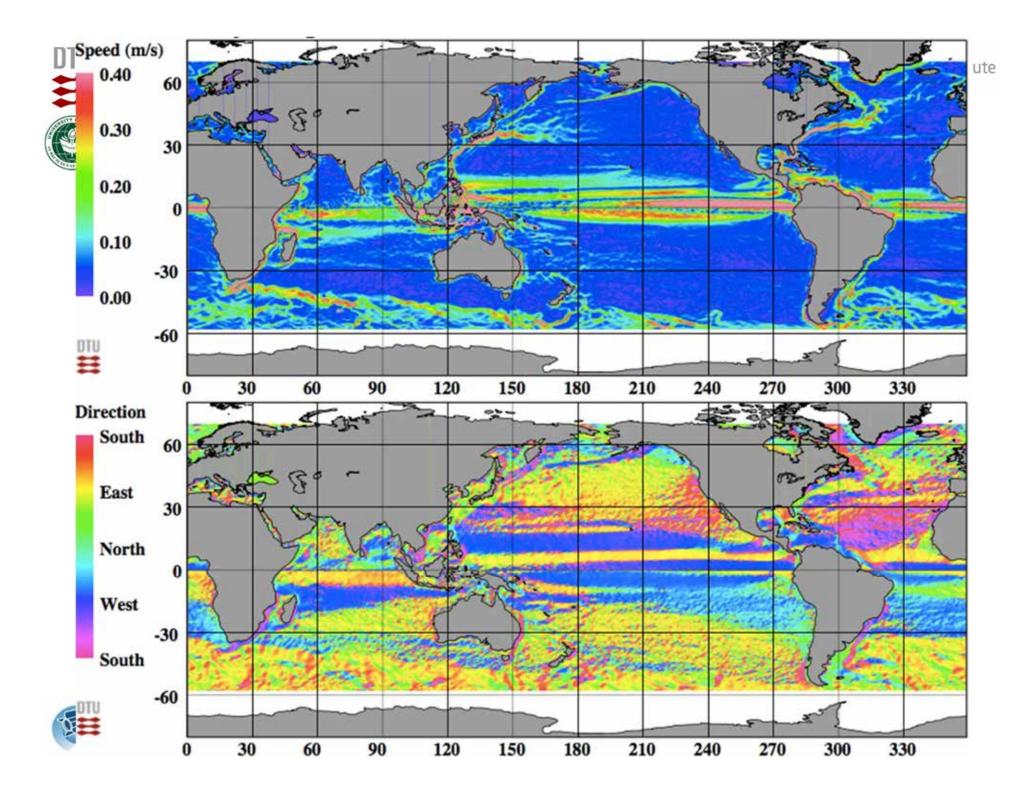


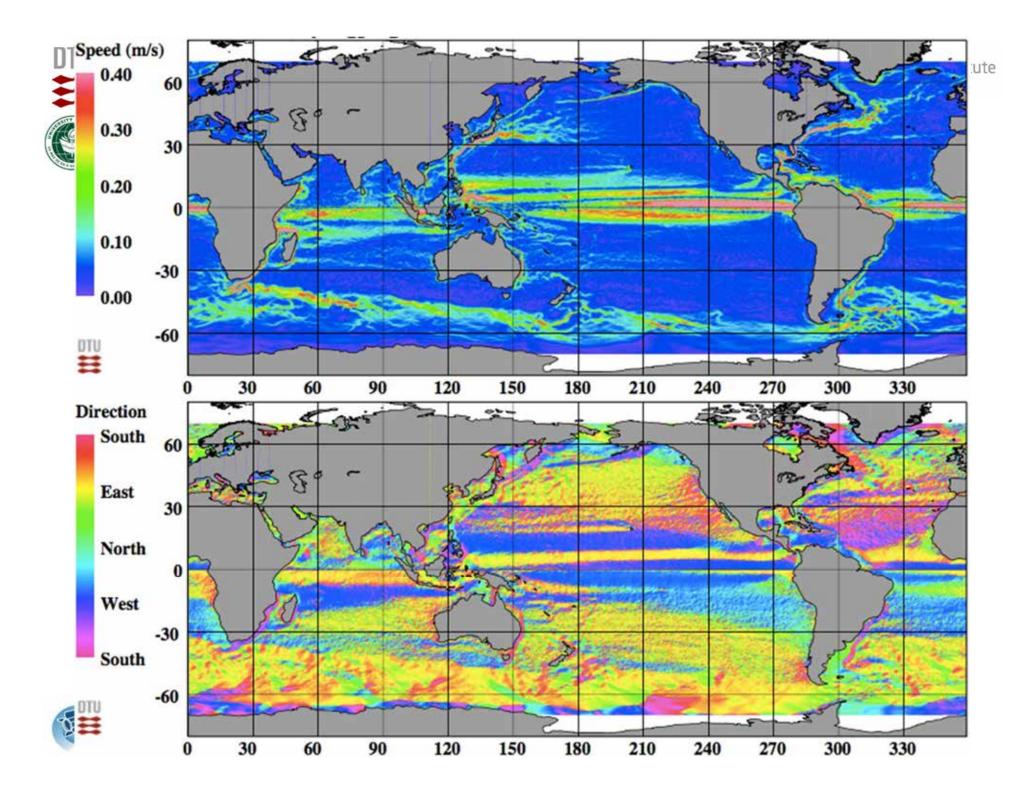














Summary

Preliminary versions of an MDT combining the geodetic DTU17MDT with drifter mean velocities have been derived.

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Still need to:

- Assess errors,
- Experiment with weights and regularization/smoothing,
- Compare solutions,
- Converge toward a joint model.

